

# Design of a Content Addressable Memory-based Parallel Processor implementing $(-1+j)$ -based Binary Number System

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**Abstract**—Contrary to the traditional base 2 binary number system, used in today's computers, in which a complex number is represented by two separate binary entities, one for the real part and one for the imaginary part, Complex Binary Number System (CBNS), a binary number system with base  $(-1+j)$ , is used to represent a given complex number in single binary string format. In this paper, CBNS is reviewed and arithmetic algorithms for this number system are presented. The design of a CBNS-based parallel processor utilizing content-addressable memory for implementation of associative dataflow concept has been described and software-related issues have also been explained.

**Keywords**—binary number; complex binary; parallel processing; content-addressable; memory; associative dataflow; compiler; operating system

## I. INTRODUCTION

A complex number consists of two components, namely the *real* part and the *imaginary* part, and it represents a point in a two-dimensional space. The real part is used to plot the position of the point along the horizontal axis while the imaginary part represents the position of the same point along the vertical axis. In today's computers, a complex number is stored in base 2 binary representation with both real and imaginary parts of the number represented individually. Thus, an arithmetic operation between two complex numbers becomes the accumulation of results from two sub-arithmetic operations on each pair of real and imaginary parts of the two given complex numbers. This increases the execution time of the arithmetic operations for complex numbers and hence causes delay in generating the output in computer applications where complex numbers are frequently used, such as image processing and signal processing. Efforts to represent the whole complex number (both real and imaginary parts) as single binary string date back to 1960s when D. Knuth proposed an imaginary-base binary number system with base  $2j$  [1] and W. Penney attempted to define a number system, first with base  $-4$  and then by using a complex number  $(-1+j)$  as the base [2,3]. The main problem encountered with using these bases at that time was the inability in formulating an efficient division process and the exorbitant cost of memory to store long string of binary numbers representing complex numbers in the new bases. In 1996, V. N. Stepanenko defined a number system with base  $j\sqrt{2}$  in which even powers of the base yielded real numbers and odd powers

of the base resulted in imaginary numbers [4]. Although he was able to resolve the division problem in his proposed number system as an "all-in-one" operation, yet in his algorithm, "everything...reduces to a good choice of an initial approximation..." in a Newton-Raphson iteration which may or may not converge. T. Jamil *et. al.* have revisited Penney's proposed  $(-1+j)$ -base number system and have done extensive mathematical analysis of *Complex Binary Number System* (CBNS) to establish it as a viable binary number system for representing complex numbers in the computer systems [5,6,7]. In 2001/2003, D. Blest and T. Jamil have presented an efficient division algorithm for complex binary numbers which has paved the way for implementation of this unique number system in computer hardware for all types of arithmetic operations [8,9]. This paper is intended to be a brief review of the CBNS and then it describes the architecture of an associative dataflow processor which amalgamates the parallelism inherent in content-addressable memories with the complex binary representation of complex numbers, a design which has been granted an innovation patent by the Australian Patent Office in 2010 [10].

This paper is organized as follows: In Section II, review of complex binary number system and algorithms for arithmetic operations for this number system are presented. In Section III, the concept of associative dataflow is described, which is followed by the design of *Complex Binary Associative Dataflow Processor* (CBADP) in Section IV. The software design issues related to CBADP are presented in Section V. Conclusions and suggestions for further research are outlined in Section VI. Acknowledgment and references are listed at the end of this paper.

