Enhancing Approximate Conformance Checking Accuracy with Hierarchical Clustering Model Behaviour Sampling

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Abstract—Conformance checking techniques evaluate how well a process model aligns with an actual event log. Existing methods, which are based on optimal trace alignment, are computationally intensive. To improve efficiency, a model sampling method has been proposed to construct a subset of model behaviour that represents the entire model. However, current model sampling techniques often lack sufficient model representativeness, limiting their potential to achieve optimal approximation accuracy. This study proposes new model behaviour sampling approaches using hierarchical clustering to compute an approximation closer to the exact result. This study also refines the existing upper bound algorithm for better approximation. Our experiments on six real-world event logs demonstrate that our method improves approximation accuracy compared to state-of-the-art model sampling methods.

Keywords—Approximate conformance checking; model behaviour sampling; hierarchical clustering; process mining

I. Introduction

Conformance checking is a set of process mining functionalities aimed at identifying deviations between the actual behaviour of the event log ("as-is") and the modeled behaviour of the process model ("to-be"). It facilitates further applications, such as model repair, anomaly detection, and algorithm evaluation [1]. In recent years, the alignment-based method [2] has become the de facto standard for conformance checking in the computation of conformance diagnostics, since it always returns the most accurate deviations, known as optimal alignment [3]. However, finding the optimal alignment is an NP-hard problem [4]. As the complexity of the log and model increases, the run-time complexity of optimal alignment computation grows exponentially, leading to extremely long computation times, sometimes even taking several weeks. This makes them impractical for real-world applications, especially large-scale event logs. Moreover, in certain cases, an exact conformance value is not necessary, such as when performing a preliminary evaluation of process models with various process discovery algorithms [5].

To address the problems, various approximation strategies have been proposed, including optimizing the search algorithm [6], [7] and decomposition schemes [8], [9]. However, sampling provides another angle for approximate conformance checking, such as sampling traces to represent the event log [10], [11] or selecting model traces to substitute for the process model [5], [12]. In this study, we adopt the latter approach, focusing on model sampling. Two main model sampling methods exist: simulation [13] and candidate selection [5]. We concentrate

on candidate selection due to its higher accuracy [5]. The candidate selection method identifies representative traces from the event log (i.e., log behaviour subset), and then computes their optimal alignments to determine the corresponding model traces (i.e., model behaviour subset). The accuracy of this approximation depends on the quality of the selected log traces [12]. However, existing log selection techniques (e.g., random, frequency-based [5], K-Medoids [14]) often lack behavioural diversity and model representativeness (see Section II), leading to reduced accuracy in the conformance approximation. Hence, there is significant potential for improving the quality of model behaviour subsets.

In this study, we propose an enhanced model behaviour sampling method to select more representative subsets and obtain more accurate approximate values. First, we apply hierarchical clustering to the event log using our proposed distance criterion. Then, we propose two in-cluster methods to select typical traces from each cluster, which are then used to construct more representative model behaviour subsets. Finally, we extend the existing cost lower bound algorithm to achieve more accurate approximation results. The experimental results show that our approach yields more accurate approximations than existing baselines, though with an increased approximation time.

The remainder of this study is organized as follows. Section II provides a motivating example to further illustrate the research problem. Section III discusses related work in approximate conformance checking. Section IV outlines the necessary preliminaries. In Section V, we propose our method for constructing model behaviour subsets using hierarchical clustering. Section VI details the evaluation setup. Section VII presents the experimental results, followed by Section VIII which presents the discussion. Finally, Section IX concludes the study and presents the limitations and future work.

II. MOTIVATING EXAMPLE

Research such as [5] and [15] has shown that selecting more typical log traces lead to higher approximation accuracy. Thus, the key challenge is determining which subset should be selected to improve approximate accuracy. Existing log selection methods, such as the frequency-based and K-medoids approaches, sometimes lack sufficient log representativeness.

To illustrate the potential limitations of these methods, we use a synthesized event $\log L$. It contains 5,106 traces consisting of 32,600 events and 12 trace variants, as shown in Table I.

TABLE I. EVENT LOG

ID	Trace Variant	Freq	ID	Trace Variant	Freq
0	$\langle a, b, c, d, f, e, g, h \rangle$	1280	6	$\langle a,d,f,h \rangle$	250
1	$\langle a,b,c,d,e,f,g,h\rangle$	912	7	$\langle a, f, b, c \rangle$	96
2	$\langle a,b,c,d,e,g,f,h \rangle$	864	8	$\langle a, c, e, f, g \rangle$	64
3	$\langle a, b, c, h \rangle$	792	9	$\langle a, d, e, g, h \rangle$	56
4	$\langle a, b, c, d, h \rangle$	400	10	$\langle a, b, f, e, g, h \rangle$	48
5	$\langle a,h angle$	320	11	$\langle b, f, g \rangle$	24

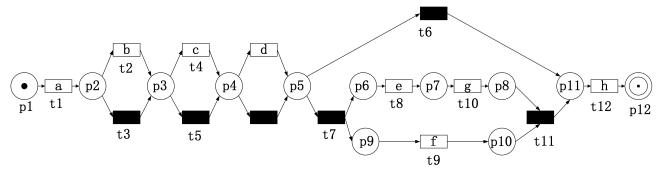


Fig. 1. The process model discovered by inductive miner with infrequent threshold equals to 0.9.

TABLE II. BEHAVIOUR SUBSETS CONSTRUCTED BY FOUR METHODS

Method	Subset	Result	Cost Deviation
	Log Behaviour	$\Sigma_L = \{ \langle a, b, c, d, f, e, g, h \rangle, \langle a, b, c, d, e, f, g, h \rangle,$	
Frequency-	Log Benavious	$\langle a,b,c,d,e,g,f,h\rangle\}$	7806
based	Model Behaviour	$\Sigma_M = \{ \langle a, b, c, d, f, e, g, h \rangle, \langle a, b, c, d, e, f, g, h \rangle,$	7000
	niodel Bellavious	$\langle a,b,c,d,e,g,f,h\rangle\}$	
	Log Behaviour	$\Sigma_L = \{ \langle a, h \rangle, \langle a, b, c, d, e, g, f, h \rangle,$	
K-Medoids	Eog Benaviour	$\langle b,f,g angle \}$	6596
TI TITEGOTAS	Model Behaviour	Model Behaviour $\Sigma_M = \{\langle a, h \rangle, \langle a, b, c, d, e, g, f, h \rangle,$	
	niodel Bellavious	$\langle a,b,e,f,g,h angle \}$	
In-cluster	Log Behaviour	$\Sigma_L = \{\langle a, h \rangle, \langle a, b, c, d, f, e, g, h \rangle, \langle a, b, c, h \rangle\}$	4698
frequency	Model Behaviour	$\Sigma_M = \{ \langle a, h \rangle, \langle a, b, c, d, f, e, g, h \rangle$	4098
	Woder Benaviour	$\langle a,b,c,h angle \}$	
In-cluster	Log Behaviour	$\Sigma_L = \{ \langle a, d, f, h \rangle, \langle a, b, c, d, f, e, g, h \rangle, \langle a, b, c, h \rangle \}$	4854
medoid	Model Behaviour	4634	
	Wiodel Bellaviour	$\langle a,b,c,h angle \}$	

To discover the event log presented in Fig. 1, we applied the Inductive Miner algorithm [16] with infrequent thresholds of 0.9.

Assuming that we select three variants to represent the event log, i.e., the behavior subset consists of three variants. Table II shows the behaviour subsets generated by the frequency-based method, K-Medoids, and our proposed methods (see Section V for details). The frequency-based subsets show two key limitations:

1) Overestimation of alignment cost: Variant 5, $\langle a, h \rangle$, can be perfectly replayed in the model with an alignment cost of 0. But it is not included in our model behaviour subset, aligning

it would require at least 6 insertions (i.e., cost of 6), resulting in an overestimated approximate cost.

2) Lack of structural diversity: The selected model traces $\langle a,b,c,d,f,e,g,h \rangle$ and $\langle a,b,c,d,e,f,g,h \rangle$ differ only in the order of e and f. This means that they represent essentially the similar structural path, potentially overlooking other important paths in the process model.

Also, the K-Medoids method has drawbacks: it clusters traces solely based on their control-flow information, that is, syntactic difference. For example, the trace $\langle b,f,g\rangle$ in log behaviour subset (as shown in Table II) may have significantly syntactic differences from other traces but, due to its low

frequency (only 24 occurrences), it is still not enough to represent the model behaviour.

To address the issues, our approach proposed in Section V effectively balances frequency and control-flow information. Table II also shows the cost deviation. It refers to the difference in alignment cost between using model behaviour subset and optimal-alignment. The values indicate that the model behaviours generated by our methods significantly reduce the cost deviations compared to vanilla methods.

