

An Automatic Segmentation Algorithm for Solar Filaments in H-Alpha Images using a Context-based Sliding Window

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Abstract—There are many features which appear on the surface of the sun. One of these features that appear clearly are the dark threads in the Hydrogen alpha ($H\alpha$) spectrum solar images. These ‘filaments’ are found to have a definite correlation with Coronal Mass Ejections (CMEs). A CME is a large release of plasma into space. It can be hazardous to astronauts and the spacecraft if it is being ejected towards the Earth. Knowing the exact attributes of solar filaments may open the way towards predicting the occurrence of CMEs. In this paper, an efficient and fully automated algorithm for solar filament segmentation without compromising accuracy is proposed. The algorithm uses some statistical measures to design the thresholding equations and it is written in the C++ programming language. The square root of the range as a measure of variability of image intensity values is used to determine the size of the sliding window at run time. There are many previous studies in this area, but no single segmentation method that could precisely claim to be fully automatic exists. Samples were taken from several representative regions in low-contrast and high-contrast solar images to verify the viability and efficacy of the method.

Keywords—Solar image processing; solar filament; segmentation; sliding window; Coronal mass ejections

I. INTRODUCTION

Solar filaments are huge regions of very thick relatively cool plasma compared to the surface of the sun. These solar features appear as elongated and dark filaments in $H\alpha$ solar images. CMEs are enormous bubbles of hot plasma (billions of tonnes of magnetized plasma) that is propagating away from the solar corona to the interplanetary medium at a very high velocity [1]. The importance of studying solar filaments comes from considering its disappearances as a significant indicator for the possible occurrence of CMEs, which is considered as the major cause of geomagnetic storms. It is now almost certain that there is a close association between CME and filament disappearances ([1]-[12]). Most of the filament detection techniques depend on sliding windows over the image region of interest. This sliding window is the number of pixels that are shifted while scanning the image. The scanning speed of images greatly depends on the size of the sliding window and the computational power of the image processing system. A context-based sliding window is proposed in this study to fully automate the process of solar filament segmentation in $H\alpha$ Images. The use of often user selectable, non-adaptable and non-automatic different sizes of

structuring elements in filament detection techniques led to them being defined as non-automated. According to this hypothesis, no single filament segmentation method thus could accurately claim to be fully automatic. Additionally, most of the previous studies ([1], [5], [7], [8], [13]-[20]) follow an image scanning process using a fixed size sliding window according to a fixed step size. Also the sliding window size affects the results of the different filtering techniques like the median filter [21]. The paper is organized as follows. The concept of the context-sensitive sliding window is presented in the next section. Section III overviews the algorithm of the context-based sliding window. Section Four is the conclusion.

Fig. 1 shows the unevenly illuminated solar images. These images were enhanced using an image enhancement technique introduced by [16].

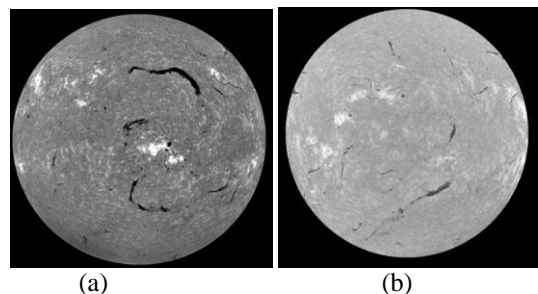


Fig. 1. (a) Solar image observed by Big Bear Solar Observatory (BBSO) on 2nd January 2001; (b) Solar image observed by Meudon Observatory on 1st April 2002.

II. CONTEXT-BASED SLIDING WINDOW

The common purpose of a sliding window is to give the possibility of checking the presence of the object in a rectangular box at different positions in the image. Subsequently, it is possible to use any of the many proposed methods to check the presence of an object in the sliding window or not. All previous methods of segmenting solar filaments rely entirely on customizing the statistical measures using a fixed sized sliding window. In general, the values of the statistical parameters in a local window are affected by the size of it. This research strongly proffers to adapt the size of the sliding window according to the window contents by using the Range (R) as a measure of variability, that is, the

difference between the lowest and highest image intensity values contained in the sliding window. To ascertain the effectiveness of using R and to optimize the image segmentation method, two samples; the first window (W_1) and the second window (W_2) were taken from two solar images as shown in the figures.

