A Novel Robust Stacked Broad Learning System for Noisy Data Regression

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Abstract-Robust broad learning system (RBLS) demonstrates the generalization and robustness for solving uncertain data regression tasks. To enhance representation ability of RBLS, this paper aims at developing a novel robust stacked broad learning system for solving noisy data regression problems, termed as RSBLS. In our work, we expand traditional BLS into a stacked broad learning system model with deep structure of feature nodes and enhancement nodes. Furthermore, ℓ_1 norm loss function is employed to update the objective function of RSBLS for processing noisy data, we apply augmented Lagrange multiplier (ALM) to get the output weights of RSBLS which keeps the effectiveness and efficiency compared with weighted loss function. Simulation results over some regression datasets with outliers demonstrate that, the proposed **RSBLS** performs favorably with better robustness with respect to RVFL, BLS, Huber-WBLS, KDE-WBLS and RBLS.

Keywords—Robust; stacking; broad learning system; deep learning; neural networks

I. INTRODUCTION

Recently, inspired by random vector functional link neural networks (RVFL) [1, 2], Chen et al. proposed a novel randomized neural network architecture, broad learning system (BLS) [3-5]. Compared with the classical deep learning model, BLS adopts the broad structure which has the advantages of higher efficiency and fewer parameters. Due to its excellent learning ability, BLS has been widely concerned by scholars since it was proposed, and has developed rapidly in theoretical and applied research. To improve the interpretability of BLS, a novel broad neuro-fuzzy model, fuzzy broad learning system (FBLS) was presented, which reduces the number of fuzzy rules and improves the learning accuracy neuro-fuzzy model [6]. Subsequently, Guo et al. used FBLS to synthesize multiview HDR images [7], Ali proposed a novel optic disk and cup segmentation method through FBLS for glaucoma screening [8]. Furthermore, compact FBLS (CFBLS) which has better interpretability and fewer fuzzy rules was designed to balance the algorithm accuracy and complexity [9]. For improve the representation of BLS, type-2 fuzzy BLS was given in [10]. For solving sequential data, recurrent broad learning system and structured manifold broad learning system (SM-BLS) were presented respectively [11, 12]. To process the data with less label, semi-supervised broad learning system (SS-BLS) by introducing manifold regularization method to BLS [13], and some other SS-BLS algorithms had been used in semisupervised classification tasks [14, 15]. Otherwise, BLS and its variants had been extensive used in various engineering fields,

such as traffic forecasting [16], image classification [17], EEG signals classification [18-20], sentiment analysis [21, 22].

practical engineering applications, In sensors are susceptible to equipment failure, human interference, working environment and other factors, and there are different degrees of noises and outliers in the collected data, thus reducing the generalization of the learning model. To solve the uncertain data regression problem effectively, Chu et al. proposed weighted broad learning system (WBLS) framework for tackling industrial noisy data [23]. Then, Zheng et al. designed a broad learning system based on maximum correntropy criterion (BLS-MCC) which used maximum correntropy criterion to calculate weights of training samples [24]. In addition, Liu et al. adopted Cauchy loss function to process the noisy data [25]. Meanwhile, ℓ_1 norm cost function and ℓ_2 regularization method were used in robust broad learning system (RBLS) [26], then elastic-net regularization approach replaced ℓ_2 regularization method in RBLS [27]. Moreover, robust manifold broad learning system (RM-BLS) was used to predict large-scale noisy chaotic time series [28]. In addition, for online sequential learning, Guo et al. presented online robust echo state broad learning system (OR-ESBLS) [29]. However, the above models improved the robustness of BLS, the shallow models still lack feature representation capability.

Now-a-days, deep neural networks with multi-layer have powerful representation capability, BLS was also been expanded with multi-layers [30-32]. Therefore, to improve the noisy data processing performance of RBLS, we demonstrate a novel robust stacked broad learning system (RSBLS) for solving outlier data regression, which adopts deep structure of feature nodes and enhancement nodes through stacking deep model, ℓ_1 norm loss function and ℓ_2 regularization method ensure the learning accuracy and efficiency.

