

# A Study of LoRa Performance in Monitoring of Patient's SPO<sub>2</sub> and Heart Rate based IoT

Puput Dani Prasetyo Adi<sup>1</sup>, Akio Kitagawa<sup>2</sup>

Electrical Engineering Department (UNMER), University of Merdeka Malang-Indonesia, Malang-East Java, Indonesia<sup>1</sup>  
Micro Electronics Research Laboratory (MeRL), Kanazawa University, Kanazawa, Ishikawa, Japan<sup>1,2</sup>

**Abstract**—In this research, a sensor that will be equipped with blood oxygen saturation function (SPO<sub>2</sub>) blood and Heart Rate is MH-ET Live max30102 Sensor with Library Max30105. The advantage of this sensor is compatible with ATmega 328P, which is the Arduino board, the first experiment using Arduino Uno. Therefore, MH-ET Sensor data is integrated with Wireless Sensor Network (WSN) devices, e.g. LoRa (Long Range) 915 MHz and calculate WSN path loss when sending sensor data in mountainous areas, the model used to represent signal analysis and measurements in this study is the Ground Reflection (2-ray) model. therefore, the conditions that can be explained are patients who will send their data over hilly areas and hospitals or medical treatments called receiving nodes or coordinator nodes in much lower areas, in the same situation adding routers is expected to be a comparison of whether the data sent faster or even no impact. Furthermore, in this study, it is expected to provide clear results on the function of the router as the sender of pulse sensor data. The point is patients who are in a higher area with the level of impossibility in bringing the patient due to the condition of the patient so that the SPO<sub>2</sub> data transmission and heart rate of the patient are expected to be known quickly by the medical authorities through the sensor node device attached to the patient's body. The use of the Adaptive Data Rate (ADR) Algorithm is used to optimize data rate, time on air (ToA) or airtime and energy consumption in the network. Therefore, the End Device (ED) in the ADR algorithm must be static (non-mobile). In the process of measuring the ADR algorithm in the position of sending data (uplink) n-bits to n-gateway. Next, the application server used is ThingsSpeak or The Things Network (TTN).

**Keywords**—Pulse; heart rate; adaptive; data rate; long range; bitrate

## I. INTRODUCTION

The development of the medical world continues to grow rapidly, medical devices are sophisticated and light, flexible increasingly widespread and Speed in getting health data. Today's technology, known as the industrial revolution 4.0, can bring to a fast-paced, fast-paced world, one of which is the existence of the Internet of Things (IoT). IoT has become a mainstay in various fields of life e.g., health, education (Virtual Reality (VR), Automation, Robotic [1],[2]), industry, Search and Rescue (SAR) application [3]. Especially for industries, for example, Programmable Logic Controller (PLC) now uses the term PLC-IoT. specifications in the Wireless Sensor Network, in the process of communication between nodes, between TX and RX, involve several components i.e., Tx Power or Power Consumption for transmitters, each wireless technology device is different. To

create an efficient sensor node for power consumption, an algorithm, e.g. Adaptive Data Rate (ADR), Automatic Sleep mode, and other algorithms are needed for efficiency [4]. therefore, Cellular devices have the largest Tx Power (mW) which is ~ 500 mW. Then Tx Power WIFI ~ 80 mW, while LoRa ~ 20 mW and Bluetooth ~ 2.5 Mw [5]. Bluetooth has the smallest Tx Power Consumption of all Wireless devices, but the disadvantage is that the short distance is only ~ 10 m. while LoRa reaches 13 km in Free Space Path Loss (FSPL). Therefore, WiFi and Cellular require a large Power Consumption but also limited by the distance that can be up to ~ 5 km on WiFi. The next advantage of LoRa is a small data rate (bps) when sending data.

In this research, the Wireless Sensor Network that is built is based on LoRa (Long Range) Radio Frequency, according to LoRa, has a different type of frequency based on ISM (Industrial, Scientific, and Medical) Band, this frequency distribution is based on the location of the continent or region of each country. e.g., Europe 867-869 MHz, North America 902-928 MHz, China 470-510 MHz, Korea, and Japan 920-928 MHz, and India 865-867 MHz. This is an example of the region's division of the Frequency value in the ISM Band [6], furthermore, the details as in the regional document parameters of the LoRa Alliance. As in research [7], LoRa and LoRaWAN are Wireless devices that have the farthest data transfer capability of ~ 13 km [8].

Therefore, the Low Power Wide Area (LPWA) technology or Low Power Wide Area Network (LPWAN) [9], it has the farthest data sending capability with low power consumption, e.g. in FSPL with the smallest data bit rate and low power consumption. therefore, Three characteristics of Wireless Sensor Network or End-node are Range (m), the speed of data transmission (data rate or bit rate (bps)), and Power Consumption (mW) [10], under conditions of the number of small nodes or nodes in large numbers, e.g. Bluetooth, ZigBee [11][12], WiFi, and LoRa. When compared to the Long Range capability, LoRa is preferable than Bluetooth, ZigBee or WiFi. However, LoRa cannot transmit large data or LoRa bit rates of only ± 250 bps, but the LoRa Power Consumption is low when compared to other radio devices. When compared with ZigBee (250 kbps), Bluetooth (± 3 Mbps) or WiFi (± 11 Mbps), however, Zigbee, Bluetooth, and WiFi are only for close distances and require a large Power Consumption. Therefore, it is difficult to transmit Long Range data at high data rates. It was concluded that the best performance of the characteristics of Wireless Sensor Network devices is seen from 3 sides, i.e. Power Consumption, Range and Speed of

Data Transmission. Fig. 1 shows the WSN best performance triangle, which is the Long Range (km), High-Speed Data Transmission (Mbps) [13].

Table I shows a comparison of i.e radio technology, Bluetooth, WiFi, 3G / 4G and LoRa with reliability ranges. LoRa and LoRaWAN [14] are Wireless Sensor Network technologies that are specifically used for long distances because in addition to being able to send data up to ~ 15 km in FSPL (Free Space Path Loss) or Line of Sight (LOS) conditions and Tx Power reaches low ~ 20 mW [15].

From the data Table I, LoRa is excellent in the data transmission range and is small in Tx Power, but the smallest in terms of transmission speed data (bps). as Fig. 1 almost impossible, which is almost close to LoRa, but LoRa cannot send large data up to Mbps in size. Therefore, this research will use LoRa at Frequency 915 MHz to send SPO<sub>2</sub> and Heart Rate data for monitoring the health of patients in mountainous locations. accordingly, the theory that will be used in this research is the Two Ray Ground theory using Matlab software. it is used mountainous locations as research locations so it uses the transmitter height parameter (*H<sub>t</sub>*). therefore, the Radio Signal Path Loss LoRa in mountainous locations. Transmitter height factor (*H<sub>t</sub>*), receiver or Base Station (*H<sub>r</sub>*). and the distance between the two or turnover distance. When the position of the transmitter (*H<sub>t</sub>*) is above the mountains it means that it is possible for transmitting data to run well or at least reduce the large Path Loss (dB) due to Diffraction, reflection, and Scattering. furthermore, when discussing the diffraction factor, reflection and scattering will go deeper into the type of material, whether buildings or buildings, trees, and material forms that cause the scattering process.

Accordingly, this research will be focused on the SPO<sub>2</sub> and Heart-beat sensor data from RF96 Chip LoRa communication. furthermore, the LoRa Communication can get the result of the Receive Signal Strength Indicator (-dBm) and the Signal Noise Ratio (SNR) (dB). Furthermore, this research will be developed with the Communication system topologies and the Transmission methods of the node sensor and the Gateway with Uplink and Downlink data (bps).

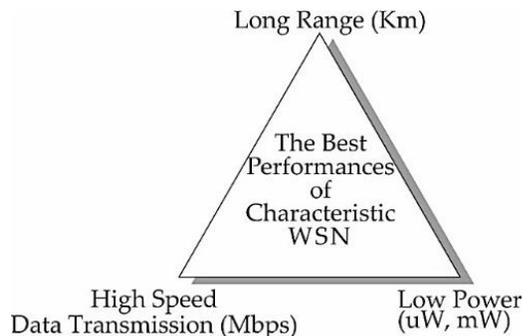


Fig. 1. The Best Performances of Characteristic WSN.

TABLE. I. THE RANGE, POWER AND TRANSMISSION SPEED OF WIRELESS TECHNOLOGY

Technology	Wireless Communication	Range	Tx Power	The Transmission Speed (bps)
Bluetooth	Short Range	~10 m	2.5 mW	±3 Mbps
ZigBee / IEEE 802.15.4	Short Range	~ 120 m (LoS)	~2 mW	250 kbps
WiFi	Short Range	~50 m	80 mW	± 11 Mbps
3G/4G	Cellular	~ 5 km	5000 mW	± 12.5 Mbps
LoRa	LPWAN	~ 2-5 km (urban) ~5-15 km (rural) > 15 km (LOS)	20 mW	±250 bps

## II. RELATED WORKS

Dong-Hoon Kim, Eun-Kyu Lee, and Jibun Kim, in their research [16], conducted a LoRa performance test to obtain the path loss value of LoRa PHY at a distance of 630 - 1344 m with a variety of Spreading Factor values. This research also uses a dynamic back-off Algorithm to improve LoRa MAC performance. And the Multi Gateway approach is also carried out so that redundant communication of data can be studied, this is an interesting research topic about LoRa and LoRaWAN in the future. At another researcher give the conclusion of a LoRa gateway supports up to 6000 nodes with PRR requirement of >70% [17], In other studies sensor nodes were added up to 1000 nodes per gateway and the lossess will be up to 32% [18].