## II. REVIEW OF COMPLEX BINARY NUMBER SYSTEM (CBNS)

### A. Conversion Algorithms [7]

- To represent a given position integer  $N$  in CBNS, the following steps are followed: (i) Express  $N$  in terms of power of 4 using repeated division process. (ii) Convert the base 4 number  $(...q_5q_4q_3q_2q_1q_0)$  to base  $-4$  by replacing each digit in odd location  $(q_1, q_3, q_5 \dots)$  with its negative to get  $(...-q_5, q_4, -q_3, q_2, -q_1, q_0)$ . (iii) Normalize the new number (i.e., get each digit in the range 0 to 3) by repeatedly adding 4 to the negative

digits and adding a 1 to the digit on its left. If the digit is 4, replace it by a zero and subtract a one from the digit on its left. (iv) Now replace each digit in base -4 representation with the corresponding four-bit sequence (0 → 0000; 1 → 0001; 2 → 1100; 3 → 1101). To convert a negative integer into CBNS representation, we simply multiply the representation of the corresponding positive integer with 11101 (equivalent to  $-1_{base -1+j}$ ) according to the multiplication algorithm given in sub-section B.

- To obtain CBNS representation of imaginary numbers, we simply multiply the CBNS representation of corresponding positive number with 11 (equivalent to  $(+j)_{base 10}$ ) or 111 (equivalent to  $(-j)_{base 10}$ ) according to the multiplication algorithm given in sub-section B.
- To represent a fraction  $F$  in CBNS, we first express the fraction in terms of powers of  $\frac{1}{2} = 2^{-1}$  such that  $F = r_0 = f_1 \cdot 2^{-1} + f_2 \cdot 2^{-2} + f_3 \cdot 2^{-3} + f_4 \cdot 2^{-4} + \dots$  to machine limit. The coefficients  $f_i$  and the remainders  $r_i$  are given as follows: Initially, if  $2r_0 - 1 < 0$  then  $f_1 = 0$  and set  $r_1 = 2r_0$  or if  $2r_0 - 1 \geq 0$  then  $f_1 = 1$  and set  $r_1 = 2r_0 - 1$ . Then, if  $2r_1 - 1 < 0$  then  $f_{i+1} = 0$  and  $r_{i+1} = 2r_1$  or if  $2r_1 - 1 \geq 0$  then  $f_{i+1} = 1$  and  $r_{i+1} = 2r_1 - 1$ . We continue this process until  $r_i = 0$  or the machine limit has been reached. Then, for  $\forall f_i = 1$ , we replace its associated  $2^{-i}$  according to the sequence ( $2^{-1} \rightarrow 1.11$ ,  $2^{-2} \rightarrow 1.1101$ ,  $2^{-3} \rightarrow 0.000011$ ,  $2^{-4} \rightarrow 0.00000001$ ) [for  $i > 4$ , refer to [8]]. Note that addition is according to algorithm given in sub-section B.
- To represent a floating-point number in CBNS, which consists of both an integer and a fraction, CBNS representation is obtained by adding the CBNS representation of each individual part according to the addition algorithm given in sub-section B. All rules for obtaining negative integer and positive/negative imaginary number representations, as discussed previously, are equally applicable for obtaining negative floating point and positive/negative imaginary floating point representations in CBNS.
- To represent a complex number in CBNS, we simply add the CBNS representation of real part with the CBNS representation of the imaginary part according to the addition algorithm given in sub-section B.

#### B. Arithmetic Algorithms [7]

- To add two complex numbers represented in CBNS format, the truth table is given as follows:  $0 + 0 = 0$ ;  $0 + 1 = 1$ ;  $1 + 0 = 1$ ;  $1 + 1 = 1100$ . When two numbers with 1s in position  $n$  are added, this results in 1s in positions  $n+3$  and  $n+2$  and 0s in positions  $n+1$  and  $n$  in the sum. Similar to the ordinary computer rule where  $1+111 \dots$  (to limit of machine) = 0, we have  $11 + 111 = 0$  [Zero Rule] in CBNS.
- To subtract two complex binary numbers, the truth table followed is:  $0 - 0 = 0$ ;  $0 - 1 = *$ ;  $1 - 0 = 1$ ;  $1 - 1 = 0$ . For the case where 1 is subtracted from 0 (the \* case in the rules), the following algorithm is applied: Given our