III. HOMOGENEITY AND HETEROGENEITY OF IMAGE REGIONS

To give an adequate opportunity for segmenting solar images and hence judge between the homogeneous and

heterogeneous regions, four values were calculated from different representative image samples, these being the value of R , the window side length; the window size (W_{SIZE}) as the integer square root of R ; the mean value (W_{μ}) and the standard deviation (W_{σ}). These values are shown in Fig. 2 and 3. Samples were taken to represent from non-filament regions (in order to represent them) as shown in Fig. 2(a) and Fig. 3(a). Other samples were taken from filament regions. Finally, the last samples were taken to represent the filament edges as shown in Fig. 2(c) and Fig. 3(c). Fig. 4 displays the same parameters for the low contrast image filaments.

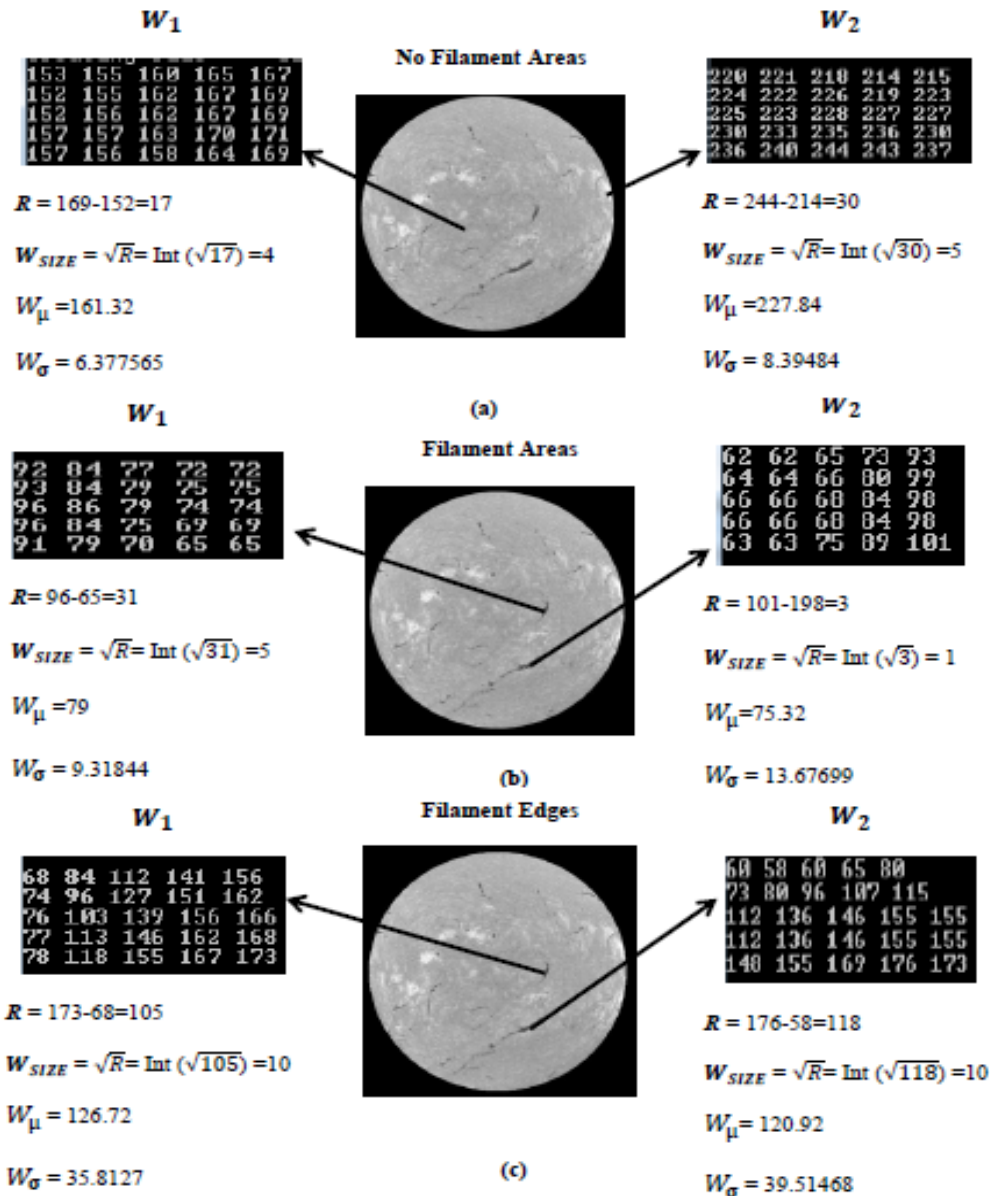


Fig. 2. Samples taken from solar image observed at Meudon Observatory on 1st April 2002: (a) Two samples from no filament pixels. (b) Two samples from filament pixels. (c) Two samples from Filament Edges.