In brief, the highlights of RSBLS are listed as follows:

- A novel robust stacked broad learning system structure is demonstrated, we presented the model architecture and algorithm description of RSBLS in detail.
- ℓ_1 norm loss function and ℓ_2 regularization method are adopted to enhance the robustness of RSBLS.
- Experiments on the benchmark datasets with different noise ratios present the superiority of RSBLS.

The other sections of our manuscript are given as follows: Section II introduces the basic algorithm description of BLS. Section III presents the architecture and optimization method of the proposed RSBLS. Section IV demonstrates the uncertain data regression results on some datasets with different percentage of outliers. Finally Section V concludes the paper.

II. RELATED WORKS

BLS is novel random neural network model with effective and efficient performance, proposed by Chen et al., which has the architecture as Fig. 1 [3-5].



Fig. 1. The structure of BLS [3-5].

The modeling process of BLS is given as follows [3-5]:

Given a training data $\{X,Y\}$, $X = \{x_1, x_2, ..., x_N\}$ and $Y = \{y_1, y_2, ..., y_N\}$ express the feature and label. Among them, $x_i = \{x_{i,1}, x_{i,2}, ..., x_{i,d}\} \in \square^d$, *d* is denoted as the number of feature dimension; i = 1, 2, ..., N, *N* indicates the number of training samples.

A. Feature Nodes Generation

The feature nodes are generated through Eq. (1), then n groups of mapping nodes can be combined according to Eq. (2), each group has L_e feature nodes.

$$Z_p = \phi(XW_{ep} + \beta_{ep}) \tag{1}$$

$$Z^{n} = [Z_{1}, Z_{2}, \dots, Z_{n}]$$
 (2)

Among them, $\phi(\cdot)$ indicates the activation function of feature mapping; W_{ep} and β_{ep} represent random weights and biases respectively; p = 1, 2, ..., n. In particularly, the authors of BLS use sparse autoencoder to tune the initial parameters for obtaining better features [3-5].

B. Enhancement Nodes Generation

All the feature nodes in Eq. (2) are enhanced by using Eq. (3), each enhancement processing generate L_h nodes. Then the enhancement nodes can be combined according to Eq. (4).

$$H_q = \xi (Z^n W_{hq} + \beta_{hq}) \tag{3}$$

$$H^{m} = [H_{1}, H_{2}, \dots, H_{m}]$$
 (4)

where, $\xi(\cdot)$ is denoted as the activation function, it can be set as the same as $\phi(\cdot)$; W_{hq} and β_{hq} are generated randomly; q = 1, 2, ..., m.

C. Output Y determination

The output \hat{y} of BLS can be calculated according to Eq. (5).

$$Y = [Z^n \mid H^m]W \tag{5}$$

$$W = [Z^n \mid H^m]^+ Y \tag{6}$$

where, *W* represents the output weight of BLS, $[Z^n | H^m]^+$ is determined by the ridge regression approximation as Eq. (7).

$$[Z^{n} | H^{m}]^{+} = \lim_{\lambda \to 0} (\lambda I + [Z^{n} | H^{m}][Z^{n} | H^{m}]^{T})^{-1} [Z^{n} | H^{m}]^{T}$$
(7)

III. ROBUST REGULARIZED HIERARCHICAL BROAD LEARNING SYSTEM

A. The Structure of RSBLS

BLS, as a randomized learning algorithm, has an effective and efficient structure. Although the novel structure can reduce the computational burden and enhance learning accuracy, BLS with multi-layer structure can extract deep representation information [30-33]. Meanwhile, the noisy and outliers in the training data affect the accuracy and generalization performance of BLS seriously. Therefore, we propose a novel RSBLS to solve noisy data regression problems. It is different from traditional BLS, RSBLS has multi-layer structure of feature nodes and enhancement nodes, the feature nodes and enhancement nodes of each layer are used as the input of next layer, only the feature nodes and enhancement nodes of the final layer are fully connected with the output.