minuend is:  $a_n a_{n-1} a_{n-2} \dots a_{k+4} a_{k+3} a_{k+2} a_{k+1} a_k 0 \dots a_{-1} \dots a_3 a_2 a_1 a_0$  and subtrahend is:  $b_n b_{n-1} b_{n-2} \dots b_{k+4} b_{k+3} b_{k+2} b_{k+1} 1 b_{k-1} \dots b_3 b_2 b_1 b_0$ . Then, the result of subtracting 1 from 0 is obtained by changing:  $a_k \rightarrow a_k + 1$ ,  $a_{k+1} \rightarrow a_{k+1}$  (unchanged),  $a_{k+2} \rightarrow a_{k+2} + 1$ ,  $a_{k+3} \rightarrow a_{k+3} + 1$ ,  $a_{k+4} \rightarrow a_{k+4} + 1$ , and  $b_k \rightarrow 0$ .

- To multiply two complex binary numbers, we follow the same method that we use for traditional binary numbers, except that while adding intermediate summands, addition algorithm outlined previously in this sub-section is used. The Zero Rule plays an important role in speeding up the result of the multiplication operation.
- To perform the division of two complex numbers represented in CBNS, we take the reciprocal of the denominator and multiply it with the numerator as per algorithm described above. The reciprocal of the complex number is estimated using the following algorithm: Given  $z = w^{-1}$ , we start with our initial approximation of  $z$  by setting  $z_0 = (-1 + j)^{-k}$  where  $k$  is obtained from the representation of  $w$  such that  $w = \sum_{i=-\infty}^k a_i (-1 + j)^{-i}$  in which  $a_k \equiv 1$  and  $a_i \equiv 0$  for  $i > k$ . The successive approximations are then obtained by  $z_{i+1} = z_i (2 - wz_i)$ . If the values of  $z$  do not converge, we correct our initial approximation of  $z$  by setting  $z_0 = j(-1 + j)^{-k}$  which will definitely converge [9].

#### III. ASSOCIATIVE DATAFLOW CONCEPT (ADC)

The associative dataflow concept is, in fact, an extension of the traditional concept of dataflow and is obtained by elimination of *tokens* generated during dataflow processing. In traditional dataflow, a computer program is represented as a graph consisting of nodes (representing instructions) and arcs (representing data dependencies between the nodes) [11]. The operands and their control information are conveyed from one node to another in data packets called *tokens*. The process of determining the executability of instructions is through matching of the tokens which is done sequentially and considered as a major bottleneck in degrading the performance of dataflow systems. The ADC eliminates the need for token generation and matching in dataflow systems and thus, by removing this bottleneck, the performance of the system improves.

In ADC, a dataflow graph is executed in two phases, namely the *search phase* and the *execution phase*. During the search phase, the dataflow graph can be assumed to be upside-down wherein the node(s) at the top-level is the *parent* and the nodes at the lower level, connected to the parent through arcs, are the *children*. The objective of the search phase is for each parent to search for its children. Since this search is conducted using content-addressable memory (also called associative memory, hence the name *associative dataflow*) which has parallel search capabilities, the search phase is conducted much faster compared to the sequential token-matching done in conventional dataflow paradigm. As a result of conducting the search phase, each node (i.e., the instruction) of the dataflow graph (i.e., the program) knows what its operands are (i.e.,

data), where they are located (i.e., location of data), and also the destination node for the result. During the execution phase, instructions are carried out as in traditional dataflow computer systems.

To better understand the concept of parent and children nodes, consider a simple dataflow graph to compute  $X = a+b+c+d$  (Fig.1). The search phase of the associative dataflow concept requires that the given dataflow graph be turned upside-down in order for each parent to search for its children. The inverted dataflow graph to allow progress of this search phase is shown in Fig. 2, wherein the node at the top (N3) is at level 0, and the nodes N1 and N2 are at level 1. Node at level 0, i.e., N3, is the parent of the nodes at level 1, i.e., N1 and N2, or in other words, the nodes N1 and N2 at level 1 are the children of the node N3 at level 0. Similarly, operands' pairs (a,b) and (c,d) are the children of the nodes N1 and N2 respectively.