III. RELATED WORK

To cope with the complexity of alignment construction, approximation techniques have been developed to balance result quality and computational cost. Early studies explored replacing the A* algorithm with faster algorithms[7], [17], [18], laying the foundation for a more efficient alignment computation. For example, Taymouri and Carmona [17], introducing an evolutionary algorithm to enhance alignment approximations. Model decomposition has also been investigated as an efficiency-oriented approximation approach. The foundational work demonstrated how breaking models into smaller and more manageable parts can simplify alignment, although it may not always result in optimal alignments [19], [20]. Furthermore, the construction of automata capable of aligning the log and the model has been explored as another approximation technique [21], [22]. This approach provides good approximations of the optimal alignments in most cases. Recently, some researchers have proposed using RNN-based neural networks to obtain recall and precision metrics for event logs and process models, demonstrating the potential of this technique for conformance analysis [23], [24].

Reducing behaviour size is another promising strategy for approximate conformance checking. One sampling approach focuses on sampling the event log. For instance, [25] proposes a trace sampling method, assuming that a few log traces can estimate the conformance value. However, it lacks upper and lower bounds for the approximation and performs worse when the event log contains many unique behaviors.

Another recent sampling approach targets model behaviour. [5] introduced a model sampling method to construct subsets of the model behaviour that represent the entire process model, significantly reducing the approximation time while largely maintaining accuracy. The method also provides upper and lower bounds to give some certainty of the approximation.

Hierarchical clustering is widely used in process mining for its structural representativeness [26]. Furthermore, [27] demonstrates how hierarchical clustering aids in discovering a better model.

IV. PRELIMINARIES

This section presents the terminology and notation for conformance checking to support the subsequent sections. We use the basic definitions of Petri net, e.g., labeled Petri Net in [28].

Given a system net SN, $\phi_f(SN)$ is the set of all complete firing sequences of SN and $\phi_v(SN)$ is the set of all possible visible traces, i.e., complete firing sequences starting in its initial marking and ending in its final marking projected onto

the set of observable activities (not silent transitions, e.g., t_3 in Fig. 1).

To measure how a trace aligns to a process model, moves are represented by pairs (a,t), where a is a log activity, and t is a model transition. Legal moves can be: log moves , model moves, or synchronous moves . Any other combination is an illegal move.

Definition 1. (Alignment). Let $\sigma_L \in L$ represent a log trace and $\sigma_M \in \phi_f(SN)$ denote a complete firing sequence of a system net SN. A_{LM} is the set of legal moves. An alignment of σ_L and σ_M is a sequence of pairs $\gamma \in A_{LM}^*$ such that the projection on the first element (ignoring \gg) yields σ_L and the projection on the second element (ignoring \gg and transition labels) yields σ_M .

To quantify the costs of alignments we introduce a cost function δ in Definition 2.

Definition 2. (Cost of Alignment). Cost function $\delta \in A_{LM} \to \mathbb{N}$ assigns costs to legal moves. The cost of an alignment $\gamma \in A_{LM}^*$ is the sum of all costs:

$$\delta(\gamma) = \sum_{(a,t)\in\gamma} \delta(a,t).$$

The cost values assigned to log moves, model moves, and synchronous moves are 1, 1, and 0, respectively. Note that an alignment is considered optimal if it has the minimum alignment cost.

Definition 3. (Optimal Alignment). Let L be an event log and SN a system net, where $\phi_v(SN) \neq \emptyset$.

- For $\sigma_L \in L$, we define: $\Gamma_{\sigma_L,SN} \in \{ \gamma \in A_{LM}^* \mid \exists \sigma_M \in \phi_f(SN) \text{ is an alignment of } \sigma_L \text{ and } \sigma_M \}.$
- An alignment $\gamma \in \Gamma_{\sigma_L,SN}$ is optimal for trace $\sigma_L \in L$ and system net SN if for any alignment $\gamma' \in \Gamma_{\sigma_L,M}$: $\delta(\gamma') \geq \delta(\gamma)$.
- $\gamma_{SN} \in A_{LM}^* \to A_{LM}^*$ is a mapping that assigns any log trace σ_L to an optimal alignment, i.e., $\gamma_{SN}(\sigma_L) \in \Gamma_{\sigma_L,SN}$ and $\gamma_{SN}(\sigma_L)$ is an optimal alignment.

Definition 4. (Levenshtein Edit Distance). As defined by [29], the Levenshtein edit distance $d(\sigma_1, \sigma_2) \to \mathbb{N}$ represents the minimum number of edit operations (i.e., insertions, deletions, and substitutions) required to transform one sequence into another. For instance, $d(\langle a,b\rangle,\langle c,d\rangle)=2$, where the two edit operations are substitutions (a,c) and (b,d).

Definition 5. (Edit Distance Cost Function). We can calculate the distance between two traces (or sequences) faster by using a modified version of the Levenshtein edit distance [30]. Let $\sigma_1, \sigma_2 \in A^*$ be two sequences of activities. The Edit Distance Cost Function $\Delta(\sigma_1, \sigma_2) \to \mathbb{N}$ is defined as the minimum number of edits (insertion or deletion of activities) required to transform σ_1 into σ_2 .

Suppose that S is a set of sequences, $\Phi(\sigma_L, S) = \min_{\sigma_M \in S} \Delta(\sigma_L, \sigma_M)$ returns the distance of the most similar sequence in S. Let $\phi_v(SN)$ be the set of all visible firing sequences in SN, and $\gamma_{SN}(\sigma)$ be an optimal alignment for sequence σ . It is possible to prove that $\delta_S(\gamma_{SN}(\sigma)) = \Phi(\sigma, \phi_v(SN))[12]$.

In the context of alignment, the edit distance function can be used as a cost function δ_S for evaluating the misalignment between a log trace σ_L and a model trace σ_M . This cost function assigns a value corresponding to the number of operations required to align the two sequences. For example, $\Delta(\langle a,c,b,e,d\rangle,\langle a,b,c,a,d\rangle)=4$ corresponds to two deletions and two insertions.

Moreover, the alignment cost of a single trace can be converted into a fitness value between 0 (poor fitness, i.e., maximal costs) and 1 (perfect fitness, i.e., zero costs) using Eq. (1) [5]. In this regard, we normalize this cost relative to the worst case, with one log move for each activity in the trace and one model move for each transition in the model's shortest path, $SPM = \min_{\sigma_M \in \phi_f}(|\sigma_M|)$. Here, the optimal alignment cost, $\delta(\gamma_{SN}(\sigma))$, can be replaced by an alternative cost (e.g., edit distance cost) to obtain a corresponding fitness value.

$$Fitness_{\text{Trace}}(\sigma_L, SN) = 1 - \frac{\delta_S(\gamma_{SN}(\sigma))}{|\sigma_L| + SPM}$$
 (1)

Note that the overall fitness between the event log and the system net is the weighted average of single trace fitness values.

V. METHOD

In this section, we present the proposed conformance approximation method. An overview of our approach is shown in Fig. 2. The method begins with a preprocessing stage using hierarchical clustering techniques. Next, two methods are proposed for constructing model behaviour subsets: incluster frequency and in-cluster medoid methods. Finally, the alignment approximation process is explained.

A. Preprocess Event Log Using Hierarchical Clustering

In this stage, we apply agglomerative hierarchical clustering [31] on event logs. Specifically, we first partition the event log based on trace variants to get the trace variant subset Σ_{σ_v} . Then, we introduce the normalized weighted Levenshtein distance to measure the distance between these variants (see Definition 6) as a new in-cluster distance criterion. This criterion considers both frequency and control-flow information, alleviating the problem with current log selection methods mentioned in Section II. It is used to build a distance matrix, then forming a dendrogram. By cutting-off the dendrogram, we obtain the desired number of clusters. The framework is illustrated in Fig. 3.

Definition 6. (Normalized Weighted Levenshtein Distance). Let A^* be the set of all possible sequences of activities in A, and let σ_{v1}, σ_{v2} be two trace variants $\in A^*$. The normalized weighted Levenshtein distance between σ_{v1} and σ_{v2} , where each trace variant has a frequency $f(\sigma_{v1})$ and $f(\sigma_{v2})$, is defined as Eq. (2):

$$d_{weighted}(\sigma_{v1}, \sigma_{v2}) = \frac{f(\sigma_{v1}) \cdot f(\sigma_{v2}) \cdot d_N(\sigma_{v1}, \sigma_{v2})}{\max\{f(\sigma_{v1})^2, f(\sigma_{v2})^2\}}$$
(2)

where, the normalized Levenshtein distance $d_N(\sigma_{v1}, \sigma_{v2})$ is given by Eq. (3):

$$d_N(\sigma_{v1}, \sigma_{v2}) = \frac{d(\sigma_{v1}, \sigma_{v2})}{\max\{|\sigma_{v1}|, |\sigma_{v2}|\}}$$
(3)

Here, $d_N(\sigma_{v1}, \sigma_{v2}) = 0$ means the two traces are exactly the same, and $d_N(\sigma_{v1}, \sigma_{v2}) = 1$ means the two traces are completely different.