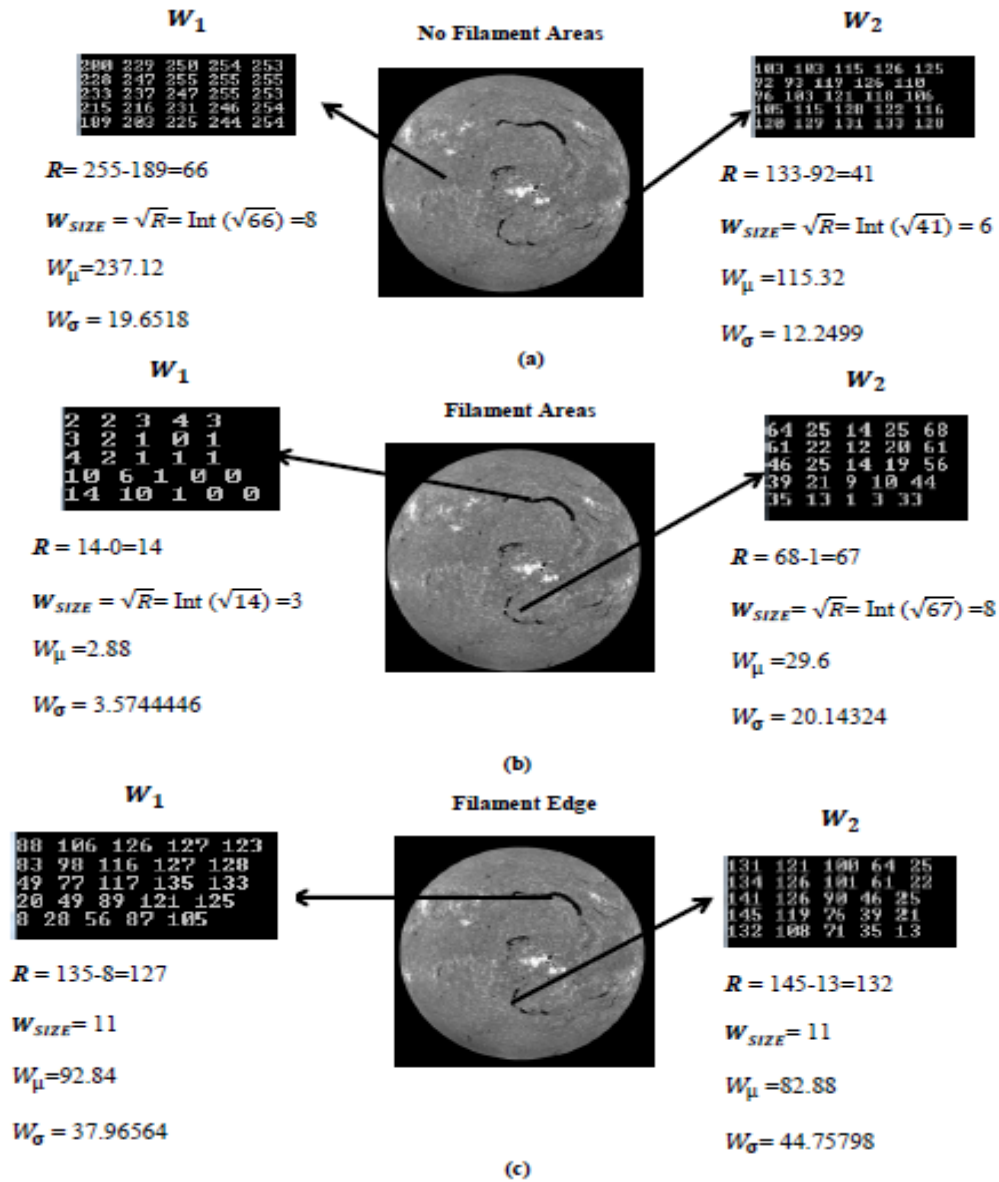


Fig. 3. Samples taken from solar image observed at Big Bear Solar Observatory 2nd January 2001: (a) Two samples from no-filament pixels. (b) Two samples from filament pixels. (c) Two samples from Filament Edges.

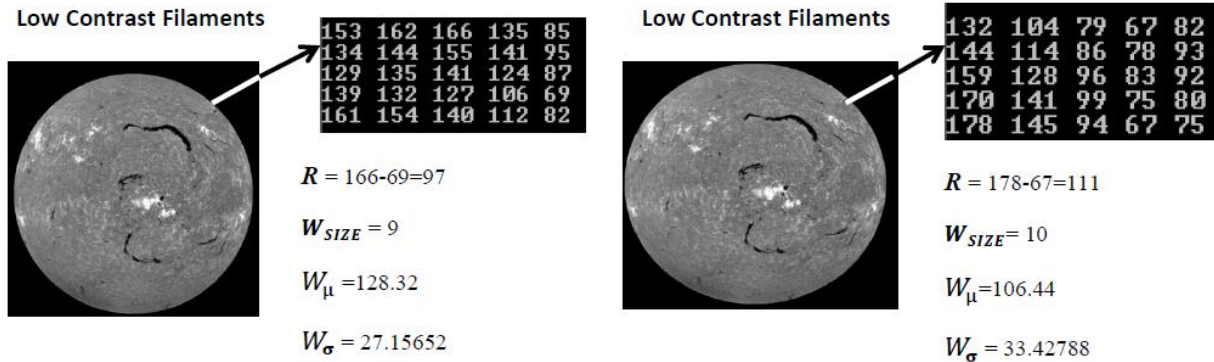


Fig. 4. Two samples from Low Contrast Filaments.

Where,

W_μ : the average for the window which is computed as $W_\mu = \frac{\sum_{i=1}^m W_i}{m}$, where W_i is the set of pixels inside the window and m being the number of pixels inside the window.

W_σ : the window standard deviation which is computed as $W_\sigma = \sqrt{\frac{1}{n} \sum_{i=1}^n (W_i - W_\mu)^2}$, where W_i are each pixel value in the window and n being the number of pixels inside the window.

R : the window image intensity range value which is computed as $R = W_{max} - W_{min}$, where W_{max} and W_{min} are the maximum and minimum pixel image intensity values inside the window.

It can be observed from the previous values that the range values become high only in the regions with heterogeneous and non-convergent intensity values, while it will be low in the regions with relatively uniform (low spread) and convergent intensity values.