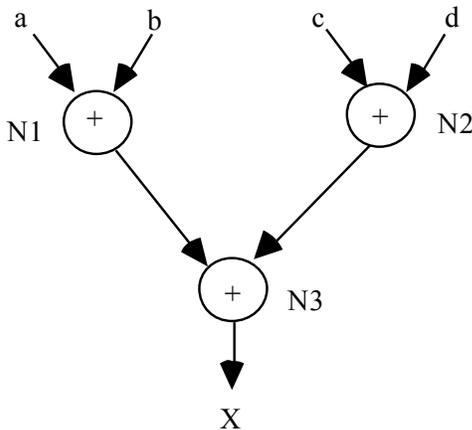


Fig. 1. Dataflow graph to compute  $X=a+b+c+d$

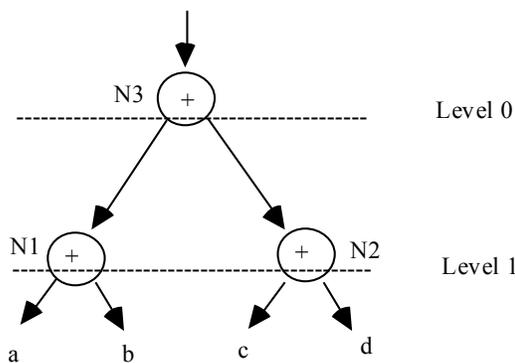


Fig. 2. Dataflow graph to compute  $X=a+b+c+d$  inverted to allow progress of search phase

In traditional dataflow machine, execution of dataflow graph given in Fig. 1 would require 3 ALU Execution Times

(one for each node N1, N2, N3) plus 1 Token Matching Time (at node N3) plus 1 Memory Fetch Time (at Node N3). In associative dataflow machine, the Fig. 1 dataflow graph would need only Total Search Time + Total Execution Time. It has been shown in [11] that associative dataflow processor, based on ADC, has much better peak and benchmark performance figures compared to typical dataflow machines.

Considering that CBNS provides an efficient format for representing data and ADC exhibits a promising future for parallel processing, it was natural for researchers to consider amalgamating the two ideas into designing of a *Complex Binary Associative Dataflow Processor* (CBADP) which takes advantage of the best features found in both concepts.

#### IV. COMPLEX BINARY ASSOCIATIVE DATAFLOW PROCESSOR (CBADP)

The schematic block diagram of a CBADP is given in Fig. 3 [12]. Each component of the diagram is described in the following sub-sections.

##### A. Associative Memory

An associative memory, also known as content-addressable memory (CAM), is defined as a collection of storage elements, called associative cells, which are accessed in parallel on the basis of data contents rather than by specific address or location. Each associative cell has the hardware capability to store and search its contents, in parallel, against the input data, and then indicate a match or mismatch by the state of a flip-flop. CBADP associative memory consists of a comparand register which contains the data to be compared against the contents of the memory array, a mask register used to mask off portions of the data word(s) which do not participate in the operations, a memory array containing a collection of memory cells providing storage and search medium for the data, and a responder indicating success or failure of a search operation.

There are two types of nodes in a dataflow graph, namely the *action-node* responsible for executing arithmetic or logic operation on the operands, and the *control-node* responsible for transferring the task of operation execution to some specific node when a certain condition is satisfied, as in case of branch operations. Depending upon the type of node, an associative memory word for action-node is of 80-bits length while a control-node word is of 18-bit length. Details about the format of the memory word can be found in [11]. Total number of words in the memory array are fixed at 64 to allow for up to 16 levels of dataflow graph with no more than four nodes per level.

##### B. Complex Binary Processing Unit

This unit is composed of four arithmetic and logic units to allow for up to four parallel operations corresponding to each node in a given level of the dataflow graph. Note that each CBALU is capable of handling arithmetic and logic operations in CBNS format, according to the algorithms described in Section II. Detailed designs of arithmetic circuits can be found in [13,14,15,16,17]. Currently, the instruction set of CBADP is composed of 21 instructions but there is a possibility of it to be extended to a total of up to 64 different instructions.