In addition, due to the outliers usually take up a fraction of training data, the noisy data can be understood as having sparsity, ℓ_1 norm function is not only more robust to solving the sparsity data, but also ensures a faster learning efficiency, it is especially suitable for solving large-scale data and deep models [34, 35]. The RSBLS adopts ℓ_1 norm cost function and ℓ_2 regularization method to solve the noisy data regression. Fig. 2 demonstrates the model structure of RSBLS; the RSBLS algorithm is described as follows:

1) RSBLS parameters initialization: To simplify the RSBLS model, the layer number is set as U, the feature mapping times of each layer are set to nu, the number of neurons in each feature mapping is L_{ue} , the enhancement processing times of each layer are set to mu, and the number of neurons in each enhancement processing is L_{uh} .

a) Feature nodes generation: The original data X is transformed into feature nodes by using Eq. (8), then all the nodes in the feature layer are combined through Eq. (9) and Eq. (10).

$$Z_p^u = \phi(X^u W_{ep} + \beta_{ep}) \tag{8}$$

$$Z^{u} = [Z_{1}^{u}, Z_{2}^{u}, \dots, Z_{nu}^{u}]$$
⁽⁹⁾

where, $X^1 = X$; $X^u = S^{u-1}$; $\phi(\cdot)$ indicates the activation function of feature mapping; W_{ep} and β_{ep} are random values of feature nodes; p = 1, 2, ..., nu; u = 1, 2, ..., U.



Fig. 2. The structure of RSBLS.

b) Enhancement nodes generation: All the feature nodes in Eq. (9) are enhanced as enhancement nodes through Eq. (10), then all the enhancement nodes are connected by Eq. (11).

$$H_q^u = \xi([Z^u W_{hq} + \beta_{hq}) \tag{10}$$

$$H^{u} = [H_{1}^{u}, H_{2}^{u}, \dots, H_{mu}^{u}]$$
(11)

where, $\xi(\cdot)$ expresses the activation function of enhancement processing; W_{hq} and β_{hq} indicate the random parameters of enhancement nodes; q = 1, 2, ..., mu; u = 1, 2, ..., U.

In addition, we combine all the nodes of layer u through Eq. (12) as the input of next layer.

$$S^{u} = [Z^{u}, H^{u}] \tag{12}$$

c) Target output matrix Y determination: To reduce the computational burden of RSBLS, we only connect the feature nodes and enhancement nodes of layer U in Eq. (13), then we use the ℓ_1 norm cost function and ℓ_2 regularization method to calculate the model output weights as Eq. (14).

$$S^U = [Z^U, H^U] \tag{13}$$

$$\beta = \arg\min_{\beta} \|S^{U}\beta - Y\|_{1} + C\|\beta\|_{2}^{2} \qquad (14)$$

where, *C* express as the ℓ_2 regularization parameter.

The outputs of RSBLS can be calculated by Eq. (15).

$$Y = S^U \beta \tag{15}$$

B. The Optimization of RSBLS

Hence Eq. (14) can be considered as a constrained convex optimization problem, we use augmented Lagrange multiplier (ALM) approach to solve this problem, and Eq. (14) can be transformed as Eq. (16).

$$L_{\mu}(e,\beta,\gamma) = ||e||_{1} + \frac{1}{C} ||\beta||_{2}^{2}$$

+ $\upsilon^{T}(Y - H\beta - e) + \frac{\mu}{2} ||Y - H\beta - e||_{2}^{2}$ (16)

where, $e = \beta H - Y$; U is denoted as the vector of Lagrange multiplier; $\mu = 2N/||Y||_1$.