Philip A.Catherwood, David Steele, Mike Little, Stephen McComb, and James Mclaughlin, with his research entitled "A Community-Based IoT Personalized Wireless Healthcare Solution Trial", have conducted a LoRaWAN Performance test at a distance of 1.1 - 6.0 Km and in this experiment apply for monitoring HealthCare or Medical, furthermore, the result of measurement obtained PathLoss radio value of 119-1141 dB [19].

## III. METHODOLOGY AND DEVICES USED

### A. The Sensor used Type

The type sensor used is MH-ET Live MAX30102, this is a sensor used to detect the Pulse Oximetry and Heart rate monitor transmission the module of the sensor. The type of microscope used is the Keyence VHX Digital Microscope. Furthermore, this sensor has dimensions x and y of x = 11,964 mm and y = 10.16 mm. The way this sensor works is to read pulse and Blood Oxygen saturation using different transmittance when the blood vessel beats.

$$SaO_2 = \frac{C_{HbO_2}}{C_{HbO_2} + C_H} \times 100 \% \quad (1)$$

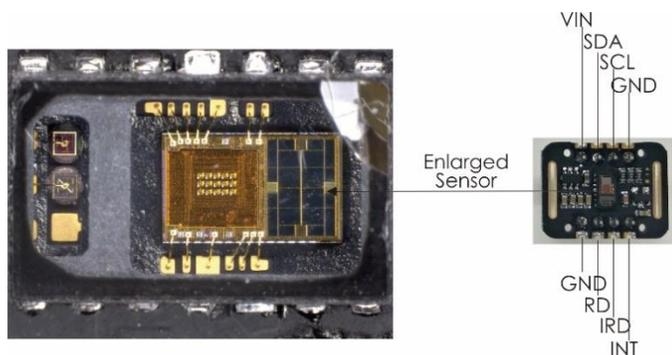


Fig. 2. Pulse Oximetry and Heart Rate Sensor Pins.

The light source, a specific wavelength of light-emitting diode selective for oxyhemoglobin (HbO<sub>2</sub>) and hemoglobin (Hb) in arterial blood.

Light transmittance is converted into an electrical signal, the change in the volume of the arterial pulsation causes the light transmittance of the light to change. At this time the light reflected by the human tissue is received by the photoelectric transducer, converted into an electrical signal, and amplified and output. The equation to measurement the SaO<sub>2</sub> is represented at equation 1.

Table II shows the MH-ET Live and Dragino LoRa Pins, there are 4 main pins used by the MH-ET Sensor i.e, Vin, SDA, SCL, and GND. Therefore for Dragino LoRa uses a voltage of 5 Volt DC for MH-ET Sensor, A4 for SDA and A5 for SCL. therefore, GND, RD, IRD and INT pins on one side of the MH-ET Sensor [Fig. 2] are not used. More can be seen in Table II. The plot of the heart rate display is shown in Fig. 21. There are three different conditions shown, Fig. 21 is a condition where the Finger is not placed on the sensor so there is no detection of arterial blood. Fig. 22 is when the Finger is detected by the sensor precisely, in this condition the IR value increases. Although using objects other than fingers, will not be detected normally, only InfraRed detects the movement of objects near the sensor, so the Hearth rate data is not accurate, as shown in Fig. 23.

**B. The Shannon-Hartley Theorem**

Shannon-Hartley Theorem concluded that the magnitude of Channel Capacity (C) in units of bits per second (bps) is determined by bandwidth (B), signals received (S) at a certain bandwidth and noise (N) or interference over the bandwidth.

$$C = B \log_2 \left( 1 + \frac{S}{N} \right) \tag{2}$$

TABLE. II. MH-ET LIVE SENSOR AND DRAGINO LORA PINS CONNECTIVITY

Pin Number	Pulse Oximetry Sensor, MH-ET pin	Dragino LoRa Pin
1	Vin	5 Volt DC
2	SDA	A4 (Analog 4)
3	SCL	A5 (Analog 5)
4	GND	GND

So Shannon-Hartley Theorem can be written with equation 2 .This means that the signal strength is influenced by the Signal Noise Ratio (SNR). Furthermore, SNR becomes a parameter in determining the radio frequency level of a Long Range (LoRa) radio frequency.

**C. The Chirp Spread Spectrum (CSS)**

According to the theory, modulation is the process of carrying analog information or digital information through a carrier signal, as the research [7] discussed about the Chirp Spread Spectrum (CSS), it was applied to Radar technology [24], There are 3 types of modulation types in signal modulation in i.e analog information, Amplitude Modulation, Frequency Modulation and Phase modulation and in digital information, i.e., Amplitude Shift Keying (ASK), Frequency Shift Keying (FSK), and Phase Shift Keying (PSK). According to research [7], there are 2 types of chirp, namely up-chirp and down-chirp. It can also be up-chirp and down-chirp referred to as part of the preamble which shows the nature or shape change of the chirp signal in the encoded (data) or up and down condition of the chirp. Furthermore, this CSS will be seen in the different Spreading Factor values. Furthermore, Chirp is stated in Real Spectrogram in Fig. 3. To detect LoRa signal or Chirp signal, this research uses Tektronix RSA 34088. Span 5 MHz to produce the appropriate Chirp signal form, in the trials in this research, LoRa signal type up -chirp and down-chirp containing CRC preamble, payload and Payload.

**D. Spreading Factor (SF)**

Spreading Factor (SF) is a factor that affects the strength of Radio Frequency Long Range Signal Frequency. The value of the Spreading Factor is 7,8,9,10,11 and 12 [7]. Spreading Factor determines the value of the symbol rate and chirp rate. Comparation Spreading Factor with different bandwidth (125 kHz, 250 kHz and 500 kHz) showed at Fig. 4, 5 and 6.

Spectrogram from Spreading Factor (SF) on Fig. 4, 5 and 6, was created using the MatLab Software in Program 1. In Program 1, for example, Bandwidth 500 kHz with Spreading Factor 7, produces a spectrogram different from other bandwidths (125 kHz, 250 kHz). furthermore, the Comparison can be made by comparing the spectrogram with the Spreading Factor 7,8,9,10,11 and 12.

With the combination of Bandwidth (BW). The red lines are called Preambles. The height of the preamble or amplitude of each preamble differs based on the value of the Bandwidth (BW) while the time difference is seen from the Spreading Factor (SF), the greater the Spreading Factor, the longer the time needed for one preamble. From the data taken from the calculation of the results of the comparison of characteristics between Bandwidth, Time on-air, Bitrate and SF obtained 2 graphs in Fig. 11 and Fig. 12.

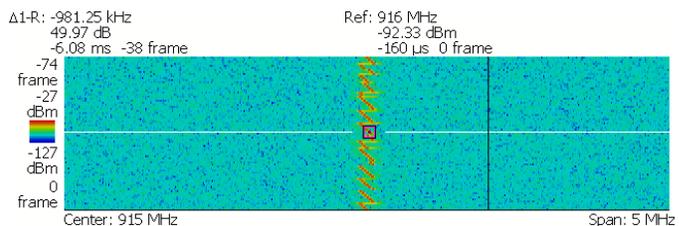


Fig. 3. Chirp Signal from Signal Analyzer.

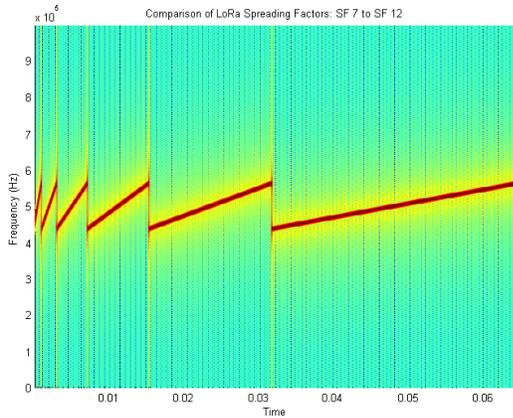


Fig. 4. Comparison Spreading Factor (SF) on 125 kHz Frequency.

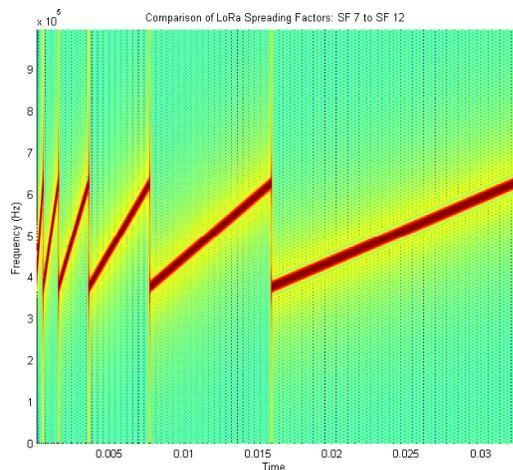


Fig. 5. Comparison Spreading Factor (SF) on 250 kHz Frequency.