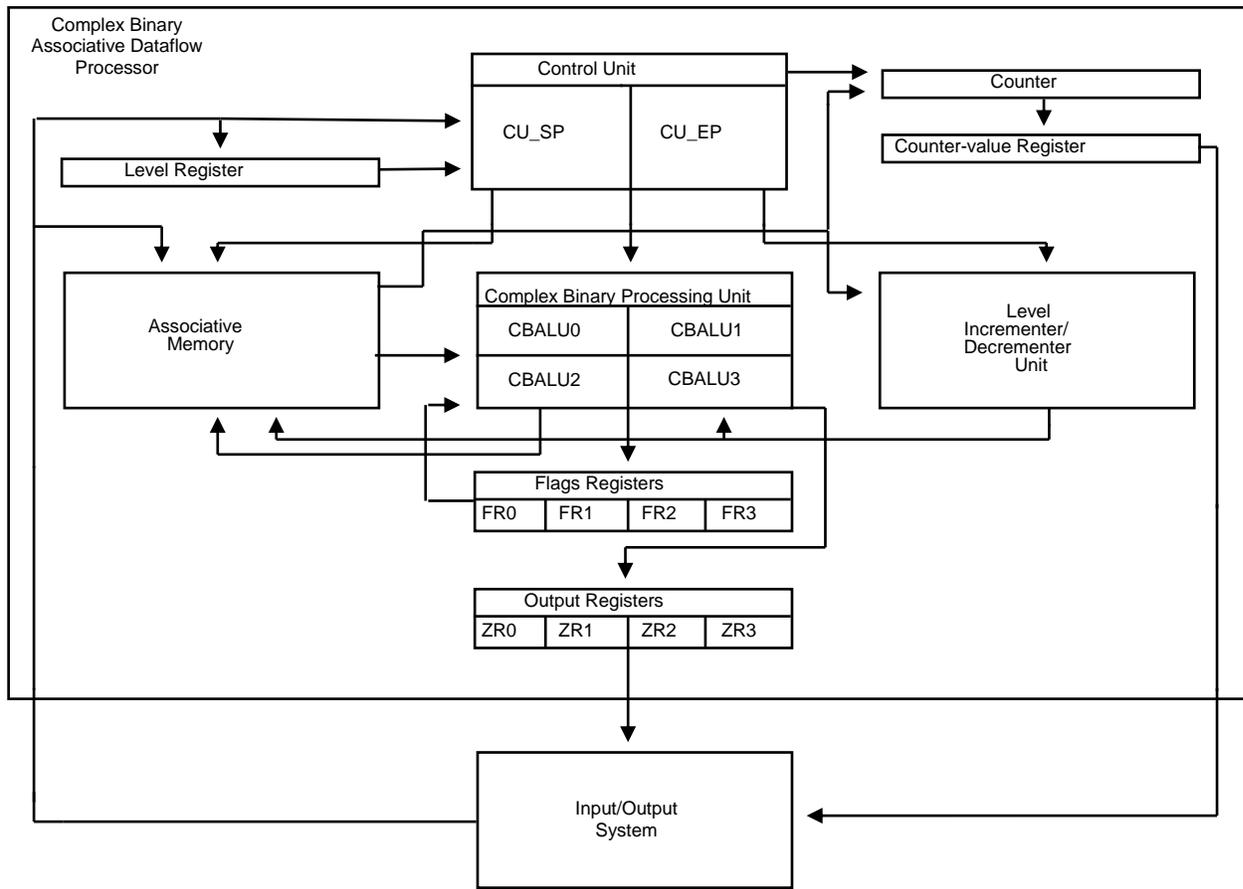


Fig. 3. Schematic block diagram of Complex Binary Associative Dataflow Processor (CBADP)