The optimal (e, β) and the Lagrange multiplier υ can be optimized by ALM method iteratively by using Eq. (17).

$$\begin{cases} (e_{\rho+1}, \beta_{\rho+1}) = \arg\min_{e,\beta} L_{\mu}(e, \beta, \upsilon_{\rho}) \\ \upsilon_{\rho+1} = \upsilon_{\rho} + \mu(Y - H\beta_{\rho+1} - e_{\rho+1}) \end{cases}$$
(17)

Moreover, we transform Eq. (17) as Eq. (18), then $\beta_{\rho+1}$ and $e_{\rho+1}$ are expressed as Eq. (19) and Eq. (20) respectively.

$$\begin{cases} \beta_{\rho+1} = \arg\min_{\beta} L_{\mu}(e_{\rho}, \beta, \upsilon_{\rho}) \\ e_{\rho+1} = \arg\min_{e} L_{\mu}(e, \beta_{\rho+1}, \upsilon_{\rho}) \\ \upsilon_{\rho+1} = \upsilon_{\rho} + \mu(Y - H\beta_{\rho+1} - e_{\rho+1}) \end{cases}$$
(18)

$$\beta_{\rho+1} = (H^T H + 2 / C \mu I)^{-1} H^T (Y - e_{\rho} + v_{\rho} / \mu) \quad (19)$$
$$e_{\rho+1} = \text{shrink} (Y - H \beta_{\rho+1} + v_{\rho} / \mu, 1 / \mu)$$

$$\max\{|Y - H\beta_{\rho+1} + v_{\rho} / \mu - 1 / \mu, 0|\}$$
(20)
osign $(Y - H\beta_{\rho+1} + v_{\rho} / \mu)$

where, "o" denotes the element-wise multiplication.

The algorithm flow of RSBLS is described in Algorithm 1.

Algorithm 1: RSBLS Dataset: $X = \{x_1, x_2, ..., x_N\}$, $x_i = \{x_{i,1}, x_{i,2}, ..., x_{i,d}\} \in \square^d$; $Y = \{y_1, y_2, ..., y_N\}$.

Parameters: the number of feature layer V, the feature mapping times of each layer n, the number of neurons in each feature mapping L_e ; the number of enhancement layer U, the enhancement processing times of each layer m, the number of neurons in each enhancement processing L_h .

Output: Y.

1. Initialize p=1, q=1, u=1

Phase 1: feature nodes generation (Step 2-8)

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2. for u \leq U, do
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3. for p \le nu, do
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- 4. Generate W_{ep} and β_{ep} randomly;
- 5. Calculate Z_p^u using Eq. (8);

6. end for

 $7. \ \text{end for}$

8. Set the feature mapping group Z^{u} using Eq. (9);

Phase 2: enhancement nodes generation (Step 9-15)

9. for $u \leq U$, do

- 10. for $q \le mu$, do
- 11. Generate W_{hq} and β_{hq} randomly;
- 12. Calculate H_q^u using Eq. (10);
- 13. end for
- 14. end for

15. Set the enhancement group H^{u} using Eq. (11);

Phase 3: target output matrix \hat{y} determination (Step 16-21)

- 16. **for** $\rho = 1, 2, ..., P_{\text{max}}$, **do**
- 17. $\mu = 2N / ||Y||_1, e_1 = 0, v_1 = 0$
- 18. Compute β by using Eq. (16)- Eq. (20);
- 19. **end for**
- 20. Compute output Y by using Eq. (13)- Eq. (15);
- 21. return Y.

IV. NUMERICAL EXPERIMENTS

The related experiments of our paper are programmed based on MATLAB 2019b.

A. Experimental Datasets

In this part, six benchmark datasets, including Concrete, Abalone, Stock, Mortgage, Treasury, and Compactiv from KEEL (http://www.keel.es/) are selected to demonstrate the feasibility of the RSBLS. Table I gives the corresponding information of these datasets.

In addition, to verify the robustness of RSBLS, the datasets are preprocessed as follows: we first carry out normalization processing, the features and corresponding labels are normalized in the range of [0, 1]. Moreover, 75% samples of the original datasets are selected as the training datasets randomly, the rest 25% samples are determined as the test datasets. In the last, 10%, 20%, 30%, 40% and 50% outliers with uniform distributed are inserted into the training datasets as Eq. (21).

$$y_{noise} = y + Vy_{outlier}, -0.5 \le Vy_{outlier} \le 0.5$$
(21)

where, y_{noise} expresses the contaminated training label in the range of [-0.5, 1.5]; $Vy_{outlier}$ means the random outlier.