Definition 7. (*Distance Matrix*). Let $\sigma_{v1}, \sigma_{v2}, \ldots, \sigma_{vi} \in A^*$ represent all trace variants in event log L. The matrix D(L) is defined as Eq. (4):

$$D(L) = \begin{bmatrix} 0 & d(\sigma_{v1}, \sigma_{v2}) & \cdots & d(\sigma_{v1}, \sigma_{vi}) \\ d(\sigma_{v2}, \sigma_{v1}) & 0 & \cdots & d(\sigma_{v2}, \sigma_{vi}) \\ \vdots & \vdots & \ddots & \vdots \\ d(\sigma_{vi}, \sigma_{v1}) & d(\sigma_{vi}, \sigma_{v2}) & \cdots & 0 \end{bmatrix}$$
(4)

where, d is the normalized weighted Levenshtein distance function.

B. Constructing Model Behaviour

In this stage, we first propose two in-cluster methods to get log behaviour subset Σ_L from the generated clusters and transform it into the model behaviour subset Σ_M . Specifically,

1) Candidate selection: After preprocessing, we obtain several clusters, each representing different behaviours within the model. The following question is how to choose the most representative traces from each cluster to construct a more effective log behaviour subset. Existing approaches in approximate conformance checking often rely on either random sampling or frequency-based selection without considering control-flow similarity, which may lead to biased or suboptimal subsets when the frequency distribution is highly imbalanced or when rare but structurally central behaviours exist. To address this, we extend the ideas of frequency-based and medoid selection by introducing two in-cluster methods — the incluster frequency method and the in-cluster medoid method — designed to balance efficiency and representativeness.

The in-cluster frequency method selects, from each cluster, the trace variant with the highest frequency of occurrence. This approach assumes that the most common behaviour within a cluster is also the most representative of that cluster's behaviour. Its main advantage lies in computational efficiency, as it does not require computing pairwise distances between traces. Compared to methods that sample traces uniformly at random [25], the frequency method reduces the risk of including low-relevance traces, especially in large-scale logs.

The in-cluster medoid method, in contrast, selects the trace variant that minimises the total Levenshtein distance to all other traces in the cluster, effectively identifying the "central" trace in terms of control-flow similarity. Specifically, it computes the pairwise Levenshtein distances between all traces in each cluster, then constructs a distance matrix and obtains the medoid trace (see Definition 8). This ensures that the selected trace best represents the structural characteristics of its cluster, even if it is not the most frequent. Compared to traditional frequency-only methods, the medoid approach mitigates the bias towards dominant behaviours and is more robust when clusters contain diverse but equally important behaviours.

2) Optimal-alignment: In this step, we align Σ_L with process model to construct the Σ_M , that is, we compute the optimal alignments of selected traces in the event log and finding the corresponding model traces for these alignments.

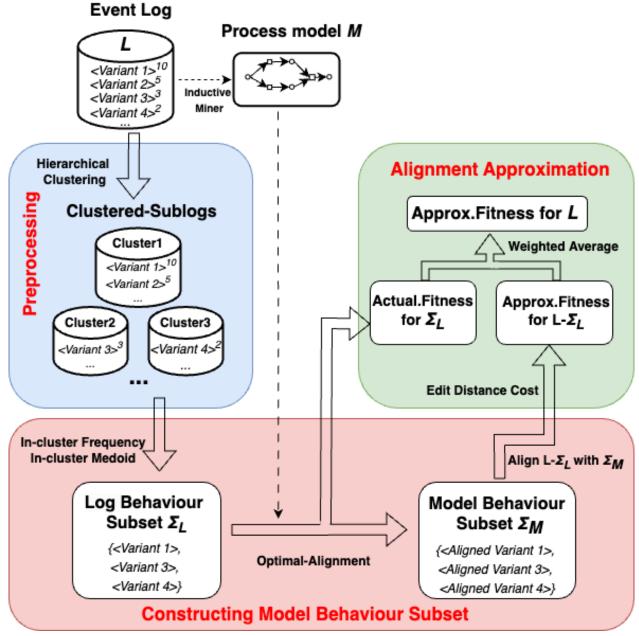


Fig. 2. Overview of our approach.

Table III shows three clusters generated from the event log in Table I. For example, applying the in-cluster frequency method to cluster 2 yields $\langle a,b,c,h\rangle^{792}$, the most frequent trace. Repeating this for each cluster, we obtain $\Sigma_L = \{\langle a,b,c,d,f,e,g,h\rangle^{1280},\langle a,b,c,h\rangle^{792},\langle a,h\rangle^{320}\}$. We then align Σ_L with the process model, as shown in Fig. 1, resulting in Σ_M . Note that Σ_L and Σ_M are same in this example, as all traces can be fully replayed in the model.

The specific algorithm steps for proposed methods are outlined in Algorithm 1 and Algorithm 2.

Definition 8. (In-cluster Medoid). Let L' be a clustered sublog, n denote the number of trace variants in L', and D(L') be the distance matrix of L'. The trace σ_i

 $\arg\min_{\sigma_j \in L'} \sum_{i \in [1,n]} d(\sigma_i, \sigma_j)$ represents the medoid trace of sublog L'.

C. Computing Alignment Approximation

After constructing M_B , we use it to approximate alignments for the traces in $L-L_C$, where L_C refers to the frequency-based trace variants used to build Σ_L . The actual alignment fitness for the variants in Σ_L has already been computed during the construction of M_B , so we can directly use this value for more accurate approximations. At this stage, we calculate the alignment approximations for the remaining variants.

Typically, the actual fitness is calculated using standard alignment costs. However, for the remaining variants, we use

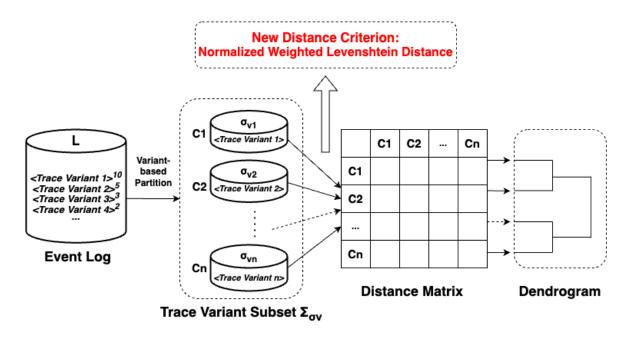


Fig. 3. Preprocessing workflow for hierarchical clustering.

TABLE III. THE CLUSTERS GENERATED FROM THE EXAMPLE LOG PROVIDED IN TABLE I

Cluster ID	Traces in each cluster
1	$\{\langle a, b, c, d, f, e, g, h \rangle^{1280}, \langle a, b, c, d, e, f, g, h \rangle^{912}, \langle a, b, c, d, e, f, g, h \rangle^{864}\}$
2	$\{\langle a,b,c,h\rangle^{792},\langle a,b,c,d,h\rangle^{400},\langle a,f,b,c\rangle^{96}\}$
3	$ \{ \langle a, h \rangle^{320}, \langle a, d, h \rangle^{250}, \langle a, c, e, f, g \rangle^{64}, \\ \langle a, d, e, g, h \rangle^{56}, \langle a, b, f, e, g, h \rangle^{48}, \langle b, f, g \rangle^{24} \} $

Algorithm 1 In-cluster Medoid Method

Input: Event $\log L$; Process model M.

Output: Model behaviour subset Σ_M .

- 1: Initialize log behaviour subset: $\Sigma_L \leftarrow \emptyset$
- 2: Initialize model behaviour subset: $\Sigma_M \leftarrow \emptyset$
- 3: Partition L based on variants into Σ_{σ_v}
- 4: Cluster Σ_{σ_v} into k clusters $\{\Sigma_{\sigma_{v1}}, \Sigma_{\sigma_{v2}}, \dots, \Sigma_{\sigma_{vk}}\}$ using hierarchical clustering
- 5: **for** i = 1 to k **do**
- Compute pairwise Levenshtein distances between all 6: variants in $\Sigma_{\sigma_{vi}}$
- 7: Construct distance matrix $D(\Sigma_{\sigma_{ni}})$
- Find the medoid trace $\sigma_L^{(i)}$ in $\Sigma_{\sigma_{ni}}$: 8:

$$\sigma_L^{(i)} = \arg\min_{\sigma \in \Sigma_{\sigma_{vi}}} \sum_{\sigma' \in \Sigma_{\sigma}} d(\sigma, \sigma')$$

- Update log behaviour subset: $\Sigma_L \leftarrow \Sigma_L \cup \{\sigma_L^{(i)}\}\$
- 10: **end for**
- 11: **for** each $\sigma_L^{(i)} \in \Sigma_L$ **do**
- Compute optimal alignment γ_{SN}^{opt} between $\sigma_L^{(i)}$ and M Map to model trace: $\sigma_M^{(i)} \leftarrow \lambda_{SN}(\sigma_L^{(i)})$ 12:
- 13:
- Update model behaviour subset: $\Sigma_M \leftarrow \Sigma_M \cup \{\sigma_M^{(i)}\}\$ 14:
- 15: end for
- 16: return Σ_M

Algorithm 2 In-cluster Frequency Method

Input: Event $\log L$; Process model M.