### C. Level Incrementer/Decrementer Unit

To allow for 16 levels within a dataflow graph, a 4-bit level incrementer/decrementer unit is used to facilitate incrementing of the level number of the dataflow graph by one during the search phase and decrementing of the level number by one during the execution phase. Levels are labelled from top-to-bottom of the dataflow graph in descending order. Since, during the search phase, the graph is assumed to be upside-down, parent nodes are at the lower level and they are searching for children nodes which are at the higher level. This requires incrementing of the level number in the associative memory word as the search progresses. During the execution phase, the data is passed from nodes at higher level to the nodes at the lower level which requires decrementing of the level numbers as the execution phase continues. Given input E such that level incrementer/decrementer unit increments when E=0 and decrements when E=1, and current level number given by  $X_0X_1X_2X_3$ , the new level number  $L_0L_1L_2L_3$  is given by the following Boolean equations:

. : Logic AND

+: Logic OR

$X_1^{\wedge}$ : Logic NOT

@: Logic XOR

$$L_0 = E.[X_0^{\wedge}.X_1^{\wedge}.X_2^{\wedge}.X_3^{\wedge} + X_0.X_2] \\ + E^{\wedge}.[X_0^{\wedge}.X_1.X_2.X_3 + X_0.X_1^{\wedge}]$$

$$+ X_0.[X_1.X_2^{\wedge} + X_1^{\wedge}.X_3 + X_2.X_3^{\wedge}] \quad (1)$$

$$L_1 = E.[X_1.X_2 + X_1^{\wedge}.X_2^{\wedge}.X_3^{\wedge}] \\ + E^{\wedge}.[X_1.X_2^{\wedge} + X_1^{\wedge}.X_2.X_3] \\ + X_1.[X_2 @ X_3] \quad (2)$$

$$L_2 = E @ X_2 @ X_3 \quad (3)$$

$$L_3 = X_3^{\wedge} \quad (4)$$

### D. Control Unit

Independent hardwired control units for search phase (CU\_SP) and execution phase (CU\_EP) have been designed for CBADP. A Hardware Programming Language (AHPL) has been used to write a total of 24 control sequences for CU\_SP and 23 control sequences for CU\_EP. Details of control unit design are presented in [11].

### E. Counter

This is a 6-bit up-down counter to keep track of up to 64 nodes which may be present in a dataflow graph to be executed on CBADP. Given input  $x_1=0$  such that the counter counts up by one from its current state  $x_2x_3x_4x_5x_6x_7$  to the next state  $y_0y_1y_2y_3y_4y_5$ , and counts down when  $x_1=1$ , the Boolean equations for the next state are given as follows:

. : Logic AND  
+ : Logic OR  
X<sub>i</sub><sup>^</sup> : Logic NOT  
@ : Logic XOR

produced by each CBALU. These registers are accessed by the Input/Output System which forms the interface to the outside world.

## V. CBADP SOFTWARE DESIGN ISSUES

There is a natural communication gap between man and machine. Computer hardware operates at a very atomic level in terms of bits and bytes, whereas people tend to express themselves in terms of natural languages such as English or in mathematical notation. This communication gap is bridged by means of an artificial language which allows the man to express himself with a well-defined set of words, sentences, and formulas that can be "understood" by a computer.

To achieve this interaction, the human is supplied with a user's manual which explains the constructs and meanings allowed by the language, and the computer is supplied with the software by which it can take a stream of bits representing the commands or programs written in the language by the human and translate this input into the internal bit patterns required to carry out the human's intent.

### A. Compiler

A compiler takes as input a source program and produces as output an equivalent sequence of machine instructions. This process is so complex that it is not reasonable, either from a logical point of view or from an implementation point of view, to consider the compilation process as occurring in one single step. Not long ago, compilers were considered almost impossible programs to write. The design of a compiler for CBADP is required to follow the same phases as the ones used today for the design of any other type of compiler, namely lexical analysis, syntax analysis, intermediate code generation, code optimization, and then code generation. The programmer will be able to write programs in one of the high-level languages, such as C, Pascal, or Fortran, and then using the CBADP compiler, the source code will be converted to the machine instructions (in terms of 0 and 1), which will be fed to the hardware components within the complex binary associative dataflow processor for onward processing and execution.