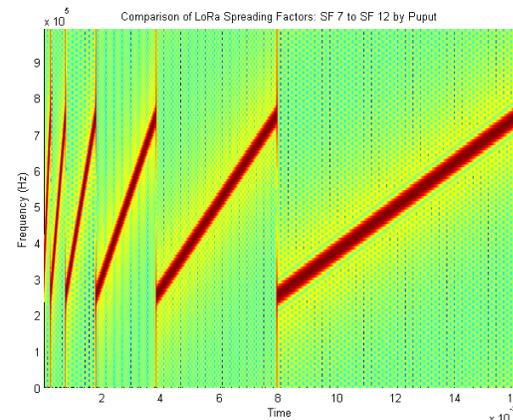


Fig. 6. Comparison Spreading Factor (SF) pada 500 kHz Frequency.

```
BW = 500000; % 500 kHz Bandwidth
Fs = 10^6; % Sampling Frequency
inverse = 0; % inverse = 1 for inverse chirps,
inverse = 0 % for normal chirps
% Case 1
SF = 7;
num_samples = Fs*(2^SF)/BW; % Number of samples
[out_preamble1] =
```

```
LoRa_Modulation(SF,BW,Fs,num_samples,0,inverse);
outp = [out_preamble1 out_preamble2 out_preamble3
out_preamble4 out_preamble5 out_preamble6];
samples = length(out_preamble1)/4;
spectrogram(outp,samples,samples-
1,samples*2,Fs,'yaxis');
title('Comparison of LoRa Spreading Factors: SF 7
to SF 12');
grid on;
axis tight;
----- Program 1 -----
```

E. Sensitivity of LoRa

To calculate the power level or sensitivity of the Receiver, 3 parameters need to be known, i.e., Bandwidth (BW), Noise Figure (NF) and SNRlimit, Sensitivity (dBm), [Fig. 9] is abbreviated with S as equation 3. with a formula like in equation 1. Accordingly the theory, S is Sensitivity (-dBm), BW is Bandwidth (Hz), Noise Figure (NF) are measures of degradation Signal to Noise Ratio (SNR), Noise Figure (NF) of LoRa differ for each device, in general, the value of the LoRa NF is 6. While the SNRlimit, refer to Table III.

$$S = -174 + 10 \log_{10}(BW) + NF + SNR_{limit} \quad (3)$$

The greater the Spreading Factor (SF) causes the data speed to be smaller, the greater the range of distance (indicated by ToA), and the greater the sensitivity (S), complete information can be seen in Table III.

Furthermore, the Sensitivity of LoRa is also influenced by SNRlimit, the greater the Spreading Factor causes the value of SNRlimit is also greater, in SF 7, the SNRlimit value is -7.5 dB, and in SF 12, the SNRlimit value reaches -20 dB.

F. Link Budget of LoRa

Link Budget shows the ability of LoRa in signal Propagation at a certain distance. Many factors that affect Link Budget include Power Transmitter, Transmitter and Receiver gain, Obstacle on Signal Propagation and Sensitivity factor. The relationship between sensitivity and Link Budget is shown in equation 4 and Fig. 10.

$$Link\ Budget\ (dB) = TX\ Power - S\ (Sensitivity) \quad (4)$$

TABLE III. LORA SPREADING FACTOR COMPARATION WITH SNR LIMIT

Spreading Factor (SF)	Chips /Symbol	SNRLimit	Time on Air (ToA) (10 byte Packet)	Bitrate
7	128	-7.5	56 ms	5470 bps
8	256	-10	103 ms	3125 bps
9	512	-12.5	205 ms	1758 bps
10	1024	-15	371 ms	977 bps
11	2048	-17.5	741 ms	537 bps
12	4096	-20	1483 ms	293 bps

G. Bit Rate or Data Rate (Rb)

Bit Rate or Data Rate (Rb) is several bits sent in units of time (s) or expressed in bits per second (bps). There is an important link between Spreading Factor and Bandwidth to determine how much Bit rate (Rb) or data rate (bps) is generated. furthermore, the LoRa bit rate is expressed as in

equation 5. Furthermore, the ratio of bandwidth (BW) and Spreading Factor (SF) to bit rate is shown in graph 1 (b) bits rate (bps) with SF.

$$R_b = SF \cdot \left[ \frac{4}{2^{SF}} \cdot \frac{1000}{BW} \right] \quad (5)$$

Where CR is a code rate of 1 to 4, and LoRa has bandwidth specifications ranging from 125 kHz, 250 kHz and 500 kHz. Based on from Libelium, LoRa or LoRaWAN has a configuration on Spreading Factor, Bandwidth and BitRate which can be seen in Table IV and Fig. 11.

#### H. Time on Air (ToA)

Time on Air (ToA) is the time used by Radio Transmission LoRa in one time sending data from the Transmitter ( $T_x$ ) to Receiver ( $R_x$ ) consisting of  $T_{Preamble}$  and  $T_{Payload}$ . Therefore, Time on Air is shown in Equation 6, Equation 7 and Fig. 12.

$$ToA = T_{Preamble} + T_{Payload} \quad (6)$$

With  $T_{preamble} = Nb_{Preamble} (8) + symbols\ added\ by\ radio (4.25) \times T_{symbol}$ ,  $T_{payload} = Nb_{PayloadSymbol} \times T_{symbol}$ .

$$n_{payload} = 8 + \max\left(\text{ceil}\left[\frac{(8PL-4SF+28+16CRC-20IH)}{4(SF-2DE)}\right] (CR + 4), 0\right) \quad (7)$$

#### I. LoRa Symbol Symbol Duration ( $T_s$ ) or $T_{sym}$

LoRa Symbol is the time used by LoRa within 1 second to transmit data or signals, this signal is a Chirp signal consisting of Preamble, Payload and Payload CRC. Furthermore, LoRa Symbol can be showed as in equation 8 [25].

$$T_{sym} \text{ or } T_s = \frac{2^{SF}}{BW} \quad (8)$$

#### J. Signal to Interference Ratio (SIR)

Signal Noise Ratio or Signal to interference ratio (SIR) is transmit Power ( $P_i$ ) or ( $P_t$ ) multiply with Direct Channel or Gain on the transmitter ( $G_{ii}$ ) divide by Power receiver ( $P_j$ ) or ( $P_r$ ) multiply with Direct Channel or Gain on receiver ( $G_{ij}$ ) plus noise on the transmitter ( $n_i$ ), which is affected by interference or noise. accordingly, equation 9 shows the value of Signal to Interference Ration (SIR) when transferring LoRa 915 MHz data. Furthermore, the percentage of SIR1 and SIR2 can be showed by equation 10.

$$SIR_i = \frac{P_i G_{ii}}{\sum_{j \neq i} P_j G_{ij} + n_i} \quad (9)$$

$$SIR_1 = \frac{P_1 G_{11}}{P_2 G_{12} + n_1} \text{ dan } SIR_2 = \frac{P_2 G_{22}}{P_1 G_{21} + n_2}, \text{ etc.} \quad (10)$$

#### K. Bit ErrorRate (BER)

Bit error rate or bit error ratio is the number of digital bits in the transmission network, in this case, LoRa 915 MHz where the total number of error bits is divided by the number of bits sent in a certain time (t), e.g. Bits sent 0110001011, while those received are 0010101001, from 10 data bits sent, there are 3 error bits, so the percentage is 3/10 or 0.3 or 30% BER, BER can be showed by equation 11[23].

$$BER = \frac{N_{error}}{N_{bits}} \quad (11)$$

#### L. Packet ErrorRate (PER)

Packet Error Rate (PER)% is the total number of Packets Error divided by the total packet received at a certain time during the Uplink process, i.e, the transmission sensor data from End Devices to the Gateway (GWs). Packet Error Rate (PER)% can be stated in equation 12. furthermore, Packets sent from EDs to GWs will be recorded by GWs and will be compared between Packets sent and Packets that Error, so that the percentage or amount of error arises from the transmitting data process [20].

$$P_p = 1 - (1 - P_e)^N = 1 - e^{N \log(1 - P_e)} \quad (12)$$

$E_b/N_o$  and  $C/N$

in data transmission,  $E_b / N_o$  is energy per bit to noise power spectral density ratio, is the same as the normalized measurement of Signal Noise Ratio (SNR), also known as SNR per bit,  $E_b / N_o$  can be showed at Equation 13, 14 and 15.

$$\frac{C}{N} = \frac{E_b}{N_o} \cdot \frac{fb}{BW} \quad (13)$$

Where,  $C / N$  is Carrier to noise ratio (dB),  $E_b / N_o$  (dB) is the ratio of energy per bit ( $E_b$ ) to the spectral noise density ( $N_o$ ),  $Fb$  is bit rate (bps) and  $B_W$  is the receiver noise bandwidth (bps).

Noise Power is computed using Boltzmann's equation:  $N = kTB$ , where,  $k = Boltzmann's\ constant = 1.380650 \times 10^{-23} J/K$ ;  $T$  is effective temperature in Kelvin, and  $B$  is the receiver bandwidth. Furthermore, the equation of  $\frac{C}{N}$  (dB) and  $\frac{E_b}{N_o}$  (dB).

$$\frac{C}{N} \text{ ratio (dB)} = \frac{E_b}{N_o} \text{ (dB)} + 10 \text{ Log} \left( \frac{fb}{BW} \right) \quad (14)$$

and,

$$\frac{E_b}{N_o} \text{ (dB)} = \frac{C}{N} \text{ (dB)} + 10 \text{ Log} \left( \frac{BW}{fb} \right) \quad (15)$$

TABLE IV. CONFIGURATION OF SPREADING FACTOR, BANDWIDTH AND BITRATE IN JAPAN

Index Number	Spreading Factor (SF)	Bandwidth (BW)	Bit Rate (bps)
0	12	125 kHz	250 bps
1	11	125 kHz	440 bps
2	10	125 kHz	980 bps
3	9	125 kHz	1760 bps
4	8	125 kHz	3125 bps
5	7	125 kHz	5470 bps
6	7	250 kHz	11000 bps

Furthermore, to calculate BER, with an approach to the energy factor per bit to noise power spectral density ratio or  $E_b / N_o$ , then, according to equation 16.

$$BER = Q \left( \frac{\log_{12}(SF)}{\sqrt{2}} \frac{E_b}{N_o} \right) \quad (16)$$

#### M. SNR (-dB)

The relationship between SNR (dB) and  $\frac{E_b}{N_o}$  (dB), can be showed at equation 17.

$$SNR (dB) = \frac{E_b}{N_o} + 10 \cdot \log_{10}(R_s) + 10 \cdot \log_{10}(k) + 10 \cdot \log_{10}(R) - 10 \cdot \log_{10}(BW_n) \quad (17)$$

Where  $R_s$  is the symbol rate;  $k$  is the number of information bits per symbol;  $R$  is code rate; and  $BW_n$  is the noise Bandwidth.