TABLE I. THE ATTRIBUTES INFORMATION OF EXPERIMENTAL DATASETS

Datasets	Features	Instances
Concrete	8	1030
Abalone	8	4177
Stock	9	950
Mortgage	15	1049
Treasury	15	1049
Compactiv	21	8192

B. Evaluation Indexes

To present the robustness of RSBLS, we carry out all the related algorithms 50 times independently, the average root mean square error (RMSE) (see Eq. (22)) of experimental results are recorded as the evaluation indexes.

RMSE =
$$\sqrt{\frac{1}{N} \sum_{i=1}^{N} (y_i - f_i)^2}$$
 (22)

where, y_i indicates the actual value of sample *i*; f_i represents the output results of sample *i*; *N* denotes the number of samples.

C. Experimental Results

1) Parameters settings: To illustrate the proposed RSBLS, RVFL [1, 2], BLS [3-5], Huber-WBLS [23], KED-WBLS [23] and RBLS [24] are chosen as the contrast algorithms, among them, we use the sigmoidal function (see Eq. (23)) as activation function of all the compared models.

$$S(x) = \frac{1}{1 + e^{-x}}$$
(23)

Some key parameters of RSBLS, RVFL, BLS, Huber-WBLS, KED-WBLS and RBLS are listed as follows:

RVFL: the hidden layer nodes are selected from {50, 100, 150, 200}, the weights and biases are generated randomly in the range of [-1,1] and [0,1] respectively.

BLS, Huber-WBLS, KED-WBLS and RBLS: the feature mappings and feature nodes are chosen from {5, 10, ..., 45, 50}, and the enhancement nodes are selected from {50, 100, 150, 200}. Moreover, these models adopt ℓ_2 regularization technique and the regularization parameter *C* are chosen from {2⁻¹⁰, 2⁻⁵, 0, ..., 2¹⁵, 2²⁰}. Some other models are set as the same as the original references.

RSBLS: the number of layers is set as 2; the feature mappings and feature nodes of each layer are chosen from {5,

10, ..., 45, 50}, and the enhancement nodes of each layer are selected from {50, 100, 150, 200}. Moreover, these models adopt ℓ_2 regularization technique and the regularization parameter *C* are chosen from {2⁻¹⁰, 2⁻⁵, 0, ..., 2¹⁵, 2²⁰}.

2) Results and discussion: In this section, we give the performance evaluation of RSBLS, Table II to Table VII show the average test RMSE results of RSBLS compared with different models on six regression problems with uniform distributed outliers. As it can be seen from Table II to Table VII, with the increase of contamination rates, the performance of RVFL and BLS gradually become worse, Huber-WBLS, KED-WBLS and RBLS can improve the robustness of BLS.

 TABLE II.
 PERFORMANCE COMPARISON OF DIFFERENT MODELS ON CONCRETE DATASET

Models	Test Performance (RMSE) at different contamination rates			
	10%	20%	30%	40%
RVFL	0.0934	0.0970	0.1062	0.1065
BLS	0.0957	0.0981	0.0983	0.0948
Huber-WBLS	0.0890	0.0893	0.0938	0.0914
KED-WBLS	0.0936	0.0883	0.0933	0.0914
RBLS	0.0889	0.0841	0.0957	0.0953
RSBLS	0.0781	0.0783	0.0834	0.0890

TABLE III. PERFORMANCE COMPARISON OF DIFFERENT MODELS ON ABALONE DATASET

Models	Test Performance (RMSE) at different contamination rates			
	10%	20%	30%	40%
RVFL	0.0745	0.0743	0.0810	0.0782
BLS	0.0742	0.0749	0.0781	0.0756
Huber-WBLS	0.0723	0.0736	0.0777	0.0732
KED-WBLS	0.0736	0.0747	0.0776	0.0744
RBLS	0.0727	0.0738	0.0778	0.0736
RSBLS	0.0719	0.0732	0.0764	0.0720