### B. Operating System

An operating system is a program that acts as an intermediary between the user of a computer and the computer hardware, and its purpose is to provide an environment in which the user can execute programs [18]. An abstract view of a CBADP system is given in Fig. 4.

The CBADP provides the basic computing resources (associative memory, processing unit, registers) which are managed by the CBADP operating system, according to the user programs, which are written in some high-level language (such as C, Fortran, or Pascal) and have been converted into machine language using the CBADP compiler.

$$y_0 = x_1 \cdot \{x_2 \cdot [x_3 + x_5 + x_3^{\wedge} \cdot x_4^{\wedge} \cdot x_7^{\wedge} \cdot (x_5^{\wedge} + x_6)] \\ + x_2^{\wedge} \cdot x_3^{\wedge} \cdot x_4^{\wedge} \cdot x_5^{\wedge} \cdot x_6^{\wedge} \cdot x_7^{\wedge}\} \\ + x_1^{\wedge} \cdot \{x_2 \cdot [x_3^{\wedge} + x_4^{\wedge} + x_3 \cdot (x_4 \cdot x_6 \cdot x_7^{\wedge} + x_5 \cdot x_6^{\wedge})] \\ + x_2^{\wedge} \cdot x_3 \cdot x_4 \cdot x_5 \cdot x_6 \cdot x_7\} \\ + x_2 \cdot (x_4 @ x_5) \quad (5)$$

$$y_1 = x_1 \cdot \{x_3 \cdot [x_4 + x_4^{\wedge} \cdot (x_5^{\wedge} \cdot x_7 + x_6 \cdot x_7^{\wedge})] \\ + x_3^{\wedge} \cdot x_4^{\wedge} \cdot x_5^{\wedge} \cdot x_6^{\wedge} \cdot x_7^{\wedge}\} \\ + x_1^{\wedge} \cdot \{x_3 \cdot [x_4^{\wedge} + x_5 \cdot x_6^{\wedge} + x_4 \cdot x_6 \cdot x_7^{\wedge}] \\ + x_2 \cdot x_4 \cdot x_5 \cdot x_6 \cdot x_7\} \\ + x_3 \cdot (x_4 @ x_5) \quad (6)$$

$$y_2 = x_1 \cdot (x_4 \cdot x_6 + x_4^{\wedge} \cdot x_5^{\wedge} \cdot x_6^{\wedge} \cdot x_7^{\wedge}) \\ + x_1^{\wedge} \cdot (x_4 \cdot x_5^{\wedge} + x_4^{\wedge} \cdot x_5 \cdot x_6 \cdot x_7) \\ + x_4 \cdot (x_5 \cdot x_6^{\wedge} + x_5^{\wedge} \cdot x_7 + x_6 \cdot x_7^{\wedge}) \quad (7)$$

$$y_3 = x_1 \cdot (x_5 @ x_6^{\wedge} \cdot x_7^{\wedge}) \\ + x_1^{\wedge} \cdot \{x_5 \cdot x_6^{\wedge} + x_6 \cdot [x_5 @ x_7]\} \quad (8)$$

$$y_4 = x_1 @ x_6 @ x_7 \quad (9)$$

$$y_5 = x_7^{\wedge} \quad (10)$$

### F. Counter-value Register

This register (6-bit) is used to store the counter value at the completion of each successful search phase. This information is then used by the operating system in formulating an efficient execution phase for the given dataflow graph.

### G. Level Register

This 4-bit register holds information about the maximum level number in the given dataflow graph. The control unit uses this information to ensure that all levels of the graph have been searched and executed.

### H. Flags Registers

There are four of these registers corresponding to each CBALU in the complex binary processing unit. Each register holds carry, zero, negative, and overflow flags.