#### N. Coding Rate (CR)

Code Rate or Coding Rate (CR) is used to handle Packet Error Rate (PER) due to interference, with a formula as shown in equation 18. where  $n$  is  $\{1, 2, 3, 4\}$ .

$$CR = 4/(4 + n) \quad (18)$$

#### O. Symbol Rate ( $R_s$ )

In digital communication Symbol Rate ( $R_s$ ) also called Boudrate, the value of  $R_s$  is shown in equation (19). the relationship between  $R_s$ , SF,  $R_c$  is shown in equation 19.

$$SF = \log_2 \left( \frac{R_c}{R_s} \right) \quad (19)$$

Where  $R_s$  is symbol rate, symbol rate ( $R_s$ ) equal  $\frac{1}{T_s}$  which showed by equation 20.

$$R_s = \frac{1}{T_s} \quad (20)$$

$R_s$  juga dapat ditentukan dengan perbandingan Bandwidth dengan  $2^{SF}$  seperti ditunjukkan pada equation 21.

$R_s$  can also be determined by comparing Bandwidth with  $2^{SF}$  as shown in equation 21.

$$R_s = \frac{BW}{2^{SF}} = \frac{R_c}{2^{SF}} \text{ symbols/s} \quad (21)$$

Fig. 13 shows the characteristics of the Symbol Rate ( $R_s$ ) in different  $BW$  and Spreading Factor ( $SF$ ).

#### P. Bandwidth or Chip Rate ( $R_c$ )

Chip Rate ( $R_c$ ) is the number of chips / second. And the value of Chip rate ( $R_c$ ) equal by Bandwidth ( $BW$ ) value. e.g, Bandwidth is 125 kHz, then  $R_c$  is 125000 chips / second, or in other words, the same as the Chirps Spread Spectrum (CSS) reaches 125000 chips / second. The relationship between Chip rate ( $R_c$ ) and Bit rate ( $R_b$ ) showed on equation 22.

$$R_c = 2^{SF} \cdot R_b \quad (22)$$

Then, The relationship between Chip rate ( $R_c$ ) with Symbol Rate ( $R_s$ ) by unit Chip/sec, showed on equation 23 and 24.

$$R_c = 2^{SF} \cdot R_s \quad (23)$$

Where,  $R_c$  equal  $BW$ .

$$R_c = BW \text{ chips/s} \quad (24)$$

Where  $R_b$  is Data rate or Bit Rate in bits per second ( $bps$ ),  $BW$  is Bandwidth in KHz (10.4, 15.6, 20.8, 31.25, 41.7, 62.5, 125.250, 500) used by LoRa is Bandwidth 125, 250, 500 kHz,  $CR$  is Code Rate (1,2,3,4) and  $SF$  is Spreading Factor (6,7,8,9,10,11,12). Code or Coding rate ( $CR$ ) equal to  $4 / (4 +$

$n)$ , with  $n \in \{1,2,3,4\}$ . Furthermore, if the bandwidth is 125 kHz, and SF 7, the bit rate result is 5.46 kbps or 5460 bps.

#### Q. RSSI (dBm)

The RSSI (Receive Signal Strength Indicator) is the amount of Power Signal in units ( $dBm$ ), accordingly the theory, RSSI can be generated from equation 25. Complete RSSI is classified in Table V which shows Signal Level Range ( $dBm$ ).

$$RSSI (dBm) = 10 \log (Pr) \quad (25)$$

#### R. Long Range Radio Propagation for LoRa FSPL

LoRa uses an RP-SMA Male type antenna which has a gain of 2.dBi with 50  $\Omega$  impedance. Table VI shows the LoRa Antenna specifications used in this research. The FSPL equation for LoRa propagation can be showed on Equation 26 and 27. Furthermore, RP-SMA Male type antenna can be showed at Fig. 7.

$$FSPL = \left( \frac{4\pi d}{\lambda} \right)^2 \text{ equal } \left( \frac{4\pi d f}{c} \right)^2, \text{ because } \lambda = \frac{c}{f} \quad (26)$$

$$FSPL (dB) = 20 \log_{10} (d) + 20 \log_{10} (f) - 147.55 \quad (27)$$

Where, LoRa 915 MHz Wavelength ( $\lambda$ ) = 0.30327642030 m,  $c$  = Speed of light (299,792.458 m/s),  $d$  is distance ( $m$ ), frequency is Hertz ( $Hz$ ) and  $\pi$  = 3.14159265358979. In several studies, the calculation and design of circuit and Power efficiency using LTSpice Software [21]. From the comparison of the specifications of the LoRa module and the distances, the FSPL of LoRa 915 Module data is obtained as in Fig. 20. LoRa has a different Frequency for every Continent as shown in the table about United States frequency allocations in the Radio Spectrum. As 433 MHz and 868 MHz (Europe), 915 MHz (Australia and North America), and 923 MHz (Asia), for Japan 920-923 MHz.

#### S. A Type of Obstacle Materials During Radio Propagation

At the time of propagation of the signal through the obstacle, the signal attains attenuation due to the material in its path [22]. Table VII shows the material type and thickness and PathLoss value. Furthermore, the equation used is the  $n$  PathLoss Exponent which shows the value of  $n$  based on the material conditions that are passed by Tx and Rx.

TABLE V. SIGNAL STRENGTH CLASSIFICATION

Signal Level Range (dBm)	Classification	Score
-120 to -95	Extremely Bad	1
-95 to -85	Bad	2
-85 to -75	Average	3
-75 to -65	Good	4
-65 to -55	Very Good	5
-54 to -30	excellent	6



Fig. 7. RP-SMA Male Type Antenna.

TABLE. VI. LoRa ANTENNA SPESIFICATION

Connector Type	Gain	Polarization	Impedance
RP-SMA Male	2.0 dBi	Linear	50 Ω

TABLE. VII. MATERIAL AND THICKNESS AND NILAI PATHLOSS (dB)

No	Material and thickness	Path Loss (dB)
1	Glass (6 mm)	0.8
2	Glass (13 mm)	2
3	Wood (76 mm)	2.8
4	Brick (89 mm)	3.5
5	Brick (178 mm)	5
6	Brick (267 mm)	7
7	Concrete (102 mm)	12
8	Stone wall (203 mm)	12
9	Brick Concrete (192 mm)	14
10	Stone wall (406 mm)	17
11	Concrete (203 mm)	23
12	Reinforced Concrete (89 mm)	27
13	Stone wall (610 mm)	28
14	Concrete (305 mm)	35

### T. Two-Ray Ground Reflection (2-ray) Model

The Ground Reflection (2-ray) model is a model that predicts Path Loss when sending data from the Transmitter Antenna (Tx) to the Receiver (Rx) Antenna with Line of Sight (LOS) or facing each other. In general, both antennas have different heights ( $ht$  and  $hr$ ).  $ht$  is the height of the transmitter antenna in meters ( $m$ ) and  $hr$  is the height of the receiving antenna in meters ( $m$ ). consequently, a signal has reflected the ground before the signal is received by the receiving antenna (Rx), while the  $d$  (distance) is the distance between the sending and receiving antennas in meters ( $m$ ). at the mountains area, the Signal transmitting from Tx antenna is far above the hill, therefore, the theory of ground signal reflection can occur so that the Ground Reflection (2-ray) of this model is used. on the 2-Ray ground reflection propagation have two wave components that arrive at the Receiver (Rx), i.e. Line of Sight (LOS) and reflected from the ground and the reflection coefficient or Fresnel Coefficient ( $\Gamma = -1$ ). The Reflection Coefficient for i-wave can be stated in the equation 28.

$$\Gamma_i = \frac{\cos \theta_i - q \sqrt{\epsilon_c - \sin^2 \theta_i}}{\cos \theta_i + q \sqrt{\epsilon_c - \sin^2 \theta_i}} \quad (28)$$

$\epsilon_c$  is the complex Permittivity of the ground,  $\theta_i$  is the incident angle with the normal to the ground,  $q$  is a polarization-dependent factor, which is  $q = 1$  for horizontal polarization and  $q = 1 / \epsilon_c$  for vertical polarization. a ZigBee has a frequency of 2.4 GHz so that the ZigBee wavelength ( $\lambda$ ) is obtained is 0.124913 meters, and LoRa 915 MHz Wavelength ( $\lambda$ ) is 0.30.327642030 meters, this value from  $\lambda = c / f$ . therefore, to get the Path loss (PL (dBm) value), it is necessary to find the strength of the transmitter ( $Pt$ ) and receiver ( $Pr$ ), in general, the calculation formula for the Power Receiver ( $Pr$ ) is as the equation 29.

$$Pr = Pt + Gt + Gr - PL \quad (29)$$

While the model of 2-ray ground reflection propagation formula from  $Pr$  added the  $ht$  and  $hr$  parameters due to the relationship with the height of the  $ht$  transmitter antenna and different  $hr$  receiving antenna which Affects the signal strength level the added angle formed from the reflected process the distance from  $x$  to  $x'$  therefore, the  $Pr$  formula becomes as the equation 30.

$$Pr (dBm) = \frac{\lambda^2}{(4 \pi d)^2} \left[ 2 \sin \frac{2 \pi}{\lambda} \frac{ht \cdot hr}{d} \right] G_t \cdot G_r \cdot P_t \quad (30)$$