Output: Model behaviour subset Σ_M .

- 1: Initialize log behaviour subset: $\Sigma_L \leftarrow \emptyset$
- 2: Initialize model behaviour subset: $\Sigma_M \leftarrow \emptyset$
- 3: Partition L based on variants into Σ_{σ_n}
- 4: Cluster Σ_{σ_v} into k clusters $\{\Sigma_{\sigma_{v1}}, \Sigma_{\sigma_{v2}}, \dots, \Sigma_{\sigma_{vk}}\}$ using hierarchical clustering
- 5: **for** i = 1 to k **do**
- Let $\Sigma_{\sigma_{vi}}$ denote the *i*-th cluster of variants 6:
- Find the most frequent variant $\sigma_L^{(i)}$ in $\Sigma_{\sigma_{vi}}$:

$$\sigma_L^{(i)} = \arg\max_{\sigma \in \Sigma_{\sigma_{ni}}} f(\sigma)$$

- Update log behaviour subset: $\Sigma_L \leftarrow \Sigma_L \cup \{\sigma_r^{(i)}\}\$
- 9: end for
- 10: **for** each $\sigma_L^{(i)} \in \Sigma_L$ **do**
- Compute optimal alignment $\gamma_{SN}^{\rm opt}$ between $\sigma_L^{(i)}$ and M11:
- 12:
- Map to model trace: $\sigma_M^{(i)} \leftarrow \lambda_{SN}(\sigma_L^{(i)})$ Update model behaviour subset: $\Sigma_M \leftarrow \Sigma_M \cup \{\sigma_M^{(i)}\}$
- 14: end for
- 15: **return** Σ_M

the edit distance cost function Δ (see Definition 5) to estimate fitness. This method provides guaranteed upper and lower bounds for the alignment cost, instead of exact values [5] (see Lemma 1 and Lemma 2 below) [see Eq. (5)].

$$Fitness(L,SN) = \frac{\sum_{\sigma \in L_C} f(\sigma) \times Fitness_{\text{Approximate}}(\sigma,SN)}{\sum_{\sigma \in L} f(\sigma)} + \frac{\sum_{\sigma \in L-L_C} f(\sigma) \times Fitness_{\text{Actual}}(\sigma,SN)}{\sum_{\sigma \in L} f(\sigma)}$$
(5)

Lemma 1 (Alignment Cost Upper Bound). Let $\sigma_L \in \mathcal{U}_A^*$ be a log trace and $\sigma_M \in \phi_v(SN)$ be a visible firing sequence of SN. We have $\delta_S(\gamma_{SN}(\sigma_L)) \leq \Delta(\sigma_L, \sigma_M)$, where $\gamma_{SN}(\sigma_L)$ is the optimal alignment.

Proof: The proof is provided in Appendix A and demonstrates how the edit distance guarantees this upper bound.

Simply put, if we align trace variant $4 \langle a, b, c, d, h \rangle$ from Table I with σ_L from the in-cluster frequency subset in Table II, the alignment cost is 1 (i.e., removing "d"). However, since σ_M is a subset of the full model, the actual cost could be smaller or equal. Thus, we use 1 as the upper bound for this variant.

Lemma 2 (Alignment Cost Lower Bound). Let SPM = $\min_{\sigma_M \in \phi_v(SN)} |\sigma_M|$ and $LPM = \max_{\sigma_M \in \phi_v(SN)} |\sigma_M|$, representing the shortest and longest paths in the process model $M. \sigma_L \lceil_{A_v(SN)}$ and $\kappa(\sigma_L)$ are as defined in Definition 9.

For any log trace σ_L , if $|\sigma_L\lceil_{A_v(SN)}| < SPM$, the alignment cost lower bound is $SPM - |\sigma_L\lceil_{A_v(SN)}| + \kappa(\sigma_L)$; if $|\sigma_L\lceil_{A_v(SN)}| > LPM$, the lower bound is $|\sigma_L\lceil_{A_v(SN)}| - LPM$. $LPM + \kappa(\sigma_L)$; if $SPM \leq |\sigma_L|_{A_v(SN)}| \leq LPM$, the lower bound is $\kappa(\sigma_L)$.

Proof: The proof is provided in Appendix B.

The cost lower bound is the minimum edit operations needed to transform σ_L into σ_M . We refine this algorithm using activity projection (see Definition 9) to improve approximation accuracy. Existing methods compare log trace length directly with the model's range, potentially yielding errors if irrelevant activities are present. For instance, in Fig. 1, a trace $\langle a, x \rangle$ might seem aligned if its length falls within the model's shortest (SPM=2) and longest paths (LPM=8), even though x is not in the model, resulting in a miscalculated cost of 0. Our algorithm removes non-model activities (e.g., removing x from $\langle a, x \rangle$ to form $\langle a \rangle$) before comparing trace lengths. This adjustment yields a more accurate cost of 1 rather than 0, resulting in a smaller upper fitness and tighter bound width.

These bounds are then used to compute the corresponding upper and lower fitness bounds (with the cost upper bound giving the fitness lower bound, and vice versa) using Eq. (1). The computations for the fitness bounds are provided in Algorithm 3 and Algorithm 4. The average of these bounds provides the approximate fitness. Once we compute the approximate fitness for each remaining variant, we take the weighted average of these values along with the previously computed actual fitness to get the overall approximate fitness for the entire event log, as shown in Eq. (5).

Definition 9 (Activity Projection). Let $A_v(SN)$ be the set of unique observable activities in the system net SN. For any

log trace σ_L , let $\sigma_L \lceil_{A_v(SN)}$ represent the projection of σ_L onto $A_v(SN)$, which means the set of activities in σ_L that also appear in the model. Define $\kappa(\sigma_L) = |\sigma_L| - |\sigma_L|_{A_n(SN)}$ as the number of activities in σ_L that are not present in the model.

For example, let $\sigma_L = \langle a, b, x \rangle$ be a log trace and the observable activities of the system net be $A_v(SN) = \{a, b, c, d, e\}$. Projecting σ_L onto $A_v(SN)$ results in $\sigma_L \lceil_{A_v(SN)} = \langle a, b \rangle$, as x is not part of $A_v(SN)$. Therefore, $\kappa(\sigma_L) = |\sigma_L| |\sigma_L[A_n(SN)]| = 3 - 2 = 1$, indicating one activity in σ_L is not present in the model.

Algorithm 3 Fitness lower bound computation

2:

3:

5: return $L_fitness(\sigma_L, M)$

```
Input: Event log L; Optimal-aligned Log L_C; Model
     behaviour subset \Sigma_M.
     Output: Lower bound fitness L_fitness(\sigma_L, M).
    for each \sigma_L \in L - L_C do
            \begin{array}{l} \Phi(\sigma_L, \Sigma_M) \text{ // } Compute \ minimun \ edit \ distance \ cost } \\ L\_fitness(\sigma_L, M) \leftarrow 1 - \frac{\Phi(\sigma_L, \Sigma_M)}{|\sigma_L| + \min_{\sigma_M} \in \phi_v(SN)^{(|\sigma_M|)}} \end{array}
4: end for
```