TABLE IV. PERFORMANCE COMPARISON OF DIFFERENT MODELS ON STOCK DATASET

Models	Test Performance (RMSE) at different contamination rates			
	10%	20%	30%	40%
RVFL	0.0456	0.0549	0.0584	0.0633
BLS	0.0425	0.0520	0.0567	0.0577
Huber-WBLS	0.0311	0.0349	0.0392	0.0460
KED-WBLS	0.0355	0.0358	0.0416	0.0428
RBLS	0.0320	0.0380	0.0394	0.0409
RSBLS	0.0301	0.0340	0.0332	0.0342

TABLE V.	PERFORMANCE COMPARISON OF DIFFERENT MODELS ON
	MORTGAGE DATASET

Models	Test Performance (RMSE) at different contamination rates			
	10%	20%	30%	40%
RVFL	0.0275	0.0351	0.0527	0.0580
BLS	0.0293	0.0416	0.0518	0.0622
Huber-WBLS	0.0088	0.0124	0.0236	0.0333
KED-WBLS	0.0096	0.0111	0.0147	0.0188
RBLS	0.0052	0.0070	0.0057	0.0063
RSBLS	0.0050	0.0059	0.0062	0.0062

TABLE VI. PERFORMANCE COMPARISON OF DIFFERENT MODELS ON TREASURY DATASET

Models	Test Performance (RMSE) at different contamination rates			
	10%	20%	30%	40%
RVFL	0.0248	0.0373	0.0427	0.0507
BLS	0.0280	0.0310	0.0484	0.0538
Huber-WBLS	0.0126	0.0125	0.0195	0.0293
KED-WBLS	0.0125	0.0121	0.0184	0.0217
RBLS	0.0119	0.0114	0.0117	0.0100
RSBLS	0.0114	0.0103	0.0109	0.0090

 TABLE VII.
 PERFORMANCE COMPARISON OF DIFFERENT MODELS ON COMPACTIV DATASET

Models	Test Performance (RMSE) at different contamination rates				
	10%	20%	30%	40%	
RVFL	0.0404	0.0421	0.0451	0.0435	
BLS	0.0287	0.0287	0.0291	0.0312	
Huber-WBLS	0.0256	0.0250	0.0252	0.0278	
KED-WBLS	0.0270	0.0265	0.0262	0.0290	
RBLS	0.0249	0.0250	0.0252	0.0279	
RSBLS	0.0242	0.0243	0.0238	0.0248	

At the same time, it is obviously that RSBLS with 2 hidden layers has a better robustness compared with Huber-WBLS, KED-WBLS and RBLS. Our proposed model, RSBLS with ℓ_1 -norm loss function gains the best mean RMSE on 6 datasets, which demonstrates the effectiveness of regularization method. In addition, the uncertain data regression performance of those models on different datasets with different contamination rates indicates the strong robustness of RSBLS, at different levels of outliers; the RSBLS shows the best consistency.

In summary, RSBLS with ℓ_1 norm loss function can solve uncertain data regression with uniform distributed outliers effectively; the stacked deep model is helpful to enhance the robustness of BLS well.

V. CONCLUSION

In the paper, we propose a novel robust stacked broad learning system model with multi-layers for solving uncertain data regression problem, named as RSBLS. In the proposed RSBLS, we expand BLS into a stacked deep model with multilayer of feature nodes and enhancement nodes, which can helpful to extract deep representation information. In addition, l1-norm function is introduced to calculate the output weights of RSBLS, which can process noisy data and ensure learning efficiency of hierarchical model. Experimental results on some regression datasets with different ratios of noisy shows that, RSBLS has better robustness compared with RVFL, BLS, Huber-WBLS, KDE-WBLS and RBLS.

In the future, as some parameters should be selected by grid search which limits the search scope, some of the latest swarm intelligence algorithms can be used to choose the parameter of RBLS.

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