Overall the variables used in the calculation are described as below:

$Pt$  = Power Transmitter (dBm)

$Pr$  = Power Receiver (dBm)

$\lambda$  = Wavelength (m)

$c$  = Speed of light (299,792,458 m/s)

$f$  = Radio Wave Frequency (Hz)

$d$  = Distance (m)

$ht$  = Height of transmitter antenna (meters)

$hr$  = Height of receiver antenna (meters)

$Gt$  = Transmitter antenna gain (dBi)

$Gr$  = Receiver antenna gain (dBi)

$PL$  = Path Loss (dBm)

$FSPL$  = Free Space Path Loss (dBm)

$RSSI$  = Receive Signal Strength Indicator (dBm)

$\pi = 3.14159265358979$

On the Ground Reflection Model, Path Difference (Capital Delta)  $\Delta$  is the result of a reduction of in reflection or ( $d''$ ) and in Line of Sight (LOS) or ( $d'$ ), therefore, the formula from the The Difference Path is shown in the equation 31.

$$\Delta = d'' - d' = \sqrt{(h_t + h_r)^2 + d^2} - \sqrt{(h_t - h_r)^2 + d^2} = \frac{2h_t h_r}{d} \quad (31)$$

Furthermore, Phase Difference  $\theta_\Delta$  is shown in equation 32, according to the equation, the difference in Phase results can be shown from the Difference Path value.

$$\theta_{\Delta} = \frac{2\pi\Delta}{\lambda} \quad (32)$$

as for the correlation with Time delay shown in equation 33. According to the equation 33, Time delay is generated from the division of the Difference Path and the speed of light (c), and equal to Phase Difference divided by  $2\pi f_c$ , where  $f_c$  is the carrier frequency.

$$t_d = \frac{\Delta}{c} = \frac{\theta_{\Delta}}{2\pi f_c} \quad (33)$$

furthermore, the Power Receiver ( $P_r$ ) can be formulated as in equation 34.

$$P_r = P_t G_t G_r \left(\frac{h_t h_r}{d^2}\right)^2 \quad (34)$$

Referring to equation 26 and 27, the comparison of the PathLoss (-dBm) results can be seen in the graph Fig. 20, the path loss value is influenced by the transmitter location, in the experiment on the hill, the transmitter is placed in different positions, which affects the signal reception power from the Fig. 14 it can be seen that the higher the transmitter is the greater the strength of the  $P_{rx}$  Signal. The first analysis is on 2-ray ground propagation models using the Matlab software, by looking at equation 30, wavelength ( $\lambda$ ) value is 0.125 m, with 3 sender height ( $H_t$ ) different that is  $H_{t1}$  is 5m,  $H_{t2}$  is 20 m and  $H_{t3}$  is 40 m with Receiver height ( $H_r$ ) is 0.5 m and 50 m. This analysis functions to find out PathLoss if it is based on the sender height ( $H_t$ ) and Receiver Height ( $H_r$ ). from the analysis it was found that if the height of  $H_t$  and  $H_r$  is almost comparable, the sinusoidal wave will dock, meaning the signal can be received properly or there is still a response from the receiver even though the power or consequently,  $P_r$  (Power Receiver ) has been decreasing, from the  $H_r = 0.5$  m, the simulation it appears that the biggest Power Receiver is -54.3 dBm on  $H_t$  5m.

### U. Block Diagram

The method used in this research is the Adaptive Data Rate (ADR) Algorithm to Sensor Node 1 ( $ED_1$ ) to Sensor Node End Device ( $ED_n$ ). Adaptive Data Rate (ADR) is proven by looking at the indicators on the ToA (Time on Air), the effectiveness of the Bit Rate (bps) and the remaining energy (mW) of the Battery at the sensor node or EDs. Adaptive Data Rate (ADR) flowchart can be seen in the Research reference [7],[26].

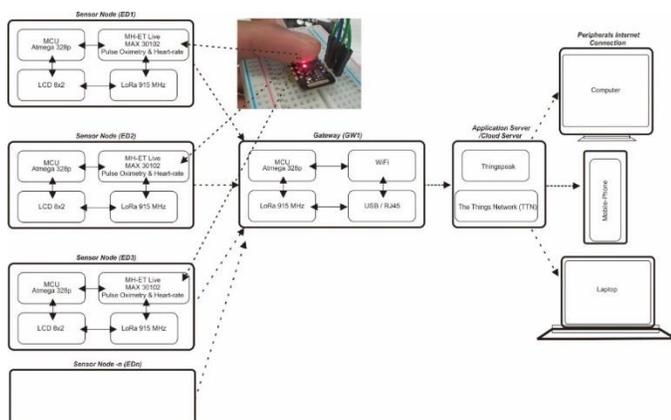


Fig. 8. Blog Diagram on this Research.

Fig. 8 is a blog diagram showing this research, this blog diagram explains how the research works from start to finish and how sensors work on EDs, furthermore, EDs transmit sensor data (transmitting) MH-ET Live Max30102 data to LoRa Gateway (GW). Furthermore, Gateway will store sensor data bits from n EDs and calculate Uplink and downlink values on the Application Server (TTN or Thingspeak) or Cloud Server LoRa. Furthermore, the MH-ET Live Max30102 sensor data provides an IP Address that can be accessed by internet-connected devices.

## IV. RESULT AND DISCUSSION

### A. Comparison of LoRa Parameters

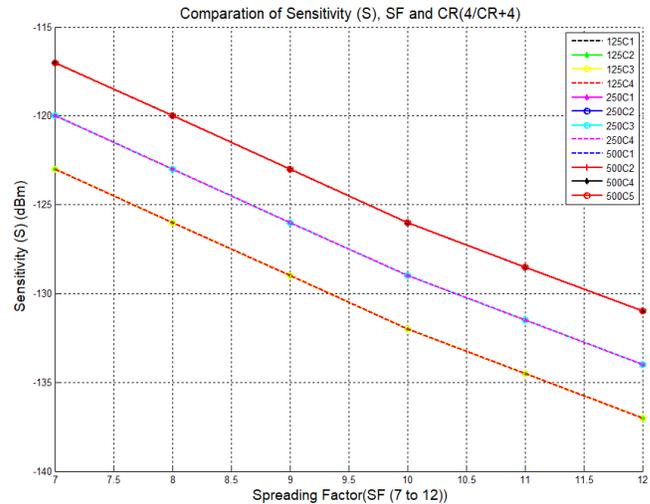


Fig. 9. Sensitivity of LoRa.

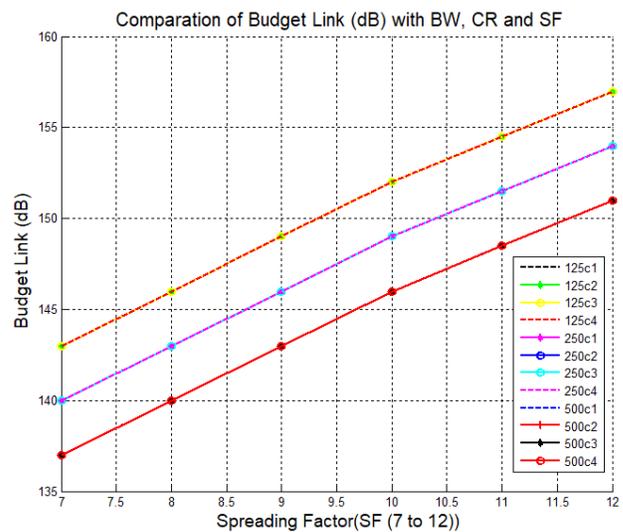


Fig. 10. Comparison of Budget Link (dB), SF and CR (4/CR+4).

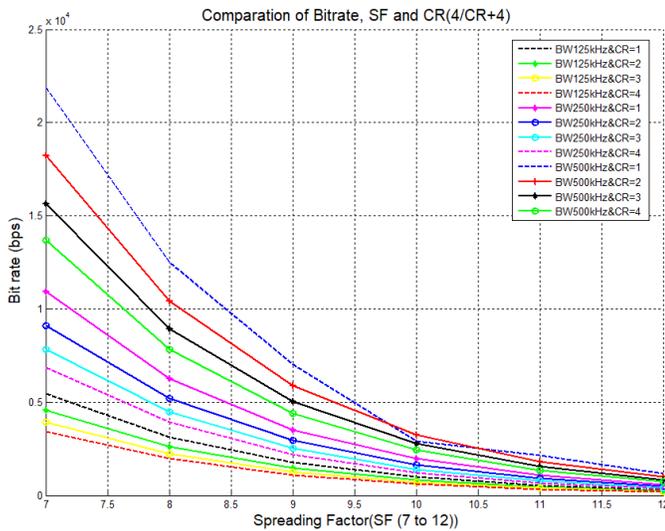


Fig. 11. Comparison of Bitrate (BW), SF and CR (4/CR+4).

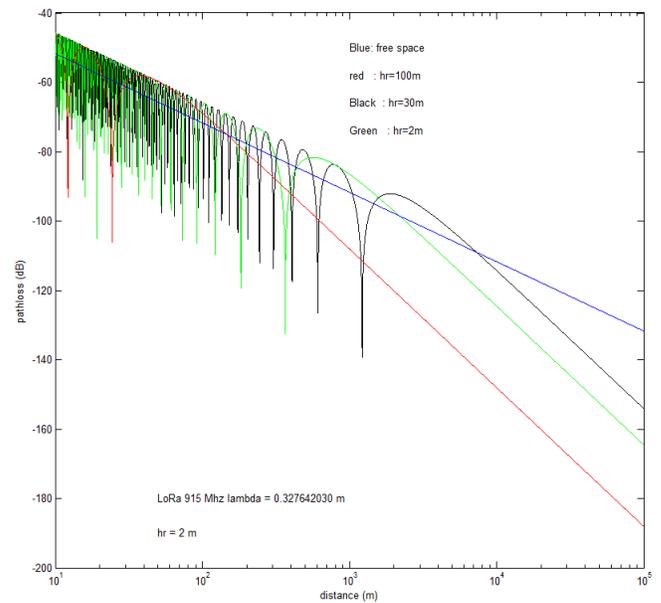


Fig. 14. LoRa 915 MHz Pathloss [dBm] of 2-Ray Ground Reflection Model.