Algorithm 4 Fitness upper bound computation

```
Input: Event log L; Optimal-aligned Log L_C; Model
behaviour subset \Sigma_M.
Output: Upper bound fitness U\_fitness(\sigma_L, M).
```

```
1: SPM \leftarrow \min_{\sigma_M \in \phi_v(SN)} |\sigma_M| // Shortest path
  2: LPM \leftarrow \max_{\sigma_M \in \phi_v(SN)} |\sigma_M| // Longest path 3: for each \sigma_L \in L - L_C do
                       Project \sigma_L onto SN: \sigma_L \lceil_{A_v(SN)}
  4:
                     Project \sigma_L onto SLL, \sigma_{L|A_v(SL)} Compute \kappa(\sigma_L) = |\sigma_L| - |\sigma_L|_{A_v(SN)}| if |\sigma_L|_{A_v(SN)}| < SPM then U\_fitness(\sigma_L, M) \leftarrow 1 - \frac{SPM - |\sigma_L|_{A_v(SN)}| + \kappa(\sigma_L)}{|\sigma_L| + \min_{\sigma_M \in \phi_v(SN)}(|\sigma_M|)}
  5:
  6:
  7:
                      else if |\sigma_L|_{A_v(SN)}| > LPM then U\_fitness(\sigma_L, M) \leftarrow 1 - \frac{|\sigma_L|_{A_v(SN)}| - LPM + \kappa(\sigma_L)}{|\sigma_L| + \min_{\sigma_M} \in \phi_v(SN)} else \kappa(\sigma_L, M) \leftarrow 1 - \frac{|\sigma_L|_{A_v(SN)}| - LPM + \kappa(\sigma_L)}{|\sigma_L| + \min_{\sigma_M} \in \phi_v(SN)} 
  8:
  9:
10:
                            U\_fitness(\sigma_L, M) \leftarrow 1 - \frac{\kappa(\sigma_L)}{|\sigma_L| + \min_{M} \in \phi_v(SN)(|\sigma_M|)}
11:
12:
13: end for
14: return U_fitness(\sigma_L, M)
```

VI. EVALUATION

In this section, we assess the accuracy and time performance of our proposed log selection methods compared to frequencybased and K-Medoids techniques, and evaluate their differences in accuracy and time against normal alignment. Note that the comparison between model behaviour sampling and other approximate methods has been discussed in [5], we focus here on comparisons with the baselines of model behaviour sampling. First, we briefly describe the implementation (Section VI-A) and experimental setup (Section VI-B), followed by a discussion of the experimental results (Section VII).

A. Implementation

Our implementation consists of two steps: first, we implemented the algorithms described in Sections V-A and V-B in Python, to generate log behaviour subsets from event logs.

Event Log	Activities #	Traces #	Variants #	Uniqueness
BPIC2012 [36]	25	13087	4366	0.33
BPIC2013-closed problems [37]	4	1487	183	0.12
BPIC2016-Questions [38]	8	21533	2261	0.10
BPIC2017 [39]	28	31509	15930	0.51
Spesis [40]	18	1050	846	0.81
RTFMP [41]	13	150370	231	0.01

TABLE IV. THE REAL-LIFE EVENT LOGS USED IN THE EXPERIMENTS

Specifically, we extended the pm4py.algo.clustering package in PM4py [32] by introducing the normalized weighted Levenshtein distance (Definition 6), to perform hierarchical clustering. And implemented two proposed in-cluster methods to get the log behaviour subset based on the clustering result. In the second step, we used an existing plugin in ProM [33], *Conformance Log to Log Approximation* [34], with the generated model behaviour subset and the original event log as input, obtaining approximate fitness bounds and values. For the baselines, we used the implementation proposed by Fanisani [5]. For normal alignment, we used PM4py to compute the time and fitness values. The source code and experimental results is available on Github ¹.

B. Experimental Setup

Our experiments were based on six real event logs, with basic information about these event logs given in Table IV. Here, Uniqueness refers to Variant#. A Uniqueness value close to 1 indicates that almost all traces are different, e.g., Sepsis. For process discovery, we used Inductive Miner infrequent algorithm [35] with infrequent thresholds of 0.4 to get the process model. Two log selection methods, frequency-based sampling, K-Medoids clustering, were used as baselines to compare with our proposed methods, i.e., *In-cluster frequency* method and In-cluster medoid method. Furthermore, we set the selection percentage to 10%, 20%, 30%, 40%, and 50%, representing the ratio of the selected variants to the total number of variants in the event logs. Our experiment was repeated four times since the conformance approximation time is non-deterministic. Finally, we performed the experiments on a computer with Apple M1 (8 cores), 8 GB RAM running macOS.

1) Evaluation metrics: To measure approximation accuracy, we used Approximate Error, defined as ApproximateError = |ActualFitness - ApproximateFitness|, where a value closer to 0 indicates higher accuracy. Additionally, we assess the Bound Width as $BoundWidth = U_fitness - L_fitness$, with a smaller width indicating tighter bounds and a more accurate approximation.

We used the $Performance\ Improvement\ (PI)$ metric, defined as $PI = \frac{Actual\ Conformance\ Time}{Approximate\ Conformance\ Time}$ to assess time performance. $Actual\ Conformance\ Time$ refers to the time needed to compute normal alignment, while $Approximate\ Conformance\ Time$ includes the total time for the approximation. A PI value greater than 1 indicates the approximation is faster than the actual

conformance computation. Preprocessing time (e.g., hierarchical clustering) is included in the approximate conformance time.

VII. RESULT

Table V presents the *Actual Fitness* and *Approximate Fitness*, *Approximate Error*, and *PI* for four selection methods using 20% of the variants in six event logs. For each metric in a given row, the best value is highlighted in bold. The results show that the proposed in-cluster methods achieve the highest *fitness* and the lowest *approximate error* in most cases, indicating superior accuracy compared to the baselines. In terms of *PI*, the frequency-based method consistently achieves the highest values, reflecting its shorter approximate time. Our complete experimental data is provided in Appendix B.

Fig. 4 shows that both Approximate Error and Bound Width decrease as the selection percentages increase. Here, Bound Width is represented by bars, and Approximate Error by lines, illustrating the improvements in these metrics as the selection percentage increases. Our in-cluster methods consistently achieve tighter bounds at each selection percentage. Notably, at a selection 50% in the BPIC2017 log, the bound widths of the baseline are around 0.05, while our methods reduce this by 40% to 0.03. Furthermore, in all data sets with different selection percentages, the in-cluster frequency method shows an average improvement of 19.1% in Approximate Error compared to the frequency-based method, while the in-cluster medoid method achieves an average improvement of 27.6% compared to the K-Medoid method. Moreover, the in-cluster frequency method often produces tighter bounds than in-cluster medoid method, especially on low uniqueness logs like BPIC2016-Questions, where selecting the most frequent trace is more effective than clustering. However, on high Uniqueness logs like Sepsis, in-cluster medoid method provides more accurate approximations. In Fig. 5, we compare the time performance of different log selection methods and their improvement over normal alignment. Note that a value of 1 represents the normal alignment time. Consistent with the results in Table V, the frequency method usually yields the highest performance improvement, followed by the K-Medoids method. Our methods are less efficient compared to these baselines, particularly on datasets with higher Uniqueness values. Table VI presents the experimental results for datasets.

VIII. DISCUSSION

Across Table V and Fig. 4, our in-cluster methods consistently achieve higher *fitness*, lower *approximate error*, and tighter bounds than the baselines, with the in-cluster frequency method performing better on low-*Uniqueness* logs

¹https://github.com/lvyl9909/Approximate-Conformance-Checking-using-Hierarchical-Clustering.git

Frequency K-Medoids In-cluster freq. In-cluster medoid **Event Log** Actual Fit. PΙ Fit. ΡĪ Fit. ΡĪ Fit. PΙ Err. Err. Err. Err. BPIC2012 0 9995 0.9741 0.0254 61.8496 0.9761 0.0234 41.1727 0.9788 0.0207 25.6113 0.9806 0.0189 24 8483 0.9860 0.0138 11.8502 0.9711 0.0286 0.9894 0.0103 0.9875 0.0122 1.6443 BPIC2013-closed problems 0.9997 5.8732 1.6728 0.0074 BPIC2016-Questions 0 9997 0.9923 45.3310 0.9463 0.0535 30.4731 0.9944 0.0053 13.1973 0.9565 0.0432 12.2026 BPIC2017 0.9995 0.9690 0.0305 11.8531 0.9700 0.0296 0.9749 0.0246 1.9688 0.9747 0.0248 1.8838 9.7231 15.7220 Road 0.9999 0.9997 0.0002 0.9996 0.0004 11.7262 0.9998 0.0001 7.5686 0.9995 6.7700 Sepsis 0.9880 0.9202 0.0679 53.4338 0.9202 0.0678 44.9919 0.9313 0.0567 22.9238 0.9319 0.0561 20.0751

TABLE V. APPROXIMATE RESULT COMPARISONS (20% SELECTION) FOR FOUR DIFFERENT SELECTION METHODS

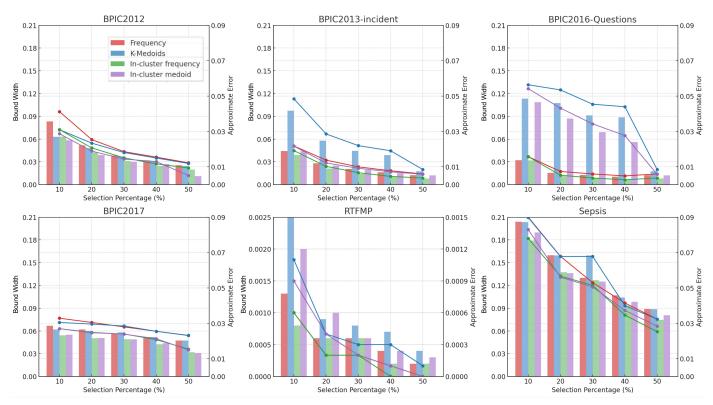


Fig. 4. The performance differences of different selection strategies on band width and approximate error.