IV. ADAPTIVE FILAMENT SEGMENTATION

The process of image segmentation is the first and most important phase in analyzing and interpreting these images. The success or failure of the segmentation process may be considered as the success or failure of the subsequent image classes. There are many features that appear on Ha images but our goal through this algorithm is to separate the image into white foreground filaments and the black background.

Fig. 5 shows the results after applying the segmentation code as shown in Fig. 7 on the solar image observed by Big Bear Solar Observatory (BBSO) on 2nd January 2001. Fig. 6 shows the results after applying the segmentation code on the solar image observed by Meudon Observatory (MO) on 1st April 2002.

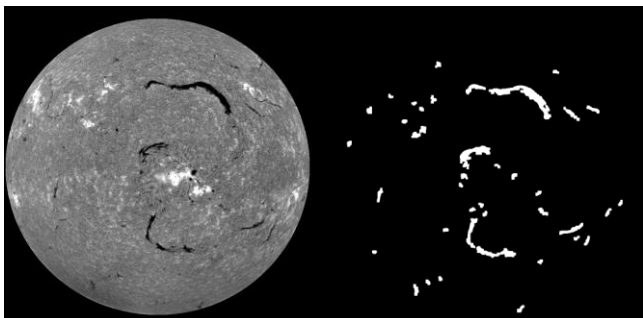


Fig. 5. The output after applying the algorithm on the BBSO image.

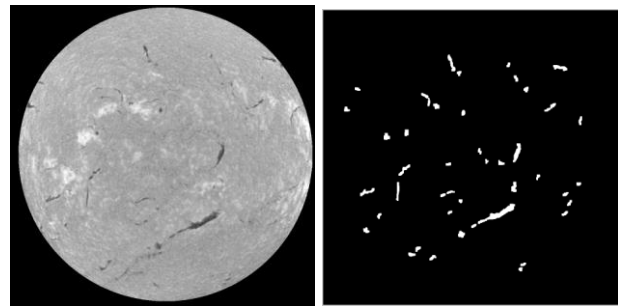


Fig. 6. The output after applying the algorithm on the MO image.

Setting the window size to any initial value

For $i=1$ to m *do* // m is the number of image rows

For $j=1$ to n *do* // n is the number of image columns

Calculate I_μ and I_σ

For $n=1$ to W *do* // W : window rows

For $m=1$ to W *do*

Calculate W_μ , W_R and W_σ

If $((I_\mu > (W_\mu + I_\sigma)) \text{ OR } (W_\mu < I_\sigma))$ *then*

Filaments

Else

No Filaments

End if

End for m

End for n

End for j

End for i

Fig. 7. The segmentation pseudo code.

V. EVALUATION AND RESULTS

The size of the sliding window will change automatically after calculating the range in the first iteration based on the sliding window intensity values. The highest value that may exist in any sliding window is 255 (white) and the lowest one is 0 (black), which means that the maximum possible can only be, $255 - 0 = 255$. A low window size indicates a homogeneous region (such as no-filament or filament region) and a high value indicates a non-homogenous region (such as the regions of filament edges). In *Ha* solar images; the filaments appear as dark features. This means if the sliding window is around the edges points of the filament pixels then the range value will be high otherwise, it will be low. The values calculated for each sample in all the regions are summarized in Table I.

TABLE I. STATISTICAL DETAILS OF THE SOLAR IMAGE AND THE SLIDING WINDOW

		R		W _{SIZE}		W _μ		W _σ		I _μ	I _σ
		W ₁	W ₂	W ₁	W ₂	W ₁	W ₂	W ₁	W ₂		
Solar Image with High Intensity values	No Filament	17	30	4	5	161.32	227.84	6.377565	8.39484	172	15.7931
	High contrast Filament	3	31	1	5	75.32	79	13.67699	9.31844		
	Filament edge	118	105	10	10	120.92	126.72	39.51468	35.8127		
Solar Image with Low Intensity values	No Filament	41	66	6	8	115.32	237.12	12.2499	19.6518	124	24.6386
	Low contrast Filament	67	14	8	3	29.6	2.88	20.14324	3.5744446		
	Filament edge	132	127	11	11	82.88	92.84	44.75798	37.96564		
	High contrast Filament	97	111	9	10	128.32	106.44	27.15652	33.42788		

Where,

I_{μ} : The mean value for the whole image which is computed as $I_{\mu} = \frac{\sum_{i=1}^n P_i}{n}$, where P_i is the set of pixels and n being the number of pixels inside the solar image.