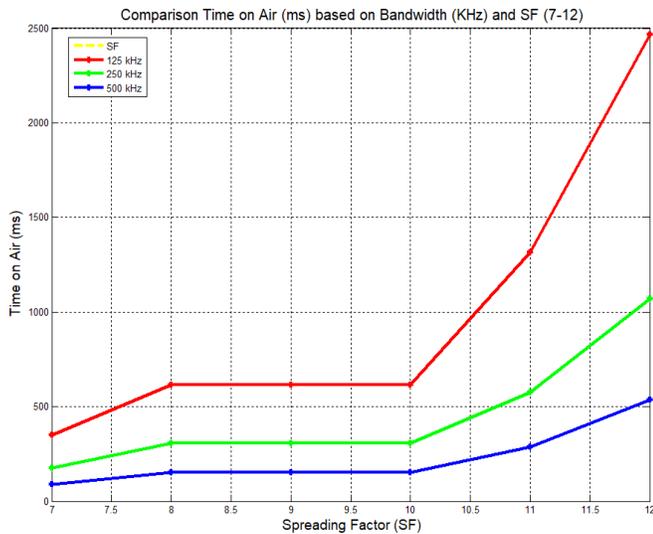


Fig. 12. ToA (ms) with SF.

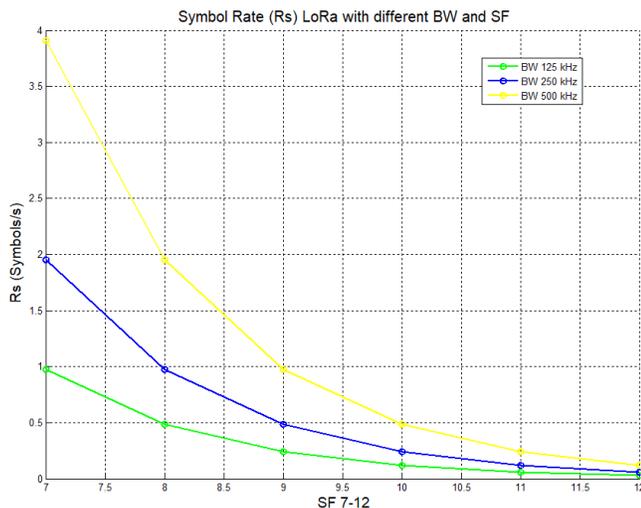


Fig. 13. Comparison of Symbol rate (Rs), BW and SF.



Fig. 15. LoRa Gateway, LoRa Tx and LoRa Rx.

**B. Testing uses a Serial Monitor and LoRa Library**

The first trial is sending the MH-ET Live sensor data max30102 sensor, point to point from the LoRa transmitter (Tx) to the LoRa receiver (Rx), from this step, it will be known that LoRa can communicate well, furthermore, the GW, Lora Tx and LoRa Rx can be showed on Fig. 15. Furthermore, Fig. 16, 17, 18, 19 and 20 are the output produced from LoRa Tx and LoRa Rx, at a certain distance on Arduino Serial Monitor, in LoRa Rx the RSSI, SNR and Packet Frequency Error values are indicated. According to him, in previous experiments the value of RSSI and SNR would experience attenuation signal based on the increasingly longer distance between Tx and Rx.

```
COM4
IR=920, BPM=0.00, Avg BPM=0 No finger?
IR=900, BPM=0.00, Avg BPM=0 No finger?
IR=921, BPM=0.00, Avg BPM=0 No finger?
IR=904, BPM=0.00, Avg BPM=0 No finger?
IR=902, BPM=0.00, Avg BPM=0 No finger?
IR=908, BPM=0.00, Avg BPM=0 No finger?
IR=908, BPM=0.00, Avg BPM=0 No finger?
IR=915, BPM=0.00, Avg BPM=0 No finger?
IR=910, BPM=0.00, Avg BPM=0 No finger?
IR=906, BPM=0.00, Avg BPM=0 No finger?
IR=902, BPM=0.00, Avg BPM=0 No finger?
IR=905, BPM=0.00, Avg BPM=0 No finger?
IR=904, BPM=0.00, Avg BPM=0 No finger?
IR=909, BPM=0.00, Avg BPM=0 No finger?
IR=926, BPM=0.00, Avg BPM=0 No finger?
IR=907, BPM=0.00, Avg BPM=0 No finger?
IR=902, BPM=0.00, Avg BPM=0 No finger?
IR=913, BPM=0.00, Avg BPM=0 No finger?
IR=903, BPM=0.00, Avg BPM=0 No finger?
IR=920, BPM=0.00, Avg BPM=0 No finger?
IR=915, BPM=0.00, Avg BPM=0 No finger?
```

Fig. 16. Output Data from LoRa Tx No Finger.

```
COM4
IR=125134, BPM=72.90, Avg BPM=65
IR=125099, BPM=72.90, Avg BPM=65
IR=125070, BPM=72.90, Avg BPM=65
IR=125065, BPM=72.90, Avg BPM=65
IR=125063, BPM=72.90, Avg BPM=65
IR=125058, BPM=72.90, Avg BPM=65
IR=125074, BPM=72.90, Avg BPM=65
IR=125088, BPM=72.90, Avg BPM=65
IR=125092, BPM=72.90, Avg BPM=65
IR=125083, BPM=72.90, Avg BPM=65
IR=125099, BPM=72.90, Avg BPM=65
IR=125099, BPM=72.90, Avg BPM=65
IR=125105, BPM=72.90, Avg BPM=65
IR=125126, BPM=72.90, Avg BPM=65
IR=125139, BPM=72.90, Avg BPM=65
IR=125
```

Fig. 17. Output Data from LoRa Tx with Finger Detected.

### C. Sensor Output

There are three examples of sensor output, on Fig. 21 is a graph from Arduino Serial Plotter, when Finger is not in the position of the sensor properly, so that the signal is irregular and does not show a precise value. Furthermore, Fig. 22 is when the finger is in the right position on the sensor, thus producing a precise HeartBeat value and the sensor detects Arterial Blood, while Fig. 23, the signal shows an inaccurate and changing value because the object used is not Finger, but the object, in other words, cannot detect Arterial Blood.

```
COM3
' with Packet Frequency Error -478
Received packet 'IR=886, BPM=0.00, Avg BPM=0 No finger?
' with RSSI -11
' with SNR 9.75
' with Packet Frequency Error -478
Received packet 'IR=894, BPM=0.00, Avg BPM=0 No finger?
' with RSSI -11
' with SNR 9.75
' with Packet Frequency Error -461
Received packet 'IR=888, BPM=0.00, Avg BPM=0 No finger?
' with RSSI -11
' with SNR 10.00
' with Packet Frequency Error -461
Received packet 'IR=892, BPM=0.00, Avg BPM=0 No finger?
' with RSSI -11
' with SNR 10.00
' with Packet Frequency Error -461
Received packet 'IR=921, BPM=0.00, Avg BPM=0 No finger?
' with RSSI -11
' with SNR 9.75
' with Packet Frequency Error -478
```

Fig. 18. Output RSSI and SNR Data from LoRa Rx.

```
COM4
red=1791, ir=1789, HR=166, HRvalid=1, SPO2=-999, SPO2Valid=0
red=1784, ir=1792, HR=166, HRvalid=1, SPO2=-999, SPO2Valid=0
red=1791, ir=1802, HR=166, HRvalid=1, SPO2=-999, SPO2Valid=0
red=1795, ir=1799, HR=166, HRvalid=1, SPO2=-999, SPO2Valid=0
red=1798, ir=1793, HR=166, HRvalid=1, SPO2=-999, SPO2Valid=0
red=1781, ir=1787, HR=166, HRvalid=1, SPO2=-999, SPO2Valid=0
red=1802, ir=1796, HR=166, HRvalid=1, SPO2=-999, SPO2Valid=0
red=1787, ir=1781, HR=166, HRvalid=1, SPO2=-999, SPO2Valid=0
red=1792, ir=1794, HR=166, HRvalid=1, SPO2=-999, SPO2Valid=0
red=1789, ir=1779, HR=166, HRvalid=1, SPO2=-999, SPO2Valid=0
red=1807, ir=1794, HR=166, HRvalid=1, SPO2=-999, SPO2Valid=0
red=1785, ir=1789, HR=115, HRvalid=1, SPO2=-999, SPO2Valid=0
red=1798, ir=1792, HR=115, HRvalid=1, SPO2=-999, SPO2Valid=0
red=1796, ir=1786, HR=115, HRvalid=1, SPO2=-999, SPO2Valid=0
red=1797, ir=1794, HR=115, HRvalid=1, SPO2=-999, SPO2Valid=0
```

Fig. 19. Output SPO<sub>2</sub> Sensor Data (Not Valid).

```
COM4
red=62055, ir=54631, HR=136, HRvalid=1, SPO2=74, SPO2Valid=1
red=62105, ir=54598, HR=136, HRvalid=1, SPO2=74, SPO2Valid=1
red=62128, ir=54577, HR=136, HRvalid=1, SPO2=74, SPO2Valid=1
red=62155, ir=54554, HR=136, HRvalid=1, SPO2=74, SPO2Valid=1
red=62164, ir=54519, HR=136, HRvalid=1, SPO2=74, SPO2Valid=1
red=62178, ir=54484, HR=136, HRvalid=1, SPO2=74, SPO2Valid=1
red=62207, ir=54448, HR=136, HRvalid=1, SPO2=74, SPO2Valid=1
red=62196, ir=54421, HR=136, HRvalid=1, SPO2=74, SPO2Valid=1
red=62217, ir=54424, HR=136, HRvalid=1, SPO2=74, SPO2Valid=1
red=62286, ir=54410, HR=136, HRvalid=1, SPO2=74, SPO2Valid=1
red=62324, ir=54374, HR=136, HRvalid=1, SPO2=74, SPO2Valid=1
red=62333, ir=54369, HR=136, HRvalid=1, SPO2=74, SPO2Valid=1
red=62411, ir=54328, HR=136, HRvalid=1, SPO2=74, SPO2Valid=1
red=62403, ir=54331, HR=136, HRvalid=1, SPO2=74, SPO2Valid=1
red=62411, ir=54267, HR=136, HRvalid=1, SPO2=74, SPO2Valid=1
```

Fig. 20. Output SPO<sub>2</sub> Sensor Data (Valid).