(e.g., BPIC2016-Questions) and the in-cluster medoid method excelling on high-Uniqueness logs such as Sepsis, highlighting a key advantage of our approach over the baselines—improved approximation accuracy. Fig. 5 shows that our methods have larger approximation times. This is because hierarchical clustering requires step-by-step merging and evaluating all possible cluster combinations, which increases preprocessing time compared to baselines. Nevertheless, they remain significantly faster than the normal alignment-based approach, keeping approximation times within acceptable limits while delivering higher accuracy—making them well-suited for large-scale processes where neither a quick, coarse estimate nor weeks of exact computation is desirable. Overall, our results indicate a clear trade-off: the proposed methods bring the approximations closer to the actual values at the cost of some additional but acceptable preprocessing time.

IX. CONCLUSION

In this study, we propose an enhanced model behaviour sampling method using hierarchical clustering to construct more representative model behaviour subsets. By incorporating both frequency and control-flow information from the event log, our approach more effectively captures the model's behaviour, leading to improved approximation accuracy. Experimental results show that our method produces approximations that are on average over 19.1% closer to the actual alignment values than baseline methods, though it requires more computation time.

A potential limitation of this study is the lack of an explicit quantification of how much "increased" time would be acceptable for the "improvement" in accuracy, which is important to evaluate the practical utility of the method under different application scenarios. As a next step, we plan to conduct a systematic, quantitative analysis of the accuracy—time trade-off. Based on it, an incremental approximation tool

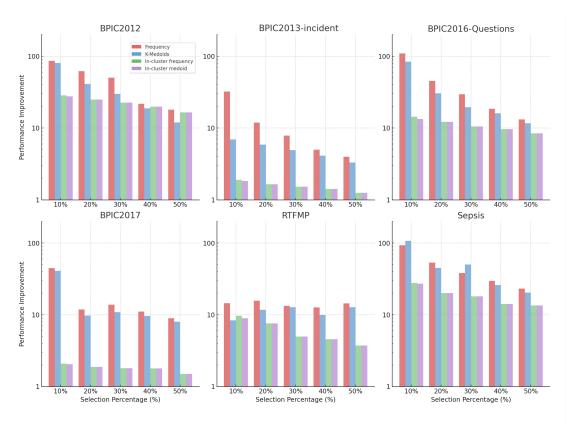


Fig. 5. The performance improvement using different methods in six event logs.

could be developed to increase the size of model behaviour during the time, allowing the user to decide when the accuracy is enough. In addition, we plan to apply a time-optimized hierarchical clustering algorithm to reduce the approximation time of our method. Furthermore, exploring how to make use of the distribution information (e.g., *Uniqueness*) in the event log to choose a better approximate method is also a direction for future research.

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DECLARATION OF COMPETING INTEREST

The author declares that there are no known financial interests or personal relationships that could have influenced the research presented in this study.

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APPENDIX

A. Proof of Alignment Cost Upper Bound

Proof: We have shown that $\min_{\sigma_M \in S} \Delta(\sigma_L, \sigma_M) = \delta_S(\gamma_{SN}(\sigma_L))$ in Definition 5, so $\Delta(\sigma_L, \sigma_M) \geq \delta_S(\gamma_{SN}(\sigma_L))$. Therefore, if $\delta_S(\gamma_{SN}(\sigma_L)) > \Delta(\sigma_L, \sigma_M)$, $\gamma_{SN}(\sigma_L)$ is not an optimal alignment. Consequently, for any $M_B \subseteq \phi_v(SN)$, $\Phi(\sigma_L, M_B)$ returns an upper bound for the cost of optimal alignment [5].

B. Proof of Alignment Cost Lower Bound

Proof: When $|\sigma_L\lceil_{A_v(SN)}| < SPM$, at least $SPM - |\sigma_L\lceil_{A_v(SN)}|$ insertions are needed. Adding the initial alignment cost, the total minimum alignment cost is $|SPM - \sigma_L\lceil_{A_v(SN)}| + |\kappa(\sigma_L)|$. Similarly, when $|\sigma_L\lceil_{A_v(SN)}| > LPM$, at least $|\sigma_L\lceil_{A_v(SN)}| - LPM$ deletions are required. Thus, the total alignment cost is $|\sigma_L\lceil_{A_v(SN)} - LPM| + |\kappa(\sigma_L)|$. When $SPM \leq |\sigma_L\lceil_{A_v(SN)}| \leq LPM$, no insertions or deletions are needed, so the alignment cost is $|\kappa(\sigma_L)|$.

TABLE VI. EXPERIMENTAL RESULTS FOR DATASETS.

		Normal	G I'l.			Approximation Method Baseline In-cluster medoid			
Log	Actual Fitness	Alignment Time	Candidate Percentage	Para	meter	Frequency	K-Medoids	In-cluster	In-cluster
		Time			Lower			frequency	medoid
				Approximate	Bound Approximate	0.9167	0.9371	0.9368	0.9416
			10%	fitness	fitness	0.9583	0.9685	0.9684	0.9708
					Upper Bound	1.0000	1.0000	1.0000	1.0000
					imation ror	0.0412	0.0310	0.0311	0.0287
				Ba	and idth	0.0833	0.0629	0.0632	0.0584
				Prepro	cessing	/	/	1219923	1259201
					ximate	411778	439928	25030	26102
					roximate				
					(ms)	411778 85.9687	439928	1244953	1285303
				1	Lower	0.9482	80.4677 0.9522	28.4348 0.9576	27.5421 0.9612
				Approximate	Bound Approximate				
				fitness	fitness Upper	0.9741	0.9761	0.9788	0.9806
					Bound	1.0000	1.0000	1.0000	1.0000
				Er	imation ror	0.0254	0.0234	0.0207	0.0189
			20%		ind idth	0.0518	0.0478	0.0424	0.0388
				Prepro	cessing (ms)	/	/	1342972	1392321
				Appro	ximate	572356	859792	39232	32323
					proximate	572356	859792	1382204	1424644
				Time	e (ms)	61.8496	41.1727	25.6113	24.8483
					Lower	0.9618	0.9629	0.9688	0.9702
			30%	Approximate	Bound Approximate	0.9809	0.9814	0.9844	0.9851
				fitness	fitness Upper				
				Approx	Bound imation	1.0000	1.0000	1.0000	1.0000
				Er	ror	0.0186	0.0181	0.0151	0.0144
				Wi	Band Width		0.0371	0.0312	0.0298
BPIC2012	0.9995	35400000		Preprocessing Time (ms)		/	/	1423219	1529312
BPIC2012	0.9995	35400000		Approximate Time (ms)		702244	1186892	41992	42223
				Total Ap	proximate	702244	1186892	1465211	1571535
				Time (ms) PI		50.4098	29.8258	24.1603	22.5257
					Lower Bound	0.9681	0.9690	0.9756	0.9730
				Approximate fitness	Approximate fitness	0.9841	0.9845	0.9878	0.9865
					Upper	1.0000	1.0000	1.0000	1.0000
					Bound imation	0.0155	0.0150	0.0117	0.0130
					ror ind				
			40%		dth	0.0319	0.0310	0.0244	0.0270
				Time	(ms) eximate	/	/	1591211	1730030
				Time	: (ms)	1229401	1480757	41503	49020
				Total Ap	proximate (ms)	1229401	1480757	1632714	1779050
				I	PI Lower	28.7945	23.9067	21.6817	19.8983
				Approximate	Bound	0.9745	0.9752	0.9802	0.9888
				fitness	Approximate	0.9873	0.9876	0.9901	0.9944
					Upper Bound	1.0000	1.0000	1.0000	1.0000
					imation ror	0.0123	0.0119	0.0094	0.0051
			50%	Ba	and idth	0.0255	0.0248	0.0198	0.0112
			30%	Prepro	cessing	/	/	1823900	2102097
			-	Appro	ximate				
				Time	(ms) proximate	1863573	1971131	42826	43503
				Time	(ms)	1863573 18.9958	1971131 17.9592	1866726	2145600 16.4989
		1			PI	18.9958	17.9592	18.9637	10.4989

TABLE VI. EXPERIMENTAL RESULTS FOR DATASETS.

Table VI continued.