### I. Output Registers

There are four of these registers corresponding to the output

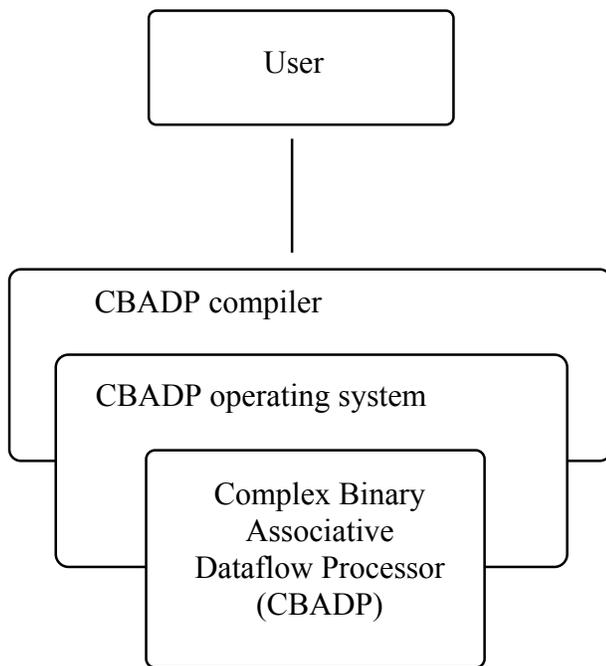


Fig. 4. Abstract view of CBADP system

The CBADP operating system has several important functions for smooth and efficient processing of the user programs, and these are:

- Based on the information provided by the CBADP compiler about the given dataflow graph, design an efficient search phase for the program.
- Provide the system call to the CU\_SP (control unit for search phase) for initiating the search phase of the dataflow graph.
- Acknowledge and handle any interrupts generated during the search phase to keep track of the information about the nodes (of dataflow graph) and their specific locations within the associative memory where they have been stored.
- Based on the information gathered during the search phase, design an efficient execution phase for the given dataflow graph.
- Provide the system call to the CU\_EP (control unit for execution phase) for initiating the execution phase of the dataflow graph.
- Acknowledge and handle any interrupts generated during the execution phase to keep track of the information about the nodes (of dataflow graph) and their execution status in the system. In case of branch operations, enable or inhibit the appropriate control-node depending upon whether the branch condition has been satisfied or not.
- Provide synchronization mechanism between the four arithmetic and logic units contained within the

processing unit of the CBADP so that the instructions are executed in proper order.

For best CBADP performance, the ideal operating system should have multitasking capabilities so that more than one dataflow graph can be processed at a given time if the necessary resources, such as CBALUs and registers, are available. For example, to achieve maximum utilization of the complex binary processing unit, all four of the CBALUs must be kept busy all the time. If there are less than four nodes at any given level for execution, the multitasking operating system can assign the idle ALU(s) to another dataflow program which can run in parallel with the current dataflow program. In case of more than one dataflow program being processed on the ADP, the protection becomes an important issue to be addressed. That is, steps need to be taken to ensure that the proper execution of one graph does not interfere with the proper execution of the other dataflow graph(s) in the system.

## VI. CONCLUSIONS AND FURTHER RESEARCH

The design of a content-addressable memory-based associative dataflow processor, for which an Australian Innovation Patent has been granted, has been presented in this paper. Work on establishing complex binary number system as a natural enhancement of traditional binary number system is still in progress and the given complex binary associative dataflow processor design is still undergoing improvements and implementation optimization for field-programmable gate arrays (FPGAs). An avenue of further research in this area would be to incorporate CBNS in an image processor design or a digital signal processor design, two of the well-known areas where complex numbers are widely used, and then compare their performances with the processors implementing base 2 binary number system. Incorporating cache memories within the CBADP and then determining statistical performance analysis of such a system will be a valuable contribution to this area of engineering. These days, efforts are underway to design computer systems which mimic human brain. Since human brain behaves very much like associative memory, a content-addressable parallel processor system, such as CBADP, may provide a useful tool for research in this area of interest to both medicine and engineering. The design of an operating system for CBADP is another interesting area of further research in this realm of computer engineering.

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