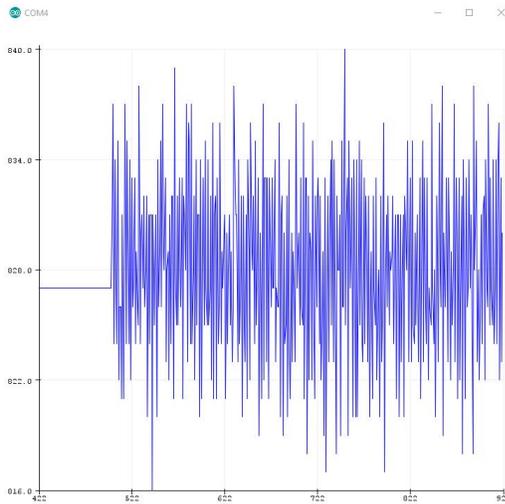


Fig. 21. The Finger is Not Placed on the Sensor, there is no Detection of Arterial Blood.

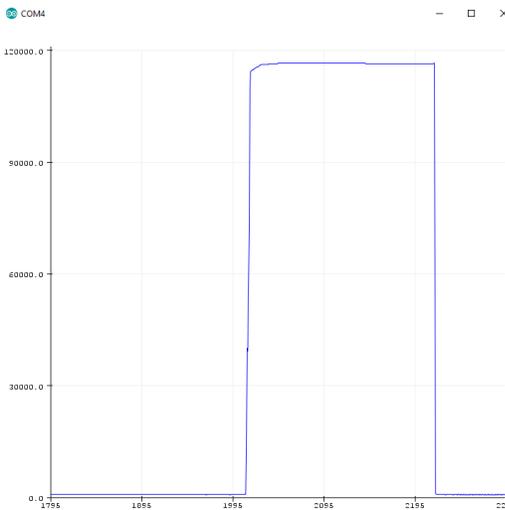


Fig. 22. The Finger is Detected by the Sensor Precisely.

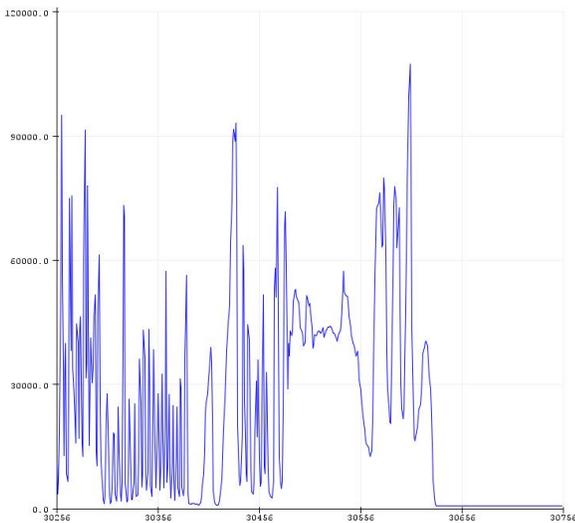


Fig. 23. Using Objects other than Fingers, the Hearth Rate Data is not Accurate.

In Fig. 24, it shows the Power Receiver (-dB) output in the Free Space Path Loss condition at the LoRa 915 MHz Frequency. At a test distance of 1 to 5000 m, the Power Receiver experiences attenuation from ~ 30 dB to ~ 105 dB at a distance of 5 km. furthermore, Fig. 25 is using a different frequency, resulting in the conclusion that with a Frequency of 433 MHz at the same distance can experience attenuation (-dB) which is smaller than other frequencies. Whereas in Fig. 26, that the types of material on the obstacle affect the attenuation signal, the smallest is shown with glass material 6 mm and 13 mm, and the greatest influence on the attenuation signal is Stone Wall and Concrete.

#### D. Observations using the Signal Analyzer

The MH-ET Live max30102 sensor data is sent using the 915 MHz Dragino LoRa board. 2 output displays are using the Arduino IDE Microcontroller serial monitor and using the LoRa Output with the command. LoRa.beginPacket, furthermore, in this case, the delay must be disabled so that the MH-ET Live max30102 sensor data is sent continuously and Chirp Signal data can be obtained. Fig. 27 and Fig. 28 are an example of a 915 MHz LoRa Spectrum using the Textronix Signal Analyzer. Fig. 28 is accompanied by a process signal demodulation. Furthermore, Fig. 29 is the LoRa Chirp signal in a position with the 10 MHz Span. Chirp shows the different ToA (ms) based on the value of Tpayload and preamble.

Fig. 30 shows the SNR (-dB) and RSSI (-dBm) values in the Receiver. The RSSI (-dBm) value attains attenuation if the distance is further (km).

Fig. 31 is the RSSI of LoRa on indoor Obstacles, these Obstacles i.e, 1 Glass Door, 2 Glass Doors, 3 Glass Doors based on increasingly longer distances (m). (a) is a distance of 10 m without obstacle (influenced by interferences) having an RSSI of ~ -20 to ~ -40 dBm, (b) a distance of 20 m is blocked by 1 glass door having an RSSI of ~ -60 dBm (c) is a distance of 30 m blocked by 3 glass doors having RSSI of ~ -80 to ~ -100 dBm, and (d) a distance of 40 m blocked by 2 doors having RSSI of ~ -70 dBm and (e) returning to initial position ie there is no barrier as in position (a). therefore, from this experiment, it can be seen that RSSI (-dBm) has an attenuation signal by Obstacle which is Glass material, according to Fig. 26.

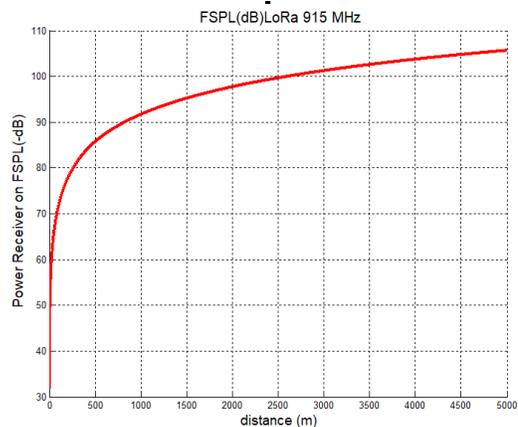


Fig. 24. Power Receiver of LoRa Module 915 MHz.

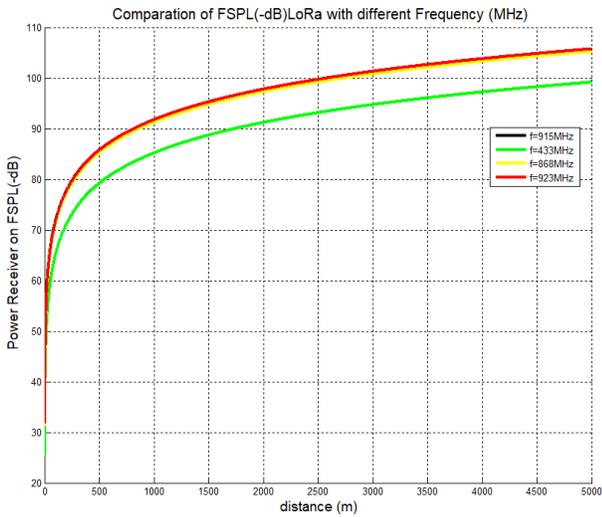


Fig. 25. Power Receiver of LoRa (-dB) Module with different Frequency.

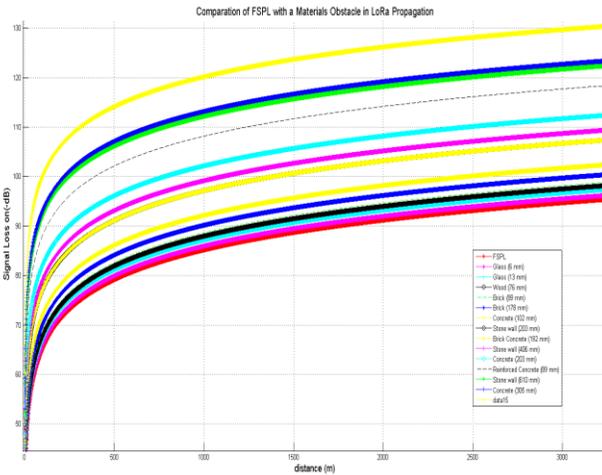


Fig. 26. Comparison of FSPL with Materials Obstacle LoRa Propagation.