	1			1			Approxima	Table tion Method	VI continued.
Log	Actual	Normal Alignment	Candidate	Para	meter	Bas	eline	In-cluste	r medoid
	Fitness	Time	Percentage			Frequency	K-Medoids	In-cluster frequency	In-cluster medoid
					Lower Bound	0.9559	0.9025	0.9610	0.9560
				Approximate fitness	Approximate fitness	0.9780	0.9513	0.9805	0.9780
				nuicss	Upper	1.0000	1.0000	1.0000	1.0000
			10%		Bound imation	0.0218	0.0485	0.0192	0.0217
				Ba	ror and	0.0441	0.0975	0.0390	0.0440
					cessing				
					(ms) ximate	/	/	69233	70923
				Time	(ms) proximate	4200	19572	2033	2992
				Time	(ms)	4200	19572	71266	73915
				1	Lower	32.2381	6.9180	1.8999	1.8318
				Approximate	Bound Approximate	0.9719	0.9422	0.9788	0.9750
				fitness	fitness	0.9860	0.9711	0.9894	0.9875
					Bound	1.0000	1.0000	1.0000	1.0000
				Er	imation ror	0.0138	0.0286	0.0103	0.0122
			20%	Wi	and idth	0.0281	0.0578	0.0212	0.0250
					cessing (ms)	/	/	78012	79232
					Approximate Time (ms)		23054	2932	3111
				Total Approximate Time (ms)		11426	23054	80944	82343
					PI	11.8502	5.8732	1.6728	1.6443
			30%		Lower Bound	0.9795	0.9554	0.9860	0.9810
				Approximate fitness	Approximate fitness	0.9898	0.9777	0.9930	0.9905
					Upper Bound	1.0000	1.0000	1.0000	1.0000
					imation ror	0.0100	0.0220	0.0067	0.0092
				Ba	Band Width		0.0446	0.0140	0.0190
				Preprocessing Time (ms)		/	/	81203	85003
BPIC2013-incident	0.9997	135400		Approximate Time (ms)		17294	27553	3504	4092
				Total Approximate		17294	27553	84707	89095
				Time (ms) PI		7.8293	4.9142	1.5985	1.5197
					Lower	0.9839	0.9612	0.9902	0.9850
				Approximate	Bound Approximate	0.9920	0.9806	0.9951	0.9925
				fitness	fitness Upper	1.0000	1.0000	1.0000	1.0000
					Bound imation				
				Er	ror and	0.0078	0.0191	0.0046	0.0072
			40%	Wi	idth	0.0161	0.0388	0.0098	0.0150
				Time	(ms) eximate	/	/	89129	91892
				Time	(ms)	27133	32868	3932	3902
				Time	proximate (ms)	27133	32868	93061	95794
				I	PI Lower	4.9902 0.9875	4.1195 0.9825	1.4550 0.9920	1.4134 0.9879
				Approximate	Bound Approximate				
				fitness	fitness	0.9938	0.9913	0.9960	0.9940
				Approx	Bound	1.0000	1.0000	1.0000	1.0000
				Er	ror and	0.0060	0.0085	0.0037	0.0058
			50%	Wi	idth	0.0125	0.0175	0.0080	0.0121
				Time	cessing (ms)	/	/	95002	104023
				Time	ximate (ms)	34006	41028	4002	4350
					proximate (ms)	34006	41028	99004	108373
					ग	3.9817	3.3002	1.3676	1.2494

TABLE VI. EXPERIMENTAL RESULTS FOR DATASETS.

Table VI continued.

	1			1			Approxima	Table tion Method	VI continued.
Log	Actual	Normal Alignment	Candidate	Para	meter	Bas	eline	In-cluste	r medoid
	Fitness	Time	Percentage			Frequency	K-Medoids	In-cluster frequency	In-cluster medoid
					Lower Bound	0.9679	0.8867	0.9680	0.8911
				Approximate fitness	Approximate fitness	0.9840	0.9434	0.9840	0.9455
					Upper Bound	1.0000	1.0000	0.9999	0.9999
					imation ror	0.0158	0.0564	0.0158	0.0542
			10%	Ba	ınd	0.0321	0.1133	0.0319	0.1088
				Prepro	dth	/	/	359923	389454
				Appro	e(ms) ximate	47607	61807	2715	1551
					e(ms) proximate	47607	61807	362638	391005
					e(ms) PI	109.2421	84.1440	14.3413	13.3008
					Lower Bound	0.9845	0.8925	0.9888	0.9130
				Approximate fitness	Approximate	0.9923	0.9463	0.9944	0.9565
				nuiess	fitness Upper	1.0000	1.0000	1.0000	1.0000
					Bound imation	0.0074	0.0535	0.0053	0.0432
					ror ind				
			20%		dth	0.0155	0.1075	0.0112	0.0870
				Time	e(ms)	/	/	390239	421292
				Approximate Time(ms) Total Approximate		114727	170665	3832	4902
				Time	e(ms)	114727	170665	394071	426194 12.2026
					Lower	45.3310 0.9874	30.4731 0.9087	13.1973 0.9920	0.9309
			30%	Approximate	Bound Approximate	0.9937	0.9544	0.9960	0.9655
				fitness	fitness Upper	1.0000	1.0000	1.0000	1.0000
				Approx	Bound imation				
				Er	ror and	0.0060	0.0454	0.0037	0.0343
				Width Preprocessing		0.0126	0.0913	0.0080	0.0691
BPIC2016-Questions	0.9997	5200690		Time(ms) Approximate		/	/	448922	489322
				Time(ms) Total Approximate		176359	266266	6020	6334
				Time(ms) PI		176359	266266	454942	495656
				1	Lower	29.4892 0.9896	19.5319 0.9114	11.4315 0.9940	10.4925 0.9440
				Approximate	Bound Approximate	0.9948	0.9557	0.9970	0.9720
				fitness	fitness Upper				
				Approx	Bound imation	1.0000	1.0000	1.0000	1.0000
				Er	ror	0.0049	0.0440	0.0027	0.0277
			40%	Wi	idth cessing	0.0104	0.0886	0.0060	0.0560
				Time	e(ms) eximate	/	/	483200	530239
				Time	e(ms)	280456	325313	9910	10355
				Time	proximate e(ms)	280456	325313	493110	540594
				I	Lower	18.5437 0.9913	15.9867 0.9294	0.9960	9.6203 0.9503
				Approximate	Bound Approximate	0.9913	0.9294	0.9980	0.9752
				fitness	fitness Upper				
				Approx	Bound imation	1.0000	1.0000	1.0000	1.0000
				Er	ror	0.0060	0.0085	0.0037	0.0058
			50%	Wi	idth cessing	0.0125	0.0175	0.0080	0.0121
				Time	e(ms)	/	/	566660	602030
				Time	ximate e(ms)	395799	445163	15330	14340
				Time	proximate e(ms)	395799	445163	581990	616370
				I	PI	13.1397	11.6827	8.9360	8.4376

TABLE VI. EXPERIMENTAL RESULTS FOR DATASETS.

	1						Approxima	Table tion Method	VI continued.
Log	Actual	Normal Alignment	Candidate	Para	meter	Bas	eline	In-cluste	r medoid
Log	Fitness	Time	Percentage	raia	meter	Frequency	K-Medoids	In-cluster frequency	In-cluster medoid
					Lower Bound	0.9332	0.9381	0.9454	0.9450
				Approximate fitness	Approximate fitness	0.9666	0.9691	0.9726	0.9725
					Upper Bound	1.0000	1.0000	0.9997	1.0000
				Er	Approximation Error		0.0305	0.0270	0.0270
			10%	Wi	and idth	0.0668	0.0619	0.0543	0.0550
				Time	cessing (ms)	/	/	86490212	87983292
				Time	ximate (ms)	4049416	4399280	400366	509232
					proximate (ms)	4049416	4399280	86890578	88492524
				PI	44.6556	41.1043	2.0811	2.0434	
					Lower Bound	0.9380	0.9399	0.9497	0.9493
			Approximate fitness	Approximate fitness	0.9690	0.9700	0.9749	0.9747	
				neicos	Upper Bound	1.0000	1.0000	1.0000	1.0000
					rimation ror	0.0305	0.0296	0.0247	0.0249
			20%	Ba	and idth	0.0620	0.0601	0.0503	0.0507
				Prepro	cessing e(ms)	/	/	91423432	95431122
				Appro Time	ximate e(ms)	15255832	18597920	424210	561543
					proximate e(ms)	15255832	18597920	91847642	95992665
					PI	11.8531	9.7231	1.9688	1.8838
			30%	Ait-	Lower Bound	0.9431	0.9420	0.9510	0.9512
				Approximate fitness	Approximate fitness	0.9715	0.9710	0.9755	0.9756
					Upper Bound	1.0000	1.0000	1.0000	1.0000
	0.9995			Er	imation ror	0.0280	0.0285	0.0240	0.0239
				Wi	Band Width		0.0580	0.0490	0.0488
BPIC2017		180829300		Preprocessing Time(ms)		/	/	95294232	99874342
				Approximate Time(ms)		13089388	16606568	502321	424931
				Total Approximate Time(ms)		13089388	16606568	95796553	100299273
				Approximate	Lower	13.8150 0.9481	10.8890 0.9480	1.8876 0.9575	1.8029 0.9564
					Bound Approximate	0.9741	0.9740	0.9788	0.9782
				fitness	fitness Upper	1.0000	1.0000	1.0000	1.0000
					Bound imation	0.0255	0.0255	0.0208	0.0213
			40%	Ba	ror and	0.0519	0.0520	0.0425	0.0436
			+0%	Prepro	dth cessing e(ms)	/	/	99034313	100293122
				Appro	ximate	16294010	18807577	582312	510124
				Total Ap	proximate	16294010	18807577	99616625	100803246
					e(ms) PI	11.0979	9.6147	1.8153	1.7939
					Lower Bound	0.9528	0.9527	0.9682	0.9691
				Approximate fitness	Approximate fitness	0.9764	0.9764	0.9841	0.9846
					Upper Bound	1.0000	1.0000	1.0000	1.0000
				Er	imation ror	0.0231	0.0232	0.0154	0.0150
			50%	Ba Wi	and idth	0.0472	0.0473	0.0318	0.0309
			30%	Time	cessing e(ms)	/	/	108224313	119901232
				Appro Time	ximate e(ms)	20183838	22539508	391222	454002
					proximate e(ms)	20183838	22539508	108615535	120355234
					PI	8.9591	8.0228	1.6649	1.5025