I_{σ} : The standard deviation for the whole image which is computed as

$$I_{\sigma} = \sqrt{\frac{1}{n} \sum_{i=1}^n (x_i - I_{\mu})^2}$$

where n the number of pixels inside the whole image and x_i the pixel value.

Tables II and III contain the values of the different operators of (1) and (2) for all the regions. Tables I, II and III verify that (1) is correct for harmonic (relatively uniform) regions (with filaments or without filaments).

$$I_{\mu} > (W_{\mu} + I_{\sigma}) \tag{1}$$

However, it was observed that (1) does not work well with the areas that have low contrast filaments; so another condition is adapted to segment these filaments, as shown in (2) and as it is clearly seen in Table III.

$$W_{\mu} < (R + W_{\sigma}) \tag{2}$$

TABLE II. FIRST WINDOW: FIRST EQUATION VERIFICATION

I _μ	R	W _μ	W _σ	W _μ + W _σ	W ₁		R + W _σ	I _σ	W _μ + I _σ
					No Filament	Filament			
172	17	161.32	6.377565	167.697565	No Filament	Filament	23.377565	15.7931	177.1131
	3	75.32	13.67699	88.99699	Filament	Filament	16.67699		75.32
	118	120.92	39.51468	160.43468	Filament Edge	Filament Edge	157.51468		120.92
124	41	115.32	12.2499	127.5699	No Filament	No Filament	53.2499	24.6386	139.9586
	67	29.6	20.14324	49.74324	Low contrast filament	Low contrast filament	87.14324		29.6
	132	82.88	44.75798	127.63798	Filament Edge	Filament Edge	176.75798		82.88
	97	128.32	27.15652	155.47652	High Contrast Filament	High Contrast Filament	124.15652		152.9586

TABLE III. SECOND WINDOW: FIRST EQUATION VERIFICATION

I _μ	R	W _μ	W _σ	W _μ + W _σ	W ₂		R + W _σ	I _σ	W _μ + I _σ
					No Filament	Filament			
172	30	227.84	8.39484	236.23484	No Filament	No Filament	38.39484	15.7931	243.6331
	31	79	9.31844	88.31844	Filament	Filament	40.31844		79
	105	126.72	35.8127	162.5327	Filament Edge	Filament Edge	140.8127		126.72
124	66	237.12	19.6518	256.7718	No Filament	No Filament	85.6518	24.6386	261.7586
	14	2.88	3.5744446	6.4544446	Low Contrast Filament	Low Contrast Filament	17.5744446		2.88
	127	92.84	37.96564	130.80564	Filament Edge	Filament Edge	164.96564		92.84
	111	106.44	33.42788	139.86788	High Contrast Filament	High Contrast Filament	144.42788		

VI. CONCLUSION

An accurate, robust and novel algorithm for solar filament segmentation has been introduced in this paper. The algorithm adopted an adaptive, automated sliding window size according to the extent of the heterogeneity of the window pixels instead of using a fixed value. The algorithm uses extracted windows from two different solar images, one high contrast image and one low contrast image. Some statistical calculations were used to judge the presence of the solar filament or not. The range as a statistical measure played an important role in

automating the segmentation process. The mean value and standard deviation of the image intensity values in addition to the range, mean value and standard deviation of the adaptive sliding window pixels have been used to make up the filament segmentation equations. This technique can be better evaluated in the subsequent solar image classes which include merging broken structures; filaments characterizations and detecting filament disappearances; additionally it can be the basis for all these subsequent automatic operations.

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