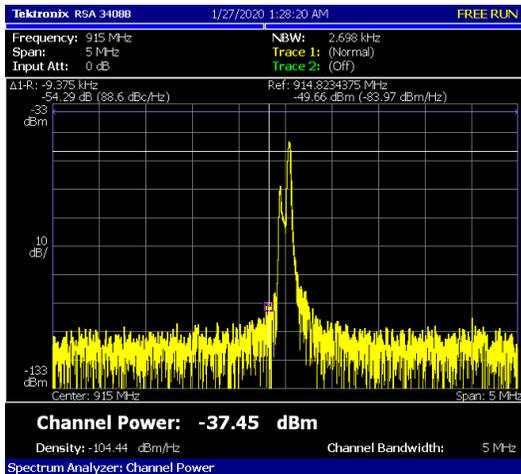


Fig. 27. LoRa Signal use a Signal Analyzer.

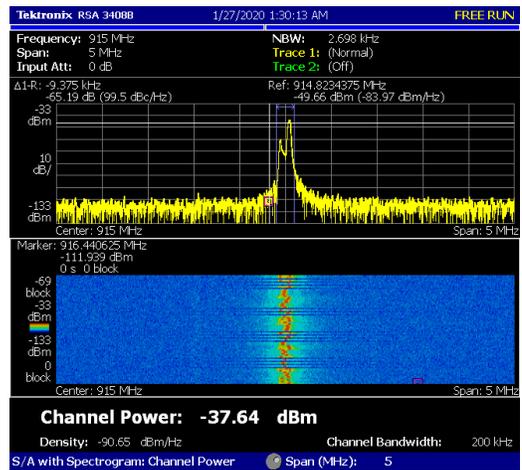


Fig. 28. LoRa Signal use a Signal Analyzer with Modulation Signal.

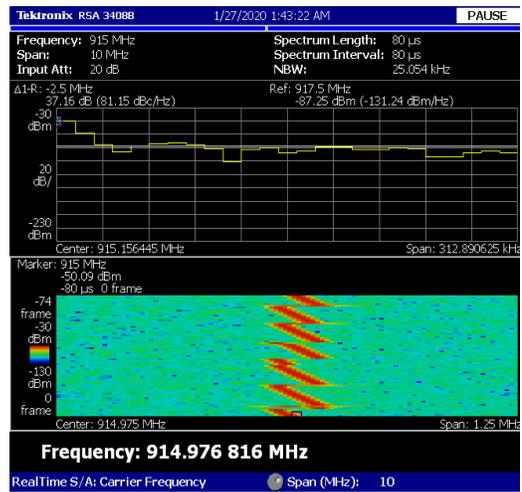


Fig. 29. LoRa Chirp Signal.

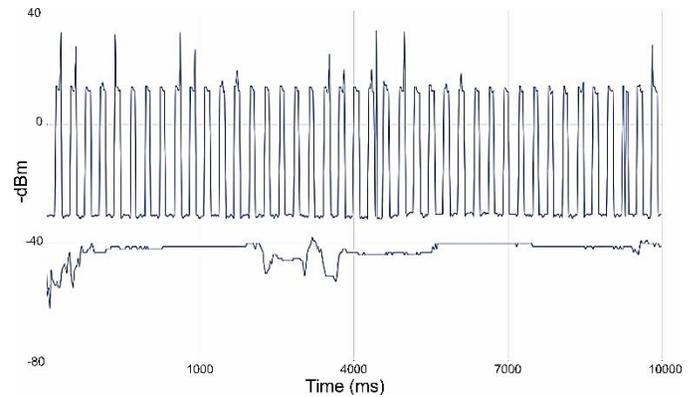


Fig. 30. RSSI and SNR Output on the LoRa Rx.

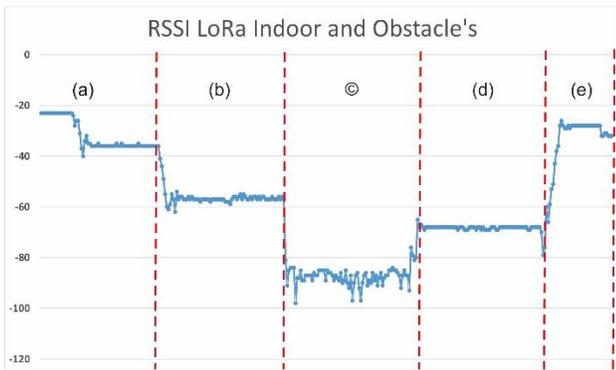


Fig. 31. RSSI (-dBm) of RF96 LoRa on Indoor Obstacles.

### E. Consumption Node and ToA Analysis

In this chapter, an analysis of the Consumption sensor node and Time on Air (ToA), with parameters 1. In other research, Power Consumption requires a method or model for efficiency, such as the use of the ARSy Framework Model to protect resources on CPU, Battery, and memory [27].

```

Parameters_1 :
LoRa Modem Setting
Spreading Factor (SF) = 7 - 12
Bandwidth (BW) = 125, 250 and 500 kHz
Coding Rate (CR) = 1, 2, 3 and 4 (4/CR+4)
Low DataRate = ON
Packet Configuration
Payload Length = 8 bytes
Programmed Preamble = 6 symbols
CRC Enabled
RF Settings
Centre Frequency = 915 MHz
Transmit Power (Tx) = 20 dBm
Battery Voltage 3.7 volt, 1000 mAh
Duty Cycle 2000 ms
ACK length 2 byte
Interrogation 4 per day
    
```

In Fig. 32, 33 and 34, it can be seen that the change in Time on Air (ms) is based on changes in Spreading Factor (SF) and the difference in Bandwidth (BW) gives different values on Time on Air (ms), in all three figures, it can be concluded that with a large bandwidth (kHz), it will have fast (ms) data transferring time. e.g, 500 kHz with SF 12 requires a ToA of ~ 37 ms. Whereas 125 kHz on SF 12 requires a longer ToA of ~ 62 ms. Or on a 250 kHz bandwidth of around ~ 45 ms.

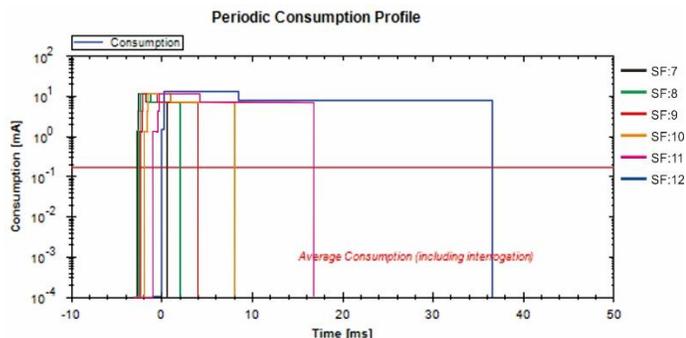


Fig. 32. Periodic Consumption with 500 kHz, CR=1,2,3,4 and SF =7 to 12.

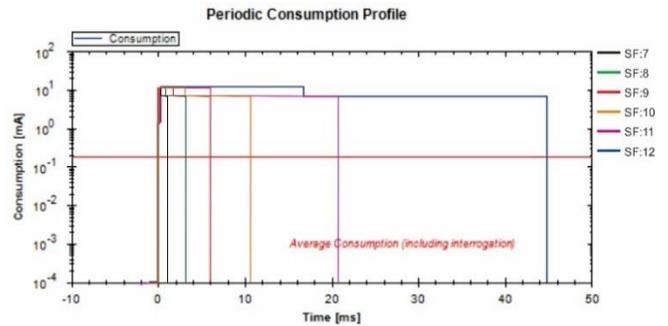


Fig. 33. Periodic Consumption with 250 kHz, CR=1,2,3,4 and SF =7 to 12.

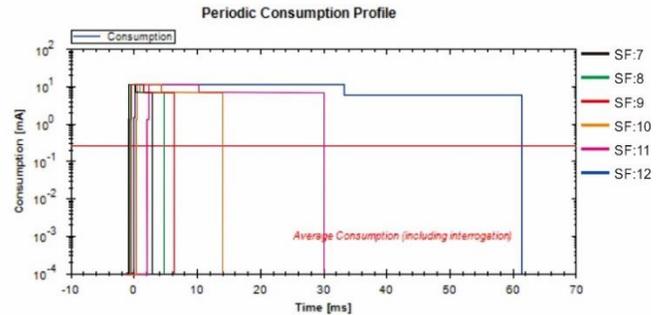


Fig. 34. Periodic Consumption with 125 kHz, CR=1,2,3,4 and SF =7 to 12.

## V. CONCLUSIONS

The MH-ET Live sensor can produce several outputs, eg, IR Value, SPO<sub>2</sub>, and Heart Rate (BPM), this sensor is compatible with ATmega 328p MCU with various types e.g., Arduino mini, therefore, right to create light-sized sensor nodes making it easier for users in SPO<sub>2</sub> and Heart Rate (BPM) testing. Spreading Factor affects the amount of bitrate (bps) and Time on Air (ms), the greater the bandwidth, the faster the process of transmitting data (ms). Attenuation when the process of transmitting sensor data (Signal propagation) is influenced by the type of material that becomes the obstacle signal  $T_x$  to  $R_x$  at a certain distance. The farther the distance, the greater attenuation (dB), e.g. FSPL LoRa at 3 km without obstacle is ~ 80 dB. Whereas with an obstacle at the same distance, attenuation occurs to ~ 130 dB. furthermore, The Two Ray Ground Reflection model is only used if the position of the Antenna LoRa transmitter ( $T_x$ ) is at a certain height ( $H_T$ ) which affects the reflection signal which causes attenuation which affects the signal strength at the receiver ( $R_x$ ).

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