TABLE VI. EXPERIMENTAL RESULTS FOR DATASETS.

Table VI continued.

	T			1			Approxima	Table tion Method	VI continued.
Log	Actual	Normal Alignment	Candidate	Para	meter	Bas	eline	In-cluste	r medoid
Log	Fitness	Time	Percentage	1 ara		Frequency	K-Medoids	In-cluster frequency	In-cluster medoid
					Lower Bound	0.9987	0.9975	0.9989	0.9980
				Approximate fitness	Approximate fitness	0.9994	0.9988	0.9993	0.9990
					Upper Bound	1.0000	1.0000	0.9997	1.0000
			10%		imation ror	0.0006	0.0011	0.0006	0.0009
					nd dth	0.0013	0.0025	0.0008	0.0020
					cessing e(ms)	/	/	10585	11021
				Time	ximate e(ms)	8986	15555	2901	3531
					proximate e(ms)	8986	15555	13486	14552
				I	PI .	14.5148	8.3851	9.6715	8.9630
				Lower Bound	0.9994	0.9991	0.9994	0.9990	
			Approximate fitness	Approximate fitness	0.9997	0.9996	0.9997	0.9995	
					Upper Bound	1.0000	1.0000	1.0000	1.0000
				Er	imation ror	0.0002	0.0004	0.0002	0.0004
			20%	Wi	and idth	0.0006	0.0009	0.0006	0.0010
				Time	cessing e(ms)	/	/	14012	15432
				Time	Approximate Time(ms) Total Approximate		11123	3221	3834
		0.9999 130430		Time	e(ms)	8296	11123	17233	19266
				1	Lower	15.7220 0.9994	11.7262 0.9992	7.5686 0.9994	6.7700 0.9994
			30%	Approximate	Bound Approximate	0.9997	0.9996	0.9997	0.9997
				fitness	fitness Upper	1.0000	1.0000	1.0000	1.0000
					Bound imation	0.0002	0.0003	0.0002	0.0002
				Ba	ror and	0.0006	0.0008	0.0006	0.0006
				Width Preprocessing Time(ms)		/	/	15236	22293
RTFMP	0.9999			Approximate Time(ms)		9831	10222	3232	3923
				Total Approximate		9831	10222	18468	26216
				Time(ms) PI		13.2672	12.7597	7.0625	4.9752
					Lower Bound	0.9996	0.9993	0.9998	0.9996
				Approximate fitness	Approximate fitness	0.9998	0.9997	0.9999	0.9998
					Upper Bound	1.0000	1.0000	1.0000	1.0000
					rimation ror	0.0001	0.0003	0.0000	0.0001
			40%	Ba	and idth	0.0004	0.0007	0.0002	0.0004
				Prepro	cessing e(ms)	/	/	17222	24422
				Appro	ximate e(ms)	10323	13123	4442	4232
				Total Ap	proximate e(ms)	10323	13123	21664	28654
					Lower	12.6349	9.9390	6.0206	4.5519
				Approximate	Bound Approximate	0.9998	0.9996	0.9998	0.9997
				fitness	fitness Upper	0.9999	0.9998	0.9999	0.9999
				Approx	Bound	1.0000	1.0000	1.0000	1.0000
				Er	ror and	0.0000	0.0001	0.0000	0.0000
			50%	Wi	dth cessing	0.0002	0.0004	0.0002	0.0003
				Time	e(ms)	/	/	19203	30020
				Approxi Time(Total Appr		9050	10212	4301	5021
				Time	e(ms)	9050 14.4122	10212 12.7722	23504 5.5493	35041 3.7222
		l		1	1	14.4122	12.//22	ر 495.د	3.1222

TABLE VI. EXPERIMENTAL RESULTS FOR DATASETS.

			1	ı			Approxima	Table tion Method	VI continued.
1	Actual	Normal	Candidate	D	meter	Bas	eline	In-cluste	r medoid
Log	Fitness	Alignment Time	Percentage	Para		Frequency	K-Medoids	In-cluster frequency	In-cluster medoid
					Lower Bound	0.7959	0.7965	0.8204	0.8100
				Approximate fitness	Approximate fitness	0.8980	0.8983	0.9101	0.9050
					Upper Bound	1.0000	1.0000	0.9997	1.0000
			10%	Eı	imation ror	0.0901	0.0898	0.0780	0.0830
					and idth	0.2041	0.2035	0.1793	0.1900
					cessing e(ms)	/	/	107478	110312
					ximate e(ms)	32599	28302	1902	2032
					proximate e(ms)	32599	28302	109380	112344
				1	PI	93.1072	107.2433	27.7491	27.0170
					Lower Bound	0.8403	0.8404	0.8626	0.8638
				Approximate fitness	Approximate fitness	0.9202	0.9202	0.9313	0.9319
					Upper Bound	1.0000	1.0000	1.0000	1.0000
				Eı	imation ror	0.0679	0.0678	0.0567	0.0561
			20%	W	and idth	0.1597	0.1596	0.1374	0.1362
				Time	Preprocessing Time(ms)		/	130101	148903
				Time	Approximate Time(ms)		67461	2303	2289
				Time	proximate e(ms)	56803	56803 67461 132404 1		151192
				1	PI I	53.4338	44.9919	22.9238	20.0751
		3035200	30%		Lower Bound	0.8701	0.8405	0.8730	0.8748
				Approximate fitness	Approximate fitness	0.9351	0.9203	0.9365	0.9374
	0.9880				Upper Bound	1.0000	1.0000	1.0000	1.0000
				Eı	imation ror	0.0530	0.0678	0.0515	0.0506
				W	Band Width		0.1595	0.1270	0.1252
Sepsis				Preprocessing Time(ms) Approximate		/	/	159232	162820
				Time(ms)		79763	60393	5201	5433
				Total Approximate Time(ms) PI		79763	60393	164433	168253
				J	Lower	38.0527	50.2575	18.4586	18.0395
				Approximate	Bound Approximate	0.8931	0.8959	0.9066	0.9015
				fitness	fitness	0.9466	0.9480	0.9533	0.9508
				Approx	Bound imation	1.0000	1.0000	1.0000	1.0000
				Ei	ror and	0.0415	0.0400	0.0347	0.0373
			40%	W	idth cessing	0.1069	0.1041	0.0934	0.0985
				Tim	e(ms) eximate	/	/	182782	209212
				Time	e(ms) proximate	102649	116824	6123	5736
				Time	e(ms)	102649	116824	188905	214948
				1	Lower	29.5687 0.9112	25.9810 0.9113	16.0673 0.9255	14.1206 0.9192
				Approximate fitness	Approximate	0.9556	0.9557	0.9628	0.9596
				nuiess	fitness Upper	1.0000	1.0000	1.0000	1.0000
					Bound	0.0324	0.0324	0.0253	0.0284
			50%	Ba	ror and	0.0888	0.0887	0.0745	0.0808
			50%	Prepro	Width Preprocessing Time(ms)		/	209823	222011
				Appro	ximate	126803	137461	3508	3769
				Total Ap	Time(ms) Total Approximate Time(ms)		137461	213331	225780
					e(ms) PI	23.9363	22.0804	14.2277	